

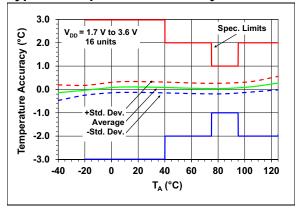
MCP9844/9844A

±1°C Accurate, 1.8V Digital Temperature Sensor

Features

- · Sensor Accuracy:
 - ±0.2°C/±1°C (typ./max.) → +75°C to +95°C
 - $\pm 0.5^{\circ}C/\pm 2^{\circ}C$ (typ./max.) $\rightarrow \pm 40^{\circ}C$ to $\pm 125^{\circ}C$
 - $\pm 1^{\circ}C/\pm 3^{\circ}C$ (typ./max.) $\rightarrow -40^{\circ}C$ to $\pm 125^{\circ}C$
- User-Programmable Temperature Limits:
 - Temperature Window Limit
- Critical Temperature Limit
- User-Programmable Temperature Alert Output
- 1MHz, 2-Wire I²C[™] Interface
- Operating Voltage Range: 1.7V to 3.6V
- Operating Current: 100 µA (typical)
- Shutdown Current: 0.1 µA (typical)
- Available Packages: 8-Pin TDFN

Typical Temperature Accuracy



Typical Applications

- Temperature Sensing for Solid State Drive (SSD)
- · General Purpose Temperature Datalog
- General Purpose
- Industrial Applications
- · Personal Computers and Servers
- · PC Peripherals
- Consumer Electronics
- · Handheld/Portable Devices

Description

Microchip Technology Inc.'s MCP9844/9844A digital temperature sensors convert temperature from -40°C to +125°C to a digital word. The devices provide an accuracy of $\pm 0.2^{\circ}C/\pm1^{\circ}C$ (typical/maximum) from +75°C to +95°C with an operating voltage of 1.7V to 3.6V.

The MCP9844/9844A digital temperature sensors come with user-programmable registers that provide flexibility for temperature sensing applications. The registers allow user-selectable settings, such as Shutdown or Low-Power modes, and the specification of temperature event boundaries. When the temperature changes beyond the specified event boundary limits, the MCP9844/9844A output displays an Alert signal at the Event pin. The user has the option of setting the temperature event output signal polarity as either an active-low or active-high comparator output for the thermostat operation, or as a temperature event interrupt output for microprocessor-based systems.

These sensors have an industry standard ${\sf I}^2{\sf C}$ Fast Mode Plus compatible 1 MHz serial interface.

Package Types



1.0 ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings †

V _{DD}
Voltage at all Input/Output pins GND – 0.3V to 4.0V
Pin A0GND – 0.3V to 11V
Storage temperature65°C to +150°C
Ambient temp. with power applied40°C to +125°C
Junction Temperature (T _J)+150°C
ESD protection on all pins (HBM:MM) (4 kV:200V)
Latch-Up Current at each pin (25°C) ±200 mA

†Notice: Stresses above those listed under "Maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

TEMPERATURE SENSOR DC CHARACTERISTICS

Electrical Specifications: Unles $T_A = -40^{\circ}C$ to $+125^{\circ}C$.	s otherwise	indicate	ed, V _{DD}	= 1.7V to	3.6V, C	GND = Ground, and
Parameters	Sym.	Min.	Тур.	Max.	Unit	Conditions
Temperature Sensor Accuracy		<u> </u>				
+75°C < $T_A \le$ +95°C	T _{ACY}	-1.0	±0.2	+1.0	°C	V _{DD} = 1.8V
$+40^{\circ}C < T_{A} \le +125^{\circ}C$		-2.0	±0.5	+2.0	°C	
$-40^{\circ}C < T_A \le +125^{\circ}C$		-3.0	±1	+3.0	°C	
Temperature Conversion Time						
MCP9844						
0.25°C/bit (POR default)		—	65	125	ms	15 S/sec (typical) (See Section 5.2.4)
MCP9844A						
0.0625°C/bit (POR default)		_	80	100	ms	12 S/sec (typical) (See Section 5.2.4)
Power Supply						
Specified Voltage Range	V _{DD}	1.7		3.6	V	
Operating Current	I _{DD}	_	100	500	μA	Applies to MCP9844
	I _{DD}	—	200	500	μA	Applies to MCP9844A
Shutdown Current	I _{SHDN}	-	0.2	1	μA	T _A = 85°C
Power On Reset (POR)	V _{POR}	_	1.4	1.6	V	Threshold for falling V _{DD} voltage
Settling time after POR	t _{POR}	—	_	1	ms	For warm and cold power cycles
Line Regulation	Δ°C	-	0.2	_	°C	V _{DD} = 1.7V to 3.6V
Event Output (Open-Drain outp	out, externa	l pull-u	p resist	or requir	ed), se	e Section 5.2.3
High-Level Current (leakage)	I _{OH}	—	—	1	μA	V _{OH} = V _{DD}
Low-Level Voltage	V _{OL}	—	—	0.4	V	I _{OL} = 3 mA (Active-Low, Pull-up Resistor)
Thermal Response, from +25°C	(Air) to +1	25°C (o	oil bath)			
TDFN-8	t _{RES}	—	0.7		S	Time to 63% (89°C)

INPUT/OUTPUT PIN DC CHARACTERISTICS

Electrical Specifications: Unles $T_A = -40^{\circ}C$ to $+125^{\circ}C$.	s otherwise	indicate	ed, V _{DD} = ′	1.7V to 3.6	8V, GN	ID = Ground, and
Parameters	Sym.	Min.	Тур.	Max.	Unit	Conditions
Serial Input/Output (SCL, SDA, A	40, A1, A2)					
Input Characteristics						
High-Level Voltage	V _{IH}	0.7V DD	_	_	V	
Low-Level Voltage	V _{IL}		—	0.3V _{DD}	V	
Input Current	I _{IN}	_	—	±5	μA	SDA and SCL only
Input Impedance (A0, A1, A2)	Z _{IN}	—	1		MΩ	V _{IN} > V _{IH}
Input Impedance (A0, A1, A2)	Z _{IN}		200	_	kΩ	V _{IN} < V _{IL}
Output (SDA only)						
Low-Level Voltage	V _{OL}	_	—	0.4	V	I _{OL} = 3 mA
High-Level Current (leakage)	I _{OH}	—	_	1	μA	$V_{OH} = V_{DD}$
MCP9844 Low-level Current	I _{OL}	20			mA	V_{OL} = 0.4V, V_{DD} ≥ 2.2V
		6	_		mA	V _{OL} = 0.6V
MCP9844A Low-level Current	I _{OL}	8		_	mA	$V_{OL} = 0.4 V, V_{DD} \ge 2.2 V$
		4	_	_	mA	V _{OL} = 0.4V
Capacitance	C _{IN}	—	5	—	pF	
SDA and SCL Inputs						
Hysteresis	V _{HYST}	_	0.05V _{DD}		V	
Spike Suppression	T _{SP}	_	—	50	ns	

TEMPERATURE CHARACTERISTICS

Electrical Specifications: Unless otherwise indicated, V_{DD} = 1.7V to 3.6V, GND = Ground, and T_A = -40°C to +125°C.									
Parameters	Sym.	Min.	Тур.	Max.	Units	Conditions			
Temperature Ranges									
Specified Temperature Range	T _A	-40		+125	°C	Note 1			
Operating Temperature Range	T _A	-40	_	+125	°C				
Storage Temperature Range	T _A	-65	_	+150	°C				
Thermal Package Resistances									
Thermal Resistance, 8L-TDFN	θ_{JA}	—	52.5	_	°C/W				

Note 1: Operation in this range must not cause T_J to exceed Maximum Junction Temperature (+150°C).

SERIAL INTERFACE TIMING SPECIFICATIONS

Electrical Specifications: Unless oth	erwise indica	ated, GND	= Ground,	T _A = -40°0	C to +125	°C, and C _L	= 80 pF	Note 1.
		V _{DD} = 1.7	V to 3.6V	V _{DD} = 2.2V to 3.6V				
		100	kHz	400	kHz	1000	kHz	
Parameters	Sym.	Min.	Max.	Min.	Max.	Min.	Max.	Units
2-Wire I ² C™ Interface		•	•			-	•	
Serial Port Frequency (Note 2, 4)	f _{SCL}	10	100	10	400	10	1000	kHz
Low Clock (Note 2)	t _{LOW}	4700	_	1300	_	500	_	ns
High Clock	t _{HIGH}	4000		600	_	260		ns
Rise Time (Note 5)	t _R	_	1000	20	300	—	120	ns
Fall Time (Note 5)	t _F	20	300	20	300	_	120	ns
Data in Setup Time (Note 3)	t _{SU:DAT}	250	—	100	_	50	_	ns
Data in Hold Time (Note 6)	t _{HD:DI}	0		0	—	0	—	ns
Start Condition Setup Time	t _{SU:STA}	4700	—	600	_	260	—	ns
Start Condition Hold Time	t _{HD:STA}	4000	—	600	_	260	_	ns
Stop Condition Setup Time	t _{SU:STO}	4000	_	600	_	260	_	ns
Bus Idle/Free	t _{B-FREE}	4700	—	1300	_	500	—	ns
Time Out	t _{OUT}	25	35	25	35	25	35	ms
Bus Capacitive Load	Cb	_			400	_	100	pf
Data Out Hold Time (Note 4)	Data Out Hold Time (Note 4)							
MCP9844 Data Out Hold time	t _{HD:DO}	200	900	200	900	0	350	ns
MCP9844A Data Out Hold time	t _{HD:DO}	200	900	200	900	0	450	ns

Note 1: All values referred to $V_{IL MAX}$ and $V_{IH MIN}$ levels.

