ebm-papst Mulfingen GmbH & Co. KG

Bachmühle 2 D-74673 Mulfingen Phone +49 (0) 7938 81-0 Fax +49 (0) 7938 81-110 info1@de.ebmpapst.com www.ebmpapst.com

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1. SAFETY REGULATIONS AND INFORMATION

Read these operating instructions carefully before starting work on the device. Observe the following warnings to prevent malfunctions or danger to persons.

These operating instructions are to be regarded as part of the device. The device is only to be sold or passed on together with the operating instructions.

These operating instructions may be duplicated and distributed to inform about potential dangers and their prevention.

1.1 Hazard levels for warnings

These operating instructions use the following hazard levels to indicate potentially hazardous situations and important safety regulations:



DANGER

Indicates an imminently hazardous situation which will result in death or serious injury if the specified actions are not taken. Compliance with the instructions is imperative.

WARNING

Indicates a potentially hazardous situation which can result in death or serious injury if the specified actions are not taken. Exercise extreme caution while working.

CAUTION

Indicates a potentially hazardous situation which can result in minor or moderate injury or damage to property if the specified actions are not taken

NOTE

A potentially harmful situation can occur and, if not avoided, can lead to property damage.

1.2 Staff qualifications

The device may only be transported, unpacked, installed, operated, maintained and otherwise used by suitably qualified, trained and authorized technical staff.

Only authorized specialists are permitted to install the device, to carry out a test run and to perform work on the electrical installation.

1.3 Basic safety rules

The safety hazards associated with the device must be assessed again following installation in the final product.

Note the following when working on the device:

⇒ Do not perform any modifications, additions or conversions on the device without the approval of ebm-papst.

1.4 Voltage

- Check the device's electrical equipment at regular intervals; see Chapter 6.2 Safety inspection.
- > Replace loose connections and defective cables immediately.



DANGER

Electrically charged device

Risk of electric shock

→ When working on an electrically charged device, stand on a rubber mat.

WARNING

Live terminals and connections even with device switched off

Electric shock





→ Wait five minutes after disconnecting the voltage at all poles before opening the device.

CAUTION

In the event of a fault, the rotor and the impeller will be energized

The rotor and the impeller have basic insulation.

→ Do not touch the rotor and impeller once installed.

CAUTION

If control voltage or a stored speed set value is applied, the motor will restart automatically, e.g. after a power failure.

Risk of injury

- → Keep out of the device danger zone.
- When working on the device, switch off the line voltage and ensure that it cannot be switched back on.
- → After working on the device, remove any tools or other objects from the device.

1.5 Safety and protective features



DANGER

Protective device missing and protective device not functioning

Without a protective device there is a risk of serious injury, for instance if the hands reach or are sucked into the device during operation.

- → Operate the device only with a fixed protective device and guard grille.# The fixed protective device must be able to withstand the kinetic energy of a fan blade that becomes detached at maximum speed. There must not be any gaps which it is possible to reach into with the fingers, for example.
- → The device is a built-in component. As the operator, you are responsible for ensuring that the device is secured adequately.
- → Stop the device immediately if you notice a missing or ineffective protective device.

1.6 Electromagnetic radiation

Interference from electromagnetic radiation is possible, e.g. in conjunction with open- and closed-loop control devices.

If impermissible radiation levels occur following installation, appropriate shielding measures have to be taken by the user.

NOTE

Electrical or electromagnetic interference after installing the device in customer equipment.

→ Verify that the entire setup is EMC-compliant.

1.7 Mechanical movement



DANGER

Rotating device

Risk of injury to body parts coming into contact with the rotor or the impeller.

- → Secure the device against accidental contact.
- → Before working on the system/machine, wait until all parts have come to a standstill.



DANGER

Ejected parts

Missing protective devices may cause balancing weights or broken fan blades to be ejected and cause injuries.

→ Take appropriate safety measures.

WARNING

Rotating device

Long hair and dangling items of clothing, jewelry and the like can become entangled and be pulled into the device. Injuries can result

→ Do not wear any loose-fitting or dangling clothing or jewelry while working on rotating parts.#Protect long hair with a cap.

1.8 Emissions

WARNING

Depending on the installation and operating conditions, the sound pressure level may exceed 70 dB(A).

Risk of noise-induced hearing loss

- → Take appropriate technical safety measures.
- → Protect operating personnel with appropriate safety equipment such as hearing protection.
- → Also observe the requirements of local agencies.