2: If t_{LOW} > t_{OUT}, the temperature sensor I²C interface will time out. A Repeat Start command is required for communication.

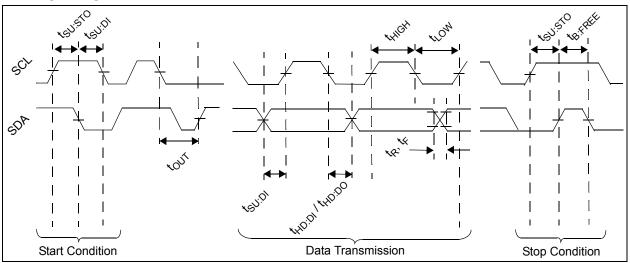
3: This device can be used in a Standard mode I²C bus system, but the requirement $t_{SU:DAT} \ge 250$ ns must be met. This device does not stretch SCL Low period. It outputs the next data bit to the SDA line within $t_{R MAX} + t_{SU:DAT MIN} = 1000$ ns + 250 ns = 1250 ns (according to the Standard mode I²C bus specification) before the SCL line is released.

4: As a transmitter, the device provides internal minimum delay time t_{HD:DAT MIN} to bridge the undefined region (min. 200 ns) of the falling edge of SCL t_{F MAX} to avoid unintended generation of Start or Stop conditions.

5: Characterized but not production tested.

6: As a receiver, SDA should not be sampled at the falling edge of SCL. SDA can transition t_{HD:DI} 0 ns after SCL toggles Low.

TIMING DIAGRAM



2.0 TYPICAL PERFORMANCE CURVES

Note: The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

Note: Unless otherwise indicated, V_{DD} = 1.7V to 3.6V, GND = Ground, SDA/SCL pulled-up to V_{DD} , and T_A = -40°C to +125°C.

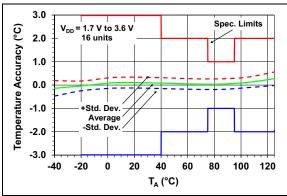


FIGURE 2-1:

Temperature Accuracy.

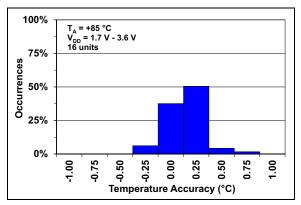


FIGURE 2-2: Temperature Accuracy Histogram, $T_A = +85$ °C.

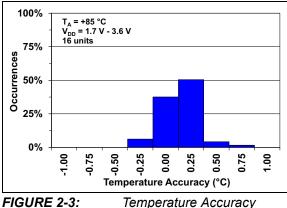


FIGURE 2-3: Temperature Accurac Histogram, T_A = + 25 °C.

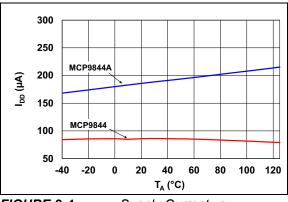


FIGURE 2-4: Supply Current vs. Temperature.

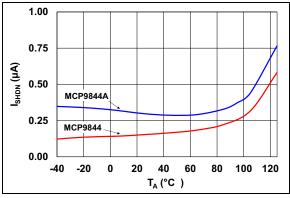


FIGURE 2-5: Shutdown Current vs. Temperature.

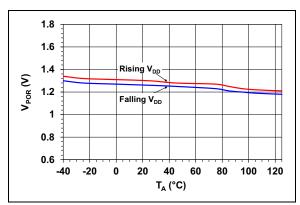


FIGURE 2-6: Power-On Reset Threshold Voltage vs. Temperature.

Note: Unless otherwise indicated, V_{DD} = 1.7V to 3.6V, GND = Ground, SDA/SCL pulled-up to V_{DD} , and T_A = -40°C to +125°C.

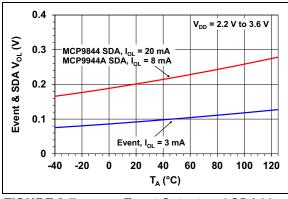


FIGURE 2-7: Event Output and SDA V_{OL} vs. Temperature.

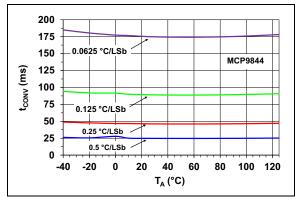


FIGURE 2-8: MCP9844 Temperature Conversion Rate vs. Temperature.

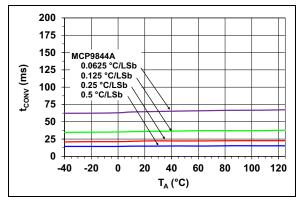


FIGURE 2-9: MCP9844A Temperature Conversion Rate vs. Temperature.

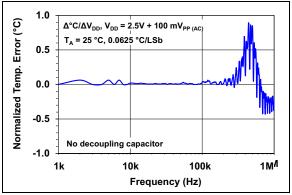


FIGURE 2-10: Power Supply Noise Rejection Normalized Temperature vs. Power Supply Frequency.

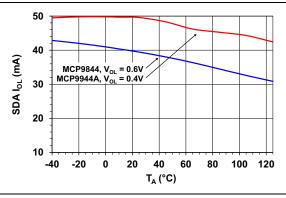


FIGURE 2-11: SDA I_{OL} vs. Temperature.

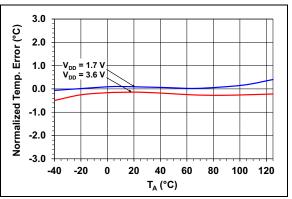


FIGURE 2-12: Line Regulation: Change in Temperature Accuracy vs. Change in V_{DD}.

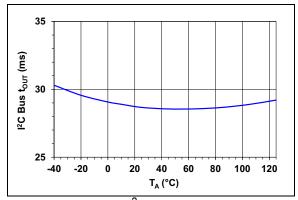


FIGURE 2-13: I^2C^{TM} Protocol Time-out vs. Temperature.

MCP9844/9844A

NOTES:

3.0 PIN DESCRIPTION

The descriptions of the pins are listed in Table 3-1.

MCP9844/9844A							
TDFN	Symbol	Description					
1	A0	Slave Address					
2	A1	Slave Address					
3	A2	Slave Address					
4	GND	Ground					
5	SDA	Serial Data Line					
6	SCL	Serial Clock Line					
7	Event	Temperature Alert Output					
8	V _{DD}	Power Pin					
9	EP	Exposed Thermal Pad (EP); can be connected to GND.					

TABLE 3-1: PIN FUNCTION TABLES

3.1 Address Pins (A0, A1, A2)

These pins are device address input pins.

The address pins correspond to the Least Significant bits (LSb) of the address bits. The Most Significant bits (MSb) are A6, A5, A4 and A3. Refer to Table 3-2.

TABLE 3-2: MCP9844/9844A ADDRESS BYTE

Device	Ad	ddres	s Co	Slave Address			
	A6	A5	A4	A3	A2	A1	A0
Sensor	0	0	1	1	х 1	х 1	х 1

Note 1: User-selectable address is shown by X, where X is '1' or '0' for V_{DD} and GND, respectively.

All address pins have an internal pull-down resistor.

3.2 Ground Pin (GND)

The GND pin is the system ground pin.

3.3 Serial Data Line (SDA)

The SDA is a bidirectional input/output pin used to serially transmit data to/from the host controller. This pin requires a pull-up resistor. (See Section 4.0 "Serial Communication".)

3.4 Serial Clock Line (SCL)

The SCL is a clock input pin. All communication and timing is relative to the signal on this pin. The clock is generated by the host or master controller on the bus. (See Section 4.0 "Serial Communication".)

3.5 Temperature Alert, Open-Drain Output (Event)

The MCP9844/9844A temperature Event output pin is an open-drain output. The device outputs a signal when the ambient temperature goes beyond the user programmed temperature limit. (See Section 5.2.3 "Event Output Configuration".)

3.6 Power Pin (V_{DD})

 V_{DD} is the power pin. The operating voltage range, as specified in the DC electrical specification table, is applied on this pin.

3.7 Exposed Thermal Pad (EP)

There is an internal electrical connection between the Exposed Thermal Pad (EP) and the GND pin; they can be connected to the same potential on the Printed Circuit Board (PCB). This provides better thermal conduction from the PCB to the die.

4.0 SERIAL COMMUNICATION

4.1 2-Wire Standard Mode I²C[™] Protocol-Compatible Interface

The MCP9844/9844A serial clock input (SCL) and the bidirectional serial data line (SDA) form a 2-wire bidirectional Standard mode I²C compatible communication port (refer to the **Temperature Sensor DC Characteristics** table and the **Serial Interface Timing Specifications** table).

The following MCP9844/9844A bus protocol is defined in Table 4-1.

TABLE 4-1:MCP9844/9844A SERIAL BUS
PROTOCOL DESCRIPTIONS

Term	Description
Master	The device that controls the serial bus, typically a microcontroller.
Slave	The device addressed by the master, such as the MCP9844/9844A.
Transmitter	Device sending data to the bus.
Receiver	Device receiving data from the bus.
START	A unique signal from the master to initiate serial interface with a slave.
STOP	A unique signal from the master to terminate serial interface from a slave.
Read/Write	A read or write to the MCP9844/9844A registers.
ACK	A receiver Acknowledges (ACK) the reception of each byte by polling the bus.
NAK	A receiver Not-Acknowledges (NAK) or releases the bus to show End-of-Data (EOD).
Busy	Communication is not possible because the bus is in use.
Not Busy	The bus is in the Idle state; both SDA and SCL remain high.
Data Valid	SDA must remain stable before SCL becomes high in order for a data bit to be considered valid. During normal data transfers, SDA only changes state while SCL is low.

4.1.1 DATA TRANSFER

Data transfers are initiated by a Start condition (START), followed by a 7-bit device address and a read/write bit. An Acknowledge (ACK) from the slave confirms the reception of each byte. Each access must be terminated by a Stop condition (STOP).

Repeated communication is initiated after t_{B-FREE}.

This device does not support sequential register read/ write. Each register needs to be addressed using the Register Pointer.

This device supports the Receive Protocol. The register can be specified using the pointer for the initial read. Each repeated read or receive begins with a Start condition and address byte. The MCP9844/9844A retains the previously selected register. Therefore, they output data from the previously specified register (repeated pointer specification is not necessary).

4.1.2 MASTER/SLAVE

The bus is controlled by a master device (typically a microcontroller) that controls the bus access and generates the Start and Stop conditions. The MCP9844/9844A is a slave device and does not control other devices in the bus. Both master and slave devices can operate as either transmitter or receiver. However, the master device determines which mode is activated.

4.1.3 START/STOP CONDITION

A high-to-low transition of the SDA line (while SCL is high) is the Start condition. All data transfers must be preceded by a Start condition from the master. A lowto-high transition of the SDA line (while SCL is high) signifies a Stop condition.

If a Start or Stop condition is introduced during data transmission, the MCP9844/9844A releases the bus. All data transfers are ended by a Stop condition from the master.

4.1.4 ADDRESS BYTE

Following the Start condition, the host must transmit an 8-bit address byte to the MCP9844/9844A. The address for the MCP9844/9844A temperature sensor is '0011, A2, A1, A0' in binary, where the A2, A1 and A0 bits are set externally by connecting the corresponding pins to V_{DD} '1' or GND '0'. The 7-bit address transmitted in the serial bit stream must match the selected address for the MCP9844/9844A to respond with an ACK. Bit 8 in the address byte is a read/write bit. Setting this bit to '1' commands a read operation, while '0' commands a write operation (see Figure 4-1).

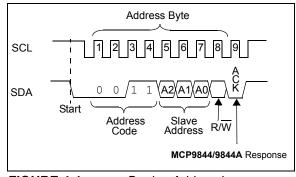


FIGURE 4-1: Device Addressing.

4.1.5 DATA VALID

After the Start condition, each bit of data in the transmission needs to be settled for a time specified by $t_{SU-DATA}$ before SCL toggles from low-to-high (see **Serial Interface Timing Specifications** table).

4.1.6 ACKNOWLEDGE (ACK/NAK)

Each receiving device, when addressed, is obliged to generate an ACK bit after the reception of each byte. The master device must generate an extra clock pulse for ACK to be recognized.

The acknowledging device pulls down the SDA line for $t_{SU\text{-}DATA}$ before the low-to-high transition of SCL from the master. SDA also needs to remain pulled down for $t_{H\text{-}DATA}$ after a high-to-low transition of SCL.

During read, the master must signal an End-of-Data (EOD) to the slave by not generating an ACK bit (NAK) once the last bit has been clocked out of the slave. In this case, the slave will leave the data line released to enable the master to generate the Stop condition.

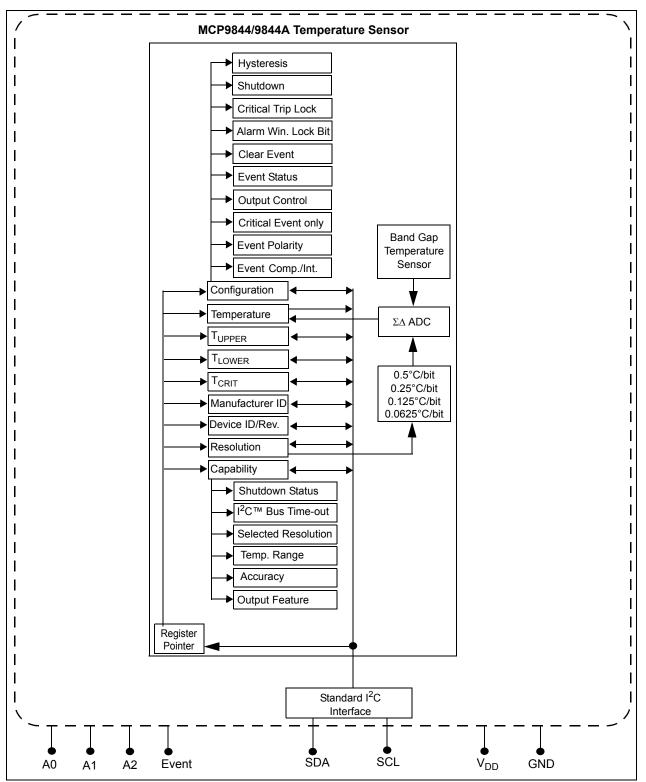
4.1.7 TIME OUT (T_{OUT})

If the SCL stays low or high for time specified by t_{OUT} , the MCP9844/9844A resets the serial interface. This dictates the minimum clock speed as specified in the specification.

5.0 FUNCTIONAL DESCRIPTION

The MCP9844/9844A temperature sensors consist of a band gap type temperature sensor, a Delta-Sigma Analog-to-Digital Converter ($\Sigma \Delta$ ADC), user-program-

mable registers and a 2-wire I²C protocol compatible serial interface. Figure 5-1 shows a block diagram of the register structure.





5.1 Registers

The MCP9844/9844A device has several registers that are user accessible. These registers include the Capability register, Configuration register, Event Temperature Upper-Boundary and Lower-Boundary Trip registers, Critical Temperature Trip register, Temperature register, Manufacturer Identification register and Device Identification register.

The Temperature register is read-only and is used to access the ambient temperature data. The data is loaded in parallel to this register after t_{CONV} . The Event Temperature Upper-Boundary and Lower-Boundary Trip registers are read/writes. If the ambient temperature drifts beyond the user-specified limits, the MCP9844/9844A device outputs a signal using the Event pin (refer to Section 5.2.3 "Event Output Configuration"). In addition, the Critical Temperature Trip register is used to provide an additional critical temperature limit.

The Capability register is used to provide bits describing the MCP9844/9844A's capability in measurement resolution, measurement range and device accuracy. The device Configuration register provides access to configure the MCP9844/9844A's various features. These registers are described in further detail in the following sections.

The registers are accessed by sending a Register Pointer to the MCP9844/9844A using the serial interface. This is an 8-bit write-only pointer. Register 5-1 describes the pointer or the address of each register. This device will not acknowledge commands to register pointers other than those listed in Register 5-1.

REGISTER 5-1: REGISTER POINTER (WRITE ONLY)

W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0		
—		—	_	Pointer Bits					
bit 7				•			bit 0		
Legend:									

R = Readable bit	W = Writable bit	bit U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 7-4 Writable Bits: Write '0'

bit 3-0 Pointer Bits:

0000 =	Capability register
0001 =	Configuration register (CONFIG)
0010 =	Event Temperature Upper-Boundary Trip register (TUPPER)
0011 =	Event Temperature Lower-Boundary Trip register (TLOWER)
0100 =	Critical Temperature Trip register (T _{CRIT})
0101 =	Temperature register (T _A)
0110 =	Manufacturer ID register
0111 =	Device ID/Revision register
1000 =	MCP9844: Reserved
	MCP9844A: Resolution register
1001 =	MCP9844: Resolution register
	MCP9844: Unused
1XXX =	Unused (The device will not acknowledge commands to other pointer locations.)

TABLE 5-1:BIT ASSIGNMENT SUMMARY FOR ALL TEMPERATURE SENSOR REGISTERS
(SEE SECTION 5.3)

Register	MSB/	Bit Assignment										
Pointer (Hex)	LSB	7	6	5	4	3	2	1	0			
0x00	MSB	0	0	0	0	0	0	0	0			
	LSB	SHDN Status	t _{OUT} Range	1	Reso	lution	Range	Accuracy	Event			
0x01	MSB	0	0	0	0	0	Hys	teresis	SHDN			
	LSB	Crt. Loc.	Win. Loc.	Int. Clr.	Evt. Stat.	Evt. Cnt.	Evt. Sel.	Evt. Pol.	Evt. Mod.			
0x02	MSB	0	0	0	SIGN	2 ⁷ °C	2 ⁶ °C	2 ⁵ °C	2 ⁴ °C			
	LSB	2 ³ °C	2 ² °C	2 ¹ °C	2 ⁰ °C	2 ⁻¹ °C	2 ⁻² °C	0	0			
0x03	MSB	0	0	0	SIGN	2 ⁷ °C	2 ⁶ °C	2 ⁵ °C	2 ⁴ °C			
	LSB	2 ³ °C	2 ² °C	2 ¹ °C	2 ⁰ °C	2 ⁻¹ °C	2 ⁻² °C	0	0			
0x04	MSB	0	0	0	SIGN	2 ⁷ °C	2 ⁶ °C	2 ⁵ °C	2 ⁴ °C			
	LSB	2 ³ °C	2 ² °C	2 ¹ °C	2 ⁰ °C	2 ⁻¹ °C	2 ⁻² °C	0	0			
0x05	MSB	$T_A \ge T_{CRIT}$	$T_A > T_{UPPER}$	T _A < T _{LOWER}	SIGN	2 ⁷ °C	2 ⁶ °C	2 ⁵ °C	2 ⁴ °C			
	LSB	2 ³ °C	2 ² °C	2 ¹ °C	2 ⁰ °C	2 ⁻¹ °C	2 ⁻² °C	2 ⁻³ °C	2 ⁻⁴ °C			
0x06	MSB	0	0	0	0	0	0	0	0			
	LSB	0	1	0	1	0	1	0	0			
0x07	MSB	0	0	0	0	0	1	1	0			
Note 2	LSB	0	0	0	0	0	0	0	1			
0x07	MSB	0	0	0	0	0	1	1	0			
Note 1	LSB	0	0	0	0	0	0	1	0			
0x08	MSB	0	0	0	0	0	1	1	0			
Note 2	LSB	0	0	0	0	0	0	0	1			
0x08	MSB	0	0	0	0	0	0	0	0			
Note 1	LSB	0	0	0	0	0	0	Reso	lution			
0x09	MSB	0	0	0	0	0	0	0	0			
Note 2	LSB	0 v for MCP98444	0	0	0	0	0	Reso	lution			

Note 1: Valid only for MCP9844A.