1.9 Hot surface



CAUTION

High temperature on electronics housing

Risk of burns

 \rightarrow Ensure sufficient protection against accidental contact.

1.10 Transport

WARNING

Transporting the fan

Injuries from tipping or slipping

→ Wear safety shoes and cut-resistant safety gloves. #The fan is only to be transported in its original packaging. #The fan is to be transported lying flat, i.e. the motor axis must be vertical. #Secure the fan(s) e.g. with a lashing strip to stop anything slipping or tipping.

1.11 Storage

- ⇒ Store the device, partially or fully assembled, in a dry and weatherproof manner in the original packaging in a clean environment.
- ⇒ Protect the device against environmental effects and dirt until final installation.
- We recommend storing the device for no longer than one year in order to guarantee trouble-free operation and the longest possible service life.
- ⇒ Even devices explicitly intended for outdoor use are to be stored as described prior to commissioning.
- Maintain the storage temperature, see Chapter 3.6 Transport and storage conditions.





2. INTENDED USE

The device is exclusively designed as a built-in device for conveying air according to its technical data.

Any other usage above and beyond this does not conform with the intended purpose and constitutes misuse of the device.

Customer equipment must be capable of withstanding the mechanical and thermal stresses that can arise from this product. This applies for the entire service life of the equipment in which this product is installed.

Intended use also includes

- Using the device only in power systems with grounded neutral (TN/ TT power systems).
- · Using the device only in stationary systems.
- Performing all maintenance work.
- conveying air at an ambient air pressure between 750 mbar and 1050 mbar.
- Using the device within the permitted ambient temperature range; see Chapter 3.6 Transport and storage conditions and Chapter 3.2 Nominal data.
- · Operating the device with all protective devices.
- Following the operating instructions.

Improper use

In particular, operating the device in the following ways is prohibited and could be hazardous:

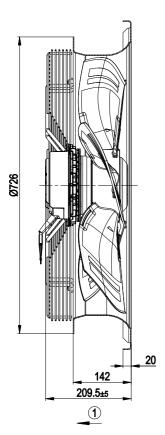
- Operating the device in an unbalanced state, e.g. due to dirt deposits or ice formation.
- Operation in medical equipment with a life-sustaining or life-support function
- Operation with external vibrations.
- · Conveying solids in the flow medium.
- Painting the device
- Connections (e.g. screws) coming loose during operation.
- Conveying air that contains abrasive particles.
- Conveying highly corrosive air, e.g. salt spray. Exception: devices
 designed for salt spray and correspondingly protected.
- Conveying air with high dust content, e.g. suctioning off sawdust.
- Operating the device close to flammable materials or components.
- Operating the device in an explosive atmosphere.
- Using the device as a safety component or to perform safety-related functions.
- Operation with completely or partially disassembled or manipulated protective devices.
- In addition, all applications not listed among the intended uses.

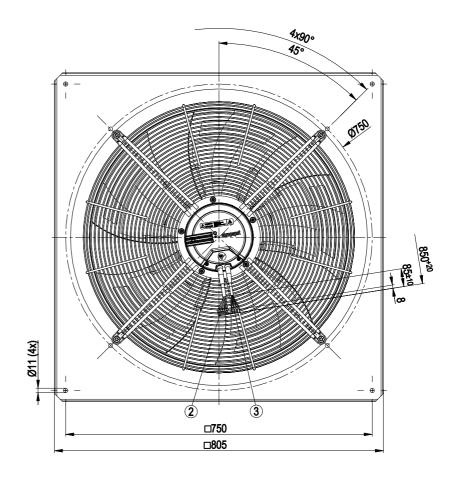




3. TECHNICAL DATA

3.1 Product drawing





All dimensions in mm.

1	Direction of air flow "V"
2	Cable PVC AWG18, 6x crimped ferrules
3	Cable PVC AWG22, 4x crimped ferrules

3.2 Nominal data

Motor	M3G112-IA
D.	
Phase	3~
Nominal voltage / VAC	400
Nominal voltage	380 480
range / VAC	
Frequency / Hz	50/60
Method of obtaining	ml
data	
Speed / min-1	1140
Power consumption / W	970
Current draw / A	1.6
Max. back pressure / Pa	170
Min. ambient	-25
temperature / °C	
Max. ambient	60
temperature / °C	

ml = Max. load \cdot me = Max. efficiency \cdot fa = Free air cs = Customer specification \cdot ce = Customer equipment