2: Valid only for MCP9844.

5.1.1 CAPABILITY REGISTER

This is a read-only register used to identify the temperature sensor capability. For example, the MCP9844/9844A device is capable of providing temperature at 0.25° C resolution, measuring temperature below and above 0° C, providing $\pm 1^{\circ}$ C and $\pm 2^{\circ}$ C accuracy over the active and monitor temperature ranges (respectively) and providing user-programmable temperature event boundary trip limits. Register 5-2 describes the Capability register. These functions are described in further detail in the following sections.

REGISTER 5-2: CAPABILITY REGISTER (READ-ONLY) \rightarrow ADDRESS '0000 0000'b

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R-1	R-1	R-1	R-0/1	R-1	R-1	R-1	R-1
SHDN Status	t _{OUT} Range	—	Resolution		Meas. Range	Accuracy	Temp. Alarm
bit 7 bit 0							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8	Unimplemented: Read as '0'
----------	----------------------------

bit 7 Event Output Status During Shutdown (SHDN Status):

- 0 = Event output remains in previous state. If the output asserts before shutdown command, it remains asserted during shutdown.
- 1 = Event output deasserts during shutdown. After shutdown, it takes t_{CONV} to reassert the event output (power-up default)

bit 6	l ² C™ Bus	Time-Out	(tour	Range):
-------	-----------------------	----------	-------	-------	----

- 0 = Bus time-out range is 10 ms to 60 ms
- 1 = Bus time-out range is 25 ms to 35 ms (power-up default)
- bit 5 **Unimplemented:** Read as '1'

bit 4-3 Resolution:

- $00 = 0.5^{\circ}C$
- 01 = 0.25°C (MCP9844 power-up default)
- 10 = 0.125°C
- 11 = 0.0625°C (MCP9844A power-up default)
 - These bits reflect the selected resolution (see Section 5.2.4 "Temperature Resolution")

bit 2 Temperature Measurement Range (Meas. Range):

- 0 = $T_A = 0$ (decimal) for temperature below 0°C
- 1 = The part can measure temperature below 0°C (power-up default)

REGISTER 5-2: CAPABILITY REGISTER (READ-ONLY) → ADDRESS '0000 0000'b (CONTINUED)

bit 1

Accuracy: $0 = Accuracy \rightarrow \pm 2^{\circ}C$ from +75°C to +95°C (Active Range) and $\pm 3^{\circ}C$ from +40

- = Accuracy $\rightarrow \pm 2^{\circ}$ C from +75°C to +95°C (Active Range) and $\pm 3^{\circ}$ C from +40°C to +125°C (Monitor Range)
- 1 = Accuracy $\rightarrow \pm 1^{\circ}$ C from +75°C to +95°C (Active Range) and $\pm 2^{\circ}$ C from +40°C to +125°C (Monitor Range)

bit 0 Temperature Alarm:

- 0 = No defined function (This bit will never be cleared or set to '0')
- 1 = The part has temperature boundary trip limits (T_{UPPER}/T_{LOWER}/T_{CRIT} registers) and a temperature event output (JC 42.4 required feature)

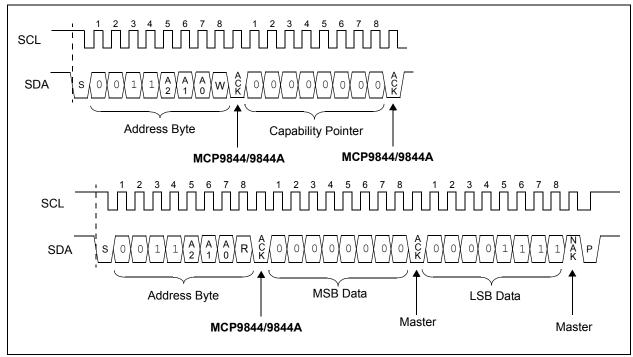


FIGURE 5-2: Timing Diagram for Reading the Capability Register (See Section 4.0 "Serial Communication").

5.1.2 SENSOR CONFIGURATION REGISTER (CONFIG)

The MCP9844/9844A device has a 16-bit Configuration register (CONFIG) that allows the user to set various functions for a robust temperature monitoring system. Bits 10 through 0 are used to select the event output boundary hysteresis, device Shutdown or Low-Power mode, temperature boundary and critical temperature lock, and temperature event output enable/disable. In addition, the user can select the event output condition (output set for T_{UPPER} and T_{LOWER} temperature boundary or T_{CRIT} only), read event output status and set event output mode).

The temperature hysteresis bits 10 and 9 can be used to prevent output chatter when the ambient temperature gradually changes beyond the user specified temperature boundary (see Section 5.2.2 "Temperature Hysteresis (T_{HYST})"). The Continuous Conversion or Shutdown mode is selected using bit 8. In Shutdown mode, the band gap temperature sensor circuit stops converting temperature and the Ambient Temperature register (T_A) holds the previous successfully converted temperature data (see **Section 5.2.1 "Shutdown Mode"**). Bits 7 and 6 are used to lock the user-specified boundaries T_{UPPER} , T_{LOWER} and T_{CRIT} to prevent an accidental rewrite. Bits 5 through 0 are used to configure the temperature Event output pin. All functions are described in Register 5-3 (see Section 5.2.3 "Event Output Configuration").

REGISTER 5-3: CONFIGURATION REGISTER (CONFIG) → ADDRESS `0000 0001' b

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—		T _{HY}	′ST	SHDN
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
Crit. Lock	Win. Lock	Int. Clear	Event Stat.	Event Cnt.	Event Sel.	Event Pol.	Event Mod.
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11 Unimplemented: Read as '0'

bit 10-9	T _{UPPER} and T _{LOWER} Limit Hysteresis (T _{HYST}):
	$0.0 = 0^{\circ}$ C (power up default)

 $00 = 0^{\circ}C$ (power-up default) $01 = 1.5^{\circ}C$ $10 = 3.0^{\circ}C$ $11 = 6.0^{\circ}C$

(Refer to Section 5.2.3 "Event Output Configuration")

This bit can not be altered when either of the lock bits are set (bit 6 and bit 7).

This bit can be programmed in Shutdown mode.

bit 8 Shutdown Mode (SHDN):

- 0 = Continuous Conversion (power-up default)
- 1 = Shutdown (Low-Power mode)

In shutdown, all power-consuming activities are disabled, though all registers can be written to or read. Event output will deassert.

This bit cannot be set '1' when either of the lock bits is set (bit 6 and bit 7). However, it can be cleared '0' for Continuous Conversion while locked (Refer to **Section 5.2.1 "Shutdown Mode"**).

REGISTER 5-3: CONFIGURATION REGISTER (CONFIG) \rightarrow ADDRESS `0000 0001'b

bit 7	T _{CRIT} Lock Bit (Crit. Lock):
	 0 = Unlocked. T_{CRIT} register can be written. (power-up default) 1 = Locked. T_{CRIT} register can not be written
	When enabled, this bit remains set '1' or locked until cleared by internal reset (Section 5.3 "Summary of Power-on Default"). This bit does not require a double-write.
	This bit can be programmed in Shutdown mode.
bit 6	T _{UPPER} and T _{LOWER} Window Lock Bit (Win. Lock):
	 0 = Unlocked. T_{UPPER} and T_{LOWER} registers can be written. (power-up default) 1 = Locked. T_{UPPER} and T_{LOWER} registers can not be written
	When enabled, this bit remains set '1' or locked until cleared by power-on Respell (Section 5.3 "Summary of Power-on Default"). This bit does not require a double-write.
	This bit can be programmed in Shutdown mode.
bit 5	Interrupt Clear (Int. Clear) Bit:
	 0 = No effect (power-up default) 1 = Clear interrupt output. When read this bit returns '0'
	This bit clears the Interrupt flag which deasserts event output. In Shutdown mode, the event output is always deasserted. Therefore, setting this bit in Shutdown mode clears the interrupt after the device returns to normal operation.
bit 4	Event Output Status (Event Stat.) Bit:
	 0 = Event output is not asserted by the device (power-up default) 1 = Event output is asserted as a comparator/Interrupt or critical temperature output
	In Shutdown mode this bit will clear because event output is always deasserted in Shutdown mode.
bit 3	Event Output Control (Event Cnt.) Bit:
	 0 = Event output Disabled (power-up default) 1 = Event output Enabled
	This bit can not be altered when either of the lock bits is set (bit 6 and bit 7).
	This bit can be programmed in Shutdown mode, but event output will remain deasserted.
bit 2	Event Output Select (Event Sel.) Bit:
	0 = Event output for T_{UPPER} , T_{LOWER} and T_{CRIT} (power-up default) 1 = $T_A \ge T_{CRIT}$ only. (T_{UPPER} and T_{LOWER} temperature boundaries are disabled.)
	When the Alarm Window Lock bit is set, this bit cannot be altered until unlocked (bit 6).
	This bit can be programmed in Shutdown mode, but event output will remain deasserted.
bit 1	Event Output Polarity (Event Pol.) Bit:
	0 = Active-low (power-up default. Pull-up resistor required) 1 = Active-high
	This bit cannot be altered when either of the lock bits is set (bit 6 and bit 7).
	This bit can be programmed in Shutdown mode, but event output will remain deasserted, see Section 5.2.3 "Event Output Configuration"
bit 0	Event Output Mode (Event Mod.) Bit:
	 0 = Comparator output (power-up default) 1 = Interrupt output
	This bit cannot be altered when either of the lock bits is set (bit 6 and bit 7).
	This bit can be programmed in Shutdown mode, but event output will remain deasserted.

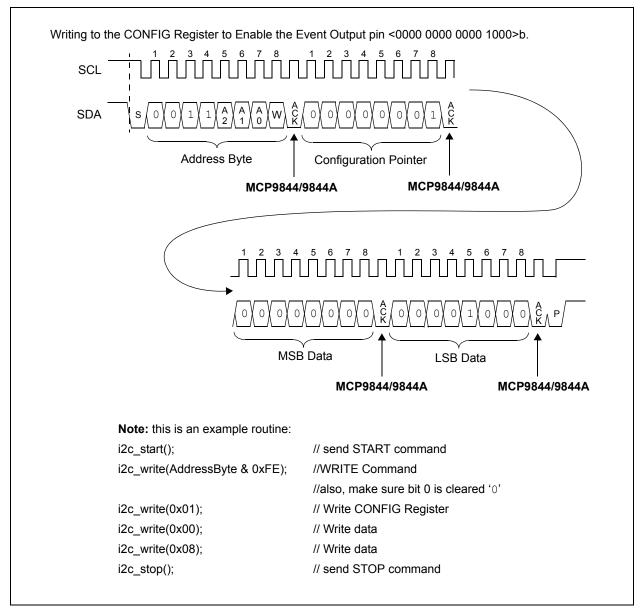


FIGURE 5-3: Timing Diagram for Writing to the Configuration Register (See Section 4.0 "Serial Communication".

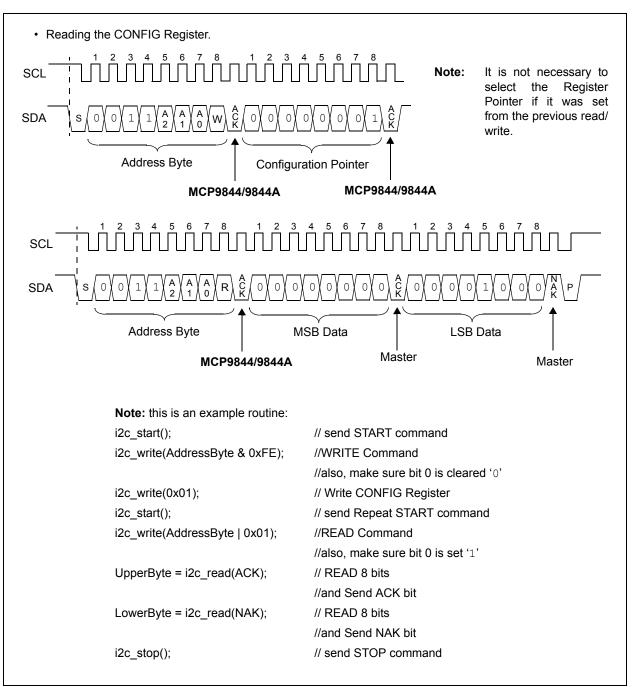


FIGURE 5-4: Timing Diagram for Reading from the Configuration Register (See Section 4.0 "Serial Communication").

5.1.3 UPPER/LOWER/CRITICAL TEMPERATURE LIMIT REGISTERS (T_{UPPER}/T_{LOWER}/T_{CRIT})

The MCP9844/9844A device has a 16-bit read/write Event Output Temperature Upper-Boundary Trip register (T_{UPPER}), a 16-bit Lower-Boundary Trip register (T_{LOWER}) and a 16-bit Critical Boundary Trip register (T_{CRIT}) that contains 11-bit data in two's complement format (0.25°C). This data represents the maximum and minimum temperature boundary or temperature window that can be used to monitor ambient temperature. If this feature is enabled (Section 5.1.2 "Sensor Configuration Register (CONFIG)") and the ambient temperature exceeds the specified boundary or window, the MCP9844/9844A asserts an event output. (Refer to Section 5.2.3 "Event Output Configuration").

REGISTER 5-4: UPPER/LOWER/CRITICAL TEMPERATURE LIMIT REGISTER (T_{UPPER}/T_{LOWER}/

 $T_{CRIT}) \rightarrow ADDRESS \text{ `0000 0010'b/`0000 0011'b/`0000 0100'b (Note 1)}$

─ ─ Sign 2 ⁷ °C 2 ⁶ °C 2 ⁵ °C 2 ⁴ °C bit 15 bit 8	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
bit 15 bit 8	—	—	—	Sign				
	bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0
2 ³ °C	2 ² °C	2 ¹ °C	2 ⁰ °C	2 ⁻¹ °C	2 ⁻² °C	—	—
bit 7						•	bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-13	Unimplemented: Read as '0'
bit 12	Sign:
	$0 = T_A \ge 0^\circ C$
	$1 = T_A < 0^{\circ}C$
bit 11-2	T _{UPPER} /T _{LOWER} /T _{CRIT} :
	Temperature boundary trip data in two's complement format.
bit 1-0	Unimplemented: Read as '0'
NI. 4. 4	

Note 1: This table shows two 16-bit registers for T_{UPPER}, T_{LOWER} and T_{CRIT} located at '0000 0010b', '0000 0011b' and '0000 0100b', respectively.

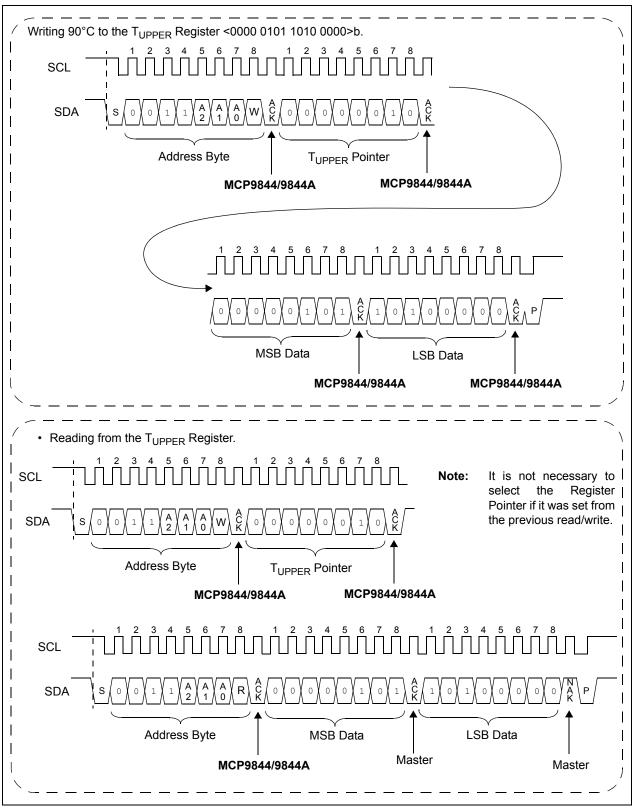


FIGURE 5-5: Timing Diagram for Writing and Reading from the T_{UPPER} Register (See Section 4.0 "Serial Communication").

5.1.4 AMBIENT TEMPERATURE REGISTER (T_A)

The MCP9844/9844A device uses a band gap temperature sensor circuit to output analog voltage proportional to absolute temperature. An internal $\Delta\Sigma$ ADC is used to convert the analog voltage to a digital word. The converter resolution is set to 0.25°C + sign (11-bit data). The digital word is loaded to a 16-bit read-only Ambient Temperature register (T_A) that contains 11-bit temperature data in two's complement format.

The T_A register bits (bits 12 through 0) are double-buffered. Therefore, the user can access the register while, in the background, the MCP9844/9844A performs an Analog-to-Digital conversion. The temperature data from the $\Delta\Sigma$ ADC is loaded in parallel to the T_A register at t_{CONV} refresh rate.

In addition, the T_A register uses three bits (bits 15, 14 and 13) to reflect the Event pin state. This allows the user to identify the cause of the event output trigger (see **Section 5.2.3 "Event Output Configuration**"); bit 15 is set to '1' if T_A is greater than or equal to T_{CRIT}, bit 14 is set to '1' if T_A is greater than T_{UPPER} and bit 13 is set to '1' if T_A is less than T_{LOWER}.

The T_A register bit assignment and boundary conditions are described in Register 5-5.