3.3 Data according to ErP Directive

	Actual	Reg. 2015	
01 Overall efficiency ηes / %	45.1	33.6	
02 Measurement category	A		
03 Efficiency category	Static		
04 Efficiency grade N	51.5	40	
05 Variable speed drive	Yes	·	
06 Year of manufacture	The year of manufacture is specified on the product's rating label.		
07 Manufacturer			
08 Type	W3G630-GR85-01		
09 Power consumption Ped / kW	0.97		
09 Air flow qv / m³/h	8935		
09 Pressure increase total psf / Pa	163		
10 Speed n / min-1	1155		
11 Specific ratio*	1.00		
12 Recycling/disposal		cycling and disposal is perating instructions.	
13 Maintenance		stallation, operation and rovided in the operating	
14 Additional components	efficiency that are	d to calculate the energy e not apparent from the egory are detailed in the	

^{*} Specific ratio = 1 + pfs / 100 000 Pa

Data obtained at optimum efficiency level. The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

3.4 Technical description

Weight	25.4 kg	
Fan size	630 mm	
Rotor surface	Painted black	
Electronics housing	Die-cast aluminum, painted black	
material	, , ,	
Blade material	Press-fitted sheet steel blank, sprayed	
	with PP plastic	
Fan housing material	Sheet steel, pre-galvanized and coated	
. an nousing material	with black plastic (RAL 9005)	
Guard grille material	Steel, coated with black plastic (RAL	
Guara grino material	9005)	
Number of blades	5	
Blade pitch	-5°	
Airflow direction	"\/"	
Direction of rotation	Counterclockwise, viewed toward rotor	
Degree of protection	IP54; installation- and position-dependent	
pegree or protection	as per EN 60034-5	
Insulation class	as per EN 60034-5 "B"	
	B F4-1	
Moisture (F) /	F4-1	
Environmental (H) protection class		
<u>-</u>	Chaft having stal as sales as hatters, sales	
Installation position	Shaft horizontal or rotor on bottom; rotor	
Condensation	on top on request On rotor side	
	On rotor side	
drainage holes	04	
Mode	S1	
84 ()	ID 111 :	
Motor bearing	Ball bearing	
Motor bearing Technical features	- Output 10 VDC, max. 10 mA	
	- Output 10 VDC, max. 10 mA - Alarm relay	
	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller	
	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation	
	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive	
	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start	
	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM	
	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential	
	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply	
	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for	
	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor	
	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure	
Technical features	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection	
Technical features Touch current	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure	
Touch current according to IEC	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection	
Touch current according to IEC 60990 (measuring	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection	
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection	
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection <= 3.5 mA	
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection <= 3.5 mA	
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system) Motor protection	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection <= 3.5 mA Thermal overload protector (TOP) internally connected	
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system) Motor protection with cable	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection <= 3.5 mA Thermal overload protector (TOP) internally connected Variable	
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system) Motor protection	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection <= 3.5 mA Thermal overload protector (TOP) internally connected Variable I (with customer connection of protective	
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system) Motor protection with cable Protection class	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection <= 3.5 mA Thermal overload protector (TOP) internally connected Variable I (with customer connection of protective earth)	
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system) Motor protection with cable Protection class Conformity with	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection <= 3.5 mA Thermal overload protector (TOP) internally connected Variable I (with customer connection of protective	
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system) Motor protection with cable Protection class	- Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection <= 3.5 mA Thermal overload protector (TOP) internally connected Variable I (with customer connection of protective earth)	





Subject to change



With regard to cyclic speed loads, note that the rotating parts of the device are designed for a maximum of one million load cycles. If you have special questions, consult ebm-papst for support.

3.5 Mounting data

For screw clearance, see Chapter 3.1 Product drawing

Secure the screws against unintentional loosening (e.g. use self-locking screws).

Strength class of	8.8
screws	

Any further mounting data required can be taken from the product drawing.

3.6 Transport and storage conditions

⇒ Use the device in accordance with its degree of protection.

Max. permitted ambient temp. for motor (transport/ storage)	+ 80 °C
Min. permitted ambient temp. for motor (transport/ storage)	- 40 °C

3.7 Electromagnetic compatibility

EMC immunity to	According to EN 61000-6-2 (industrial
interference	environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference	According to EN 55022 (Class B,
emission	household environment)



If several devices are switched in parallel on the supply side so that the line current of the arrangement is in the range of 16-75 A, then this arrangement conforms to IEC 61000-3-12 provided that the short-circuit power S_{SC} at the connection point of the customer system to the public power system is greater than or equal to 120 times the rated output of the arrangement. It is the responsibility of the installation engineer or operator/owner of the device to ensure, if necessary after consultation with the network operator, that this device is only connected to a connection point with a S_{SC} value that is greater than or equal to 120 times the rated output of the arrangement.