REGISTER 5-5: AMBIENT TEMPERATURE REGISTER $(T_A) \rightarrow ADDRESS \ 0000 \ 0101'b$ (Note 1)

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
T _A vs. T _{CRIT}	T _A vs. T _{UPPER}	T _A vs. T _{LOWER}	SIGN	2 ⁷ °C	2 ⁶ °C	2 ⁵ °C	2 ⁴ °C
bit 15							bit 8
R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
2 ³ °C	2 ² °C	2 ¹ °C	2 ⁰ °C	2 ⁻¹ °C	2 ⁻² °C	2 ⁻³ °C	2 ⁻⁴ °C
bit 7						·	bit 0
Legend:							

0			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	T _A vs. T _{CRIT} ⁽¹⁾ Bit:
	0 = T _A < T _{CRIT}
	1 = $T_A \ge T_{CRIT}$
bit 14	T _A vs. T _{UPPER} ⁽¹⁾ Bit:
	$0 = T_A \leq T_{UPPER}$
	$1 = T_A > T_{UPPER}$
bit 13	T _A vs. T _{LOWER} ⁽¹⁾ Bit:
	$0 = T_A \ge T_{LOWER}$
	$1 = T_A < T_{LOWER}$
bit 12	SIGN Bit:
	$0 = T_A \ge 0^\circ C$
	$1 = T_A < 0^{\circ}C$
bit 11-0	Ambient Temperature (T _A) Bits: (Note
	40 hit Auchieut Teurs enstaue date in turk

12-bit Ambient Temperature data in two's complement format.

Note 1: Bits 15, 14 and 13 are not affected by the status of the event output configuration (bits 5 to 0 of CONFIG) (Register 5-3).

2)

2: Bits 2, 1, and 0 may remain clear '0' depending on the status of the resolution register. The power-up default is 0.25°C/bit, bits 1 and 0 remain clear '0'.

5.1.4.1 T_A bits to Temperature Conversion

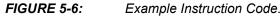
To convert the T_A bits to decimal temperature, the upper three boundary bits 15, 14 and 13) must be masked out. Then determine the sign bit (bit 12) to check positive or negative temperature, shift the bits accordingly, and combine the upper and lower bytes of the 16-bit register. The upper byte contains data for temperatures greater than 32°C while the lower byte contains data for temperature less than 32°C, including fractional data. When combining the upper and lower bytes, the upper byte must be right-shifted by 4 bits (or multiply by 2⁴), and the lower byte must be left-shifted by 4 bits (or multiply by 2⁻⁴). Adding the results of the shifted values provides the temperature data in decimal format; see Equation 5-1.

The temperature bits are in two's compliment format; therefore, positive temperature data and negative temperature data are computed differently. Equation 5-1 shows the temperature computation. The example instruction code outlined in Figure 5-6 shows the communication flow. Additionally, refer to Figure 5-7 for the timing diagram.

EQUATION 5-1: BYTES TO TEMPERATURE CONVERSION

Temperature $\ge 0^{\circ}$ C $T_A = (UpperByte \times 2^4 + LowerByte \times 2^{-4})$ Temperature $< 0^{\circ}$ C $T_A = (UpperByte \times 2^4 + LowerByte \times 2^{-4}) - 256$ Where: T_A = Ambient Temperature (°C) UpperByte = T_A bit 15 to bit 8 LowerByte = T_A bit 7 to bit 0

This example routine assumes the varia	bles and I ² C [™] communication subroutines are predefined:
i2c_start();	// send START command
i2c_write(AddressByte & 0xFE);	//WRITE Command
	//also, make sure bit 0 is cleared '0'
i2c_write(0x05);	// Write T _A Register Address
i2c_start();	//Repeat START
i2c_write(AddressByte 0x01);	// READ Command
	//also, make sure bit 0 is Set '1'
UpperByte = i2c_read(ACK);	// READ 8 bits
	//and Send ACK bit
LowerByte = i2c_read(NAK);	// READ 8 bits
	//and Send NAK bit
i2c_stop();	// send STOP command
//Convert the temperature data	
//First Check flag bits	
if ((UpperByte & 0x80) == 0x80){	$//T_A \ge T_{CRIT}$
}	
if ((UpperByte & 0x40) == 0x40){	//T _A > T _{UPPER}
}	
if ((UpperByte & 0x20) == 0x20){	//T _A < T _{LOWER}
}	
UpperByte = UpperByte & 0x1F;	//Clear flag bits
if ((UpperByte & 0x10) == 0x10){	//T _A < 0°C
UpperByte = UpperByte & 0x0F;	//Clear SIGN
Temperature = (UpperByte x 16 + Lov	werByte / 16) - 256;
}else	$//T_A \ge 0^{\circ}C$
Temperature = (UpperByte x 16 + Lov	werByte / 16);
	<pre>//Temperature = Ambient Temperature (°C)</pre>



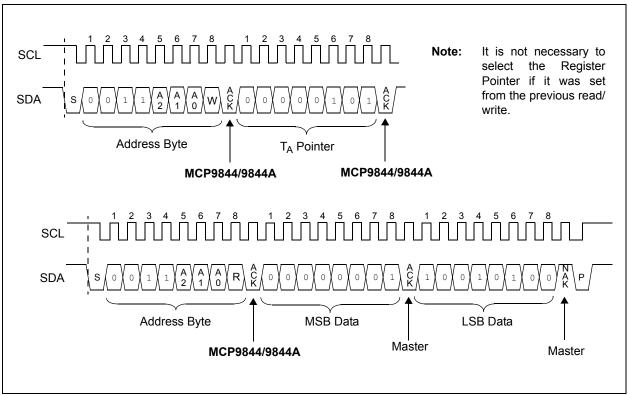
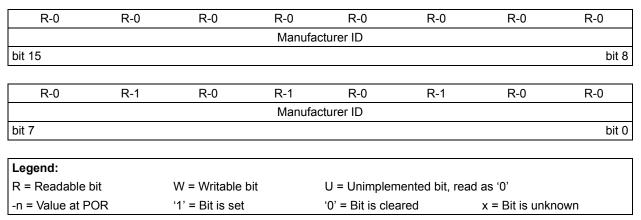


FIGURE 5-7: Timing Diagram for Reading +25.25°C Temperature from the T_A Register (See **Section 4.0 "Serial Communication"**).

5.1.5 MANUFACTURER ID REGISTER

This register is used to identify the manufacturer of the device in order to perform manufacturer specific operations. The Manufacturer ID for the MCP9844/ 9844A is 0x0054 (hexadecimal).

REGISTER 5-6: MANUFACTURER ID REGISTER (READ-ONLY) → ADDRESS `0000 0110'b



bit 15-0 Device Manufacturer Identification Number

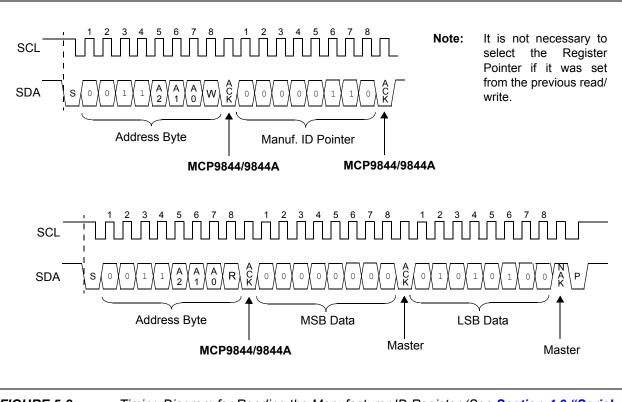


FIGURE 5-8: Timing Diagram for Reading the Manufacturer ID Register (See Section 4.0 "Serial Communication").

5.1.6 DEVICE ID AND REVISION REGISTER

The Device ID and Revision register is used to identify Microchip devices. The upper byte of these registers is used to specify the device identification and the lower byte is used to specify device silicon revision. The device ID for the MCP9844/9844A is 0x06 (hex).

The revision (Lower Byte) begins with 0x00 (hex) for the first release, with the number being incremented as revised versions are released (see Register 5-7 and Register 5-8).

REGISTER 5-7: DEVICE ID AND DEVICE REVISION (READ-ONLY) → ADDRESS `0000 1000' b (MCP9844)

R-0	R-0	R-0	R-0	R-0	R-1	R-1	R-0
			Devi	ce ID			
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-1
Device Revision							
bit 7 bit (bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Device ID: Bit 15 to bit 8 are used for device ID

bit 7-0 **Device Revision:** Bit 7 to bit 0 are used for device revision

R-0	R-0	R-0	R-0	R-0	R-1	R-1	R-0
Device ID							
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R-0	R-1	R-0
Device Revision							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8	Device ID: Bit 15 to bit 8 are used for device ID
bit 7 0	Device Povicion: Dit 7 to bit 0 are used for device revis

bit 7-0 Device Revision: Bit 7 to bit 0 are used for device revision

5.1.7 RESOLUTION REGISTER

This register allows the user to change the sensor resolution (see **Section 5.2.4** "**Temperature Resolution**"). The POR default resolution is 0.25°C. The selected resolution is also reflected in the Capability register (see Register 5-2).

Note: For MCP9844/9844A, in order to prevent accidentally writing the resolution register, a Shutdown command (using the CONFIG register) is required to change the resolution register. The device must be in Shutdown mode to change the resolution.

REGISTER 5-9: RESOLUTION REGISTER → `0000 1001'b (MCP9844) `0000 1000'b (MCP9844A)

R/W-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
				—			
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-1
			Re	solution			
bit 7							bit 0
Legend:							
R = Readable b	R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'						
-n = Value at P	OR	'1' = Bit is set	Bit is set '0' = Bit is cleared x = Bit is unknown				

bit 15 Unimplemented: Read as '0'

bit 14-2 Unimplemented: Read as '0'

bit 1-0 Resolution (MCP9844):

 $00 = LSb = 0.5^{\circ}C (t_{CONV} = 30 \text{ ms, typical})$

01 = LSb = 0.25°C (Power-up default, t_{CONV} = 65 ms, typical)

- $10 = LSb = 0.125^{\circ}C (t_{CONV} = 130 \text{ ms, typical})$
- $11 = LSb = 0.0625^{\circ}C$ (t_{CONV} = 260 ms, typical)

Resolution (MCP9844A):

- $00 = LSb = 0.5^{\circ}C (t_{CONV} = 10 \text{ ms, typical})$
- 01 = LSb = $0.25^{\circ}C$ (t_{CONV} = 20 ms, typical)
- $10 = LSb = 0.125^{\circ}C$ (t_{CONV} = 40 ms, typical)
- 11 = LSb = 0.0625°C (Power-up default, t_{CONV} = 80 ms, typical)

5.2 SENSOR FEATURE DESCRIPTION

5.2.1 SHUTDOWN MODE

Shutdown mode disables all power-consuming activities (including temperature sampling operations) while leaving the serial interface active. This mode is selected by setting bit 8 of CONFIG to '1'. In this mode, the device consumes I_{SHDN} . It remains in this mode until bit 8 is cleared '0' to enable Continuous Conversion mode, or until power is recycled.

The Shutdown bit (bit 8) cannot be set to '1' while bits 6 and 7 of CONFIG (Lock bits) are set to '1'. However, it can be cleared '0' or returned to Continuous Conversion while locked.

In Shutdown mode, all registers can be read or written. However, the serial bus activity increases the shutdown current.

If the device is shutdown while the Event pin is asserted, then the event output will be deasserted during shutdown. It will remain deasserted until the device is enabled for normal operation. Once the device is enabled, it takes t_{CONV} before the device reasserts the event output.

5.2.2 TEMPERATURE HYSTERESIS (T_{HYST})

A hysteresis of 0°C, 1.5°C, 3°C or 6°C can be selected for the T_{UPPER}, T_{LOWER} and T_{CRIT} temperate boundaries using bits 10 and 9 of CONFIG. The hysteresis applies for decreasing temperature only (hot to cold), or as temperature drifts below the specified limit.

The hysteresis bits can not be changed if either of the lock bits, bits 6 and 7 of CONFIG, are set to '1'.

The T_{UPPER} , T_{LOWER} and T_{CRIT} boundary conditions are described graphically in Figure 5-9.

5.2.3 EVENT OUTPUT CONFIGURATION

The event output can be enabled using bit 3 of CONFIG (Event Output Control bit) and can be configured as either a comparator output or as Interrupt Output mode using bit 0 of CONFIG (Event mode). The polarity can also be specified as an active-high or active-low using bit 1 of CONFIG (event polarity). The event output requires a pull-up resistor to function.

These configurations are designed to serve processors with low-to-high or high-to-low edge triggered inputs. With active-high configuration, when the event output deasserts, power will be dissipated across the pull-up resistor. When the ambient temperature increases above the critical temperature limit, the event output is forced to a comparator output (regardless of bit 0 of CONFIG). When the temperature drifts below the critical temperature limit minus hysteresis, the event output automatically returns to the state specified by bit 0 of CONFIG.

The status of the event output can be read using bit 4 of CONFIG (Event status). This bit can not be set to '1' in Shutdown mode.

Bit 7 and 6 of the CONFIG register can be used to lock the T_{UPPER} , T_{LOWER} and T_{CRIT} registers. The bits prevent false triggers at the event output due to an accidental rewrite to these registers.

The event output can also be used as a critical temperature output using bit 2 of CONFIG (critical output only). When this feature is selected, the event output becomes a comparator output. In this mode, the interrupt output configuration (bit 0 of CONFIG) is ignored.

5.2.3.1 Comparator Mode

Comparator mode is selected using bit 0 of CONFIG. In this mode, the event output is asserted as active-high or active-low using bit 1 of CONFIG. Figure 5-9 shows the conditions that toggle the event output.

If the device enters Shutdown mode with asserted event output, the output will deassert. It will remain deasserted until the device enters Continuous Conversion mode and after the first temperature conversion is completed, t_{CONV} . After the initial temperature conversion, T_A must satisfy the T_{UPPER} or T_{LOWER} boundary conditions in order for event output to be asserted.

Comparator mode is useful for thermostat type applications, such as turning on a cooling fan or triggering a system shutdown when the temperature exceeds a safe operating range.

5.2.3.2 Interrupt Mode

In Interrupt mode, the event output is asserted as activehigh or active-low (depending on the polarity configuration) when T_A drifts above or below T_{UPPER} and T_{LOWER} limits. The output is deasserted by setting bit 5 (Interrupt Clear) of CONFIG. If the device enters Shutdown mode with asserted event output, the output will deassert. It will remain deasserted until the device enters Continuous Conversion mode and after the first temperature conversion is completed, t_{CONV} . If the interrupt clear bit (bit 5) is never set, then the event output will reassert after the first temperature conversion.

In addition, if $T_A >= T_{CRIT}$, the event output is forced as Comparator mode and asserts until $T_A < T_{CRIT} - T_{HYST}$. While the event output is asserted, the user must send a Clear Interrupt command (bit 5 of CONFIG) for the event output to deassert when the temperature drops below the critical limit, $T_A < T_{CRIT} - T_{HYST}$. Otherwise, the event output remains asserted (see Figure 5-9 for a graphical description). Switching from Interrupt mode to Comparator mode also deasserts event output.

This mode is designed for interrupt driven microcontrollerbased systems. The microcontroller receiving the interrupt will have to acknowledge the interrupt by setting bit 5 of the CONFIG register from the MCP9844/9844A.

5.2.4 TEMPERATURE RESOLUTION

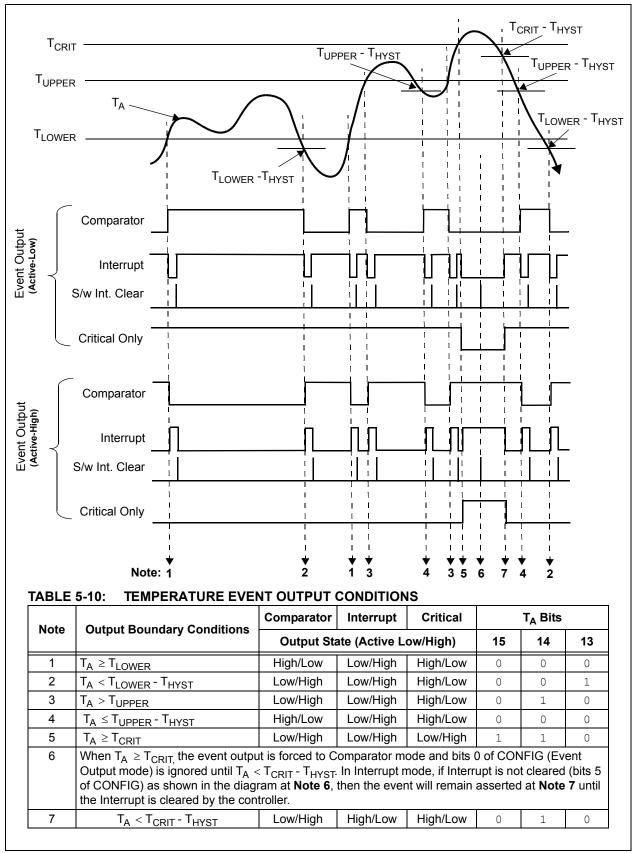
The MCP9844/9844A devices are capable of providing temperature data with 0.5°C to 0.0625°C resolution. The resolution can be selected using the Resolution register (Register 5-9), which is located in address '00001001'b for MCP9844 and '00001000'b for MCP9844A. For MCP9844/9844A, in order to prevent accidentally changing the resolution, the device must be in Shutdown mode to change this register. The selected resolution can be read by the user using bit 4 and bit 3 of the Capability register (Register 5-2).

TABLE 5-2: TEMPERATURE CONVERSION TIME (MCP9844)

Resolution	t _{CONV} (ms)	Samples/sec (typical)
0.5°C	30	33
0.25°C (Power-up default)	65	15
0.125°C	130	8
0.0625°C	260	4

TABLE 5-3: TEMPERATURE CONVERSION TIME (MCP9844A)

Resolution	t _{CONV} (ms)	Samples/sec (typical)
0.5°C	10	100
0.25°C	20	50
0.125°C	40	25
0.0625°C (Power-up default)	80	12





5.3 Summary of Power-on Default

The MCP9844/9844A have internal Power-On Reset (POR) circuits. If the power supply voltage V_{DD} glitches down to the V_{POR_TS} and V_{POR_EE} thresholds, the devices reset the registers to the power-on default settings.

Table 5-4 shows the power-on default summary for the temperature sensor.

Registers			Davies the Defeet		
Address (Hexadecimal)	Register Name	– Default Register Data (Hexadecimal)	Power-Up Default Register Description		
0x00	Capability	0x00EF (MCP9844) 0x00FF (MCP9844A)	Event output deasserts in shutdown I ² C [™] time out 25 ms to 35 ms. Accepts V _{HV} at A0 Pin 0.25°C Resolution (MCP9844) 0.0625°C Resolution (MCP9844A) Measures temperature below 0°C ±1°C accuracy over active range Temperature event output		
0x01	CONFIG	0x0000	Comparator mode Active-Low output Event and critical output Output disabled Event not asserted Interrupt cleared Event limits unlocked Critical limit unlocked Continuous conversion 0°C Hysteresis		
0x02	T _{UPPER}	0x0000	0°C		
0x03	T _{LOWER}	0x0000	0°C		
0x04	T _{CRIT}	0x0000	0°C		
0x05	T _A	0x0000	0°C		
0x06	Manufacturer ID	0x0054	—		
0x07	Microchip Device ID/ Device Revision (MCP9844)	0x0601	_		
	Microchip Device ID/ Device Revision (MCP9844A)	0x0602	_		
0x08	Reserved (MCP9844)	0x0601			
	Resolution (MCP9844A)	0x8003	Most Significant bit is set by default 0.0625°C Measurement Resolution		
0x09	Resolution (MCP9844)	0x8001	Most Significant bit is set by default 0.25°C Measurement Resolution		

TABLE 5-4: MCP9844/9844A TEMPERATURE SENSOR POWER-ON RESET DEFAULTS

6.0 APPLICATIONS INFORMATION

6.1 Layout Considerations

The MCP9844/9844A device does not require any additional components besides the master controller in order to measure temperature. However, it is recommended that a decoupling capacitor of 0.1 μ F to 1 μ F be used between the V_{DD} and GND pins. A high-frequency ceramic capacitor is recommended. It is necessary for the capacitor to be located as close as possible to the power and ground pins of the device in order to provide effective noise protection.

In addition, good PCB layout is key for better thermal conduction from the PCB temperature to the sensor die. For good temperature sensitivity, add a ground layer under the device pins as shown in Figure 6-1.

6.2 Thermal Considerations

A potential for self-heating errors can exist if the MCP9844/9844A SDA, SCLK and event lines are heavily loaded with pull-ups (high current). Typically, the self-heating error is negligible because of the relatively small current consumption of the MCP9844/9844A. A temperature accuracy error of approximately 0.5°C could result from self-heating if the communication pins sink/source the maximum current specified.

For example, if the event output is loaded to maximum I_{OL} , Equation 6-1 can be used to determine the effect of self-heating.

EQUATION 6-1: EFFECT OF SELF-HEATING

$T_{\Delta} = \theta_{JA} (V_{DD} \bullet I_{DD} +$	$V_{OL_Event} \bullet I_{OL_Event} + V_{OL_SDA} \bullet I_{OL_SDA})$
Where:	
T_{Δ} =	T _{J -} T _A
T _J =	Junction Temperature
T _A =	Ambient Temperature
$\theta_{JA} =$	Package Thermal Resistance
V _{OL_Event, SDA} =	Event and SDA Output V _{OL} (0.4 V _{max})
I _{OL_Event} , SDA =	Event and SDA Output I _{OL} (3 mA _{max} and 20 mA _{max,} respectively)

At room temperature (T_A = +25°C) with maximum I_{DD} = 500 μ A and V_{DD} = 3.6V, the self-heating due to power dissipation T_Δ is 0.58°C for the TDFN-8 package.

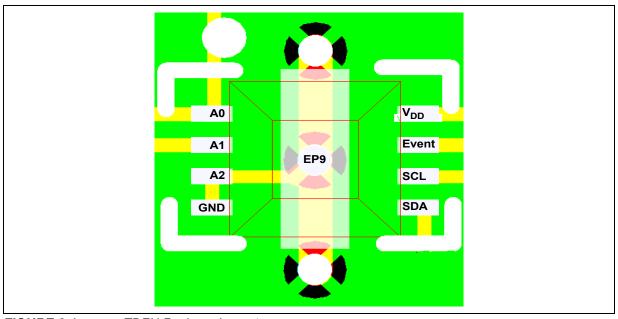


FIGURE 6-1: TDFN Package Layout.

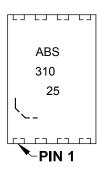
7.0 PACKAGING INFORMATION

7.1 Package Marking Information

8-Lead TDFN (2x3) (MCP9844/44A)



Part Number	Code
MCP9844T-BE/MNY	ABS
MCP9844AT-E/MNY	ADF

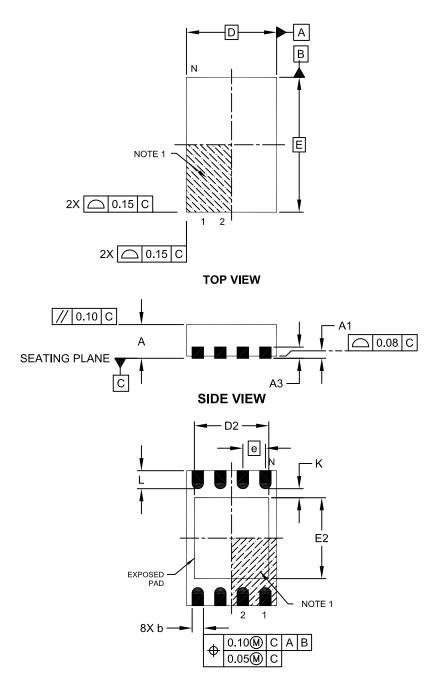


Example:

Legen	d: XXX Y YY WW NNN e3 *	Customer-specific information Year code (last digit of calendar year) Year code (last 2 digits of calendar year) Week code (week of January 1 is week '01') Alphanumeric traceability code Pb-free JEDEC [®] designator for Matte Tin (Sn) This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.
Note:	be carrie	nt the full Microchip part number cannot be marked on one line, it will d over to the next line, thus limiting the number of available s for customer-specific information.

8-Lead Plastic Dual Flat, No Lead Package (MN) – 2x3x0.75mm Body [TDFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging

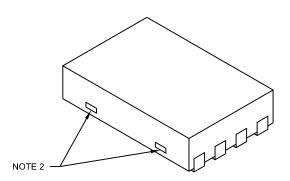


BOTTOM VIEW

Microchip Technology Drawing No. C04-129C Sheet 1 of 2

8-Lead Plastic Dual Flat, No Lead Package (MN) – 2x3x0.75mm Body [TDFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	N	ILLIMETER	S
Dimensior	n Limits	MIN	NOM	MAX
Number of Pins	Ν		8	
Pitch	е		0.50 BSC	
Overall Height	Α	0.70	0.75	0.80
Standoff	A1	0.00	0.02	0.05
Contact Thickness	A3	0.20 REF		
Overall Length	D	2.00 BSC		
Overall Width	E	3.00 BSC		
Exposed Pad Length	D2	1.20	-	1.60
Exposed Pad Width	E2	1.20	-	1.60
Contact Width	b	0.20	0.25	0.30
Contact Length	L	0.25	0.30	0.45
Contact-to-Exposed Pad	K	0.20	-	-

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Package may have one or more exposed tie bars at ends.

3. Package is saw singulated

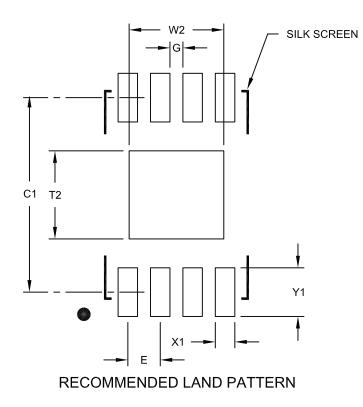
4. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances. REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing No. C04-129C Sheet 2 of 2

8-Lead Plastic Dual Flat, No Lead Package (MN) – 2x3x0.75 mm Body [TDFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units		١	MILLIMETER	S
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	E 0.50 BSC		
Optional Center Pad Width	W2			1.46
Optional Center Pad Length T2				1.36
Contact Pad Spacing C1			3.00	
Contact Pad Width (X8)	X1			0.30
Contact Pad Length (X8)	Y1			0.75
Distance Between Pads G		0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2129A

APPENDIX A: REVISION HISTORY

Revision C (October 2016)

Added the MCP9844A device. The following is the list of modifications.

- 1. Updated the Temperature Sensor DC Characteristics table.
- 2. Updated the sections:
 - Section 2.0 "Typical Performance Curves"
 - Section 5.1 "Registers"
 - Section 5.2.4 "Temperature Resolution"
 - Section 7.0 "Packaging Information"
 - Section "Product Identification System"
- 3. Updated verbiage throughout the document.

Revision B (July 2014)

The following is the list of modifications.

- 4. Updated the Serial Interface Timing Specifications section to include 400 kHz operation from 1.7V to 3.6V.
- 5. Updated the Temperature Sensor DC Characteristics table.
- 6. Updated verbiage throughout the document.

Revision A (March 2013)

• Original release of this document.

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

Device Temp	X /XX erature Package nge	Exa a) b)	MCP9844T-BE/MNY:	Tape and Reel, Extended temp., 8LD 2x3 TDFN pkg. Tape and Reel,
Devices:	MCP9844T: Temperature Sensor MCP9844AT: Temperature Sensor	5)		Extended temp., 8LD 2x3 TDFN pkg.
Temperature Range:	E = -40° C to $+125^{\circ}$ C (Extended)			
Package:	MNY* = Plastic Dual Flat, No Lead, (2x3 TDFN), 8-lead (TDFN)			
	* Y = Nickel palladium gold manufacturing designator. Only available on the TDFN package.			

MCP9844/44A

NOTES:

Note the following details of the code protection feature on Microchip devices:

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