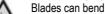
4. CONNECTION AND STARTUP

4.1 Mechanical connection



CAUTION

Cutting and crushing hazard when removing device from packaging



- → Carefully remove the device from its packaging, by the fan housing. Strictly avoid shocks.
- → Wear safety shoes and cut-resistant safety gloves.

CAUTION

Heavy load when unpacking device

Risk of physical injury, such as back injuries.

- → Two people should work together to remove the device from its packaging.
- ⇒ Check the device for transport damage. Damaged devices are not to be installed
- ⇒ Install the undamaged device in accordance with your application.



CAUTION

Possible damage to the device

If the device slips during installation, serious damage can result.

Ensure that the device is securely positioned at its place of installation until all fastening screws have been tightened.

4.2 Electrical connection



DANGER

Voltage on the device

Electric shock

- → Always connect a protective earth first.
- → Check the protective earth.



DANGER

Faulty insulation

Risk of fatal injury from electric shock

- → Use only cables that meet the specified installation regulations for voltage, current, insulation material, capacity, etc.
- → Route cables so that they cannot be touched by any rotating parts.



DANGER

Electrical charge (>50 μ C) between phase conductor and protective earth connection after switching off supply with multiple devices connected in parallel.

Electric shock, risk of injury

→ Ensure sufficient protection against accidental contact. Before working on the electrical hookup, short the supply and PE connections.

CAUTION

Voltage

The fan is a built-in component and has no disconnecting switch.

- → Only connect the fan to circuits that can be switched off with an all-pole disconnection switch.
- → When working on the fan, secure the system/machine in which the fan is installed so as to prevent it from being switched back on.





NOTE

Device malfunctions possible

Route the device's control lines separately from the supply line.

→ Maintain the greatest possible clearance. Recommendation: clearance > 10 cm (separate cable routing)

NOTE

Water ingress into wires or cables

Water ingress at the customer end of the cable can damage the device.

→ Make sure the end of the cable is connected in a dry environment.



Only connect the device to circuits that can be switched off with an all-pole disconnection switch.

4.2.1 Requirements

- ⇒ Check whether the data on the nameplate match the connection data.
- ⇒ Before connecting the device, make sure the power supply matches the device voltage.
- Only use cables designed for the current level indicated on the nameplate.

For determining the cross-section, note the sizing criteria according to EN 61800-5-1. The protective earth must have a cross-section equal to or greater than that of the phase conductor.

We recommend the use of 105 $^{\circ}\text{C}$ cables. Ensure that the minimum cable cross-section is at least

AWG 26 / 0.13 mm².

Ground conductor contact resistance according to EN 61800-5-1

Compliance with the impedance specifications according to EN 61800-5-1 for the protective earth connection circuit must be verified in the end application.

Depending on the circumstances of installation, it may be necessary to connect an additional protective earth conductor to the extra protective earth terminal on the device.

The protective earth terminal is on the housing and has a ground conductor symbol and a bore hole.

4.2.2 Supply connection and fuses

Assignment of supply cable cross-sections and their required fuses (line protection only, no equipment protection).

Nominal voltage	Fuse		Automatic circuit breaker	Cable cross- section	Cable cross-section
	VDE	UL	VDE	mm²	*AWG
3/PE AC 380-480 VAC	16 A	15 A	C16A	1.5	16
3/PE AC 380-480 VAC	20 A	20 A	C20A	2.5	14
3/PE AC 380-480 VAC	25 A	25 A	C25A	4.0	12
3/PE AC 380-480 VAC	32 A	30 A	C32A	6.0	10

^{*} AWG = American Wire Gauge

4.2.3 Reactive currents



Because of the EMC filter integrated for compliance with EMC limits (interference emission and immunity to interference), reactive currents can be measured in the supply line even when the motor is at a standstill and the line voltage is switched on.

- The values are typically less than 250 mA.
- At the same time, the effective power in this operating state (operational readiness) is typically < 5 W.

4.2.4 Residual current circuit breaker (RCCB)



Only universal residual current devices (type B or B+) are allowed. As with variable frequency drives, residual current devices cannot provide personal safety while operating the device

When the device's power supply is switched on, pulsed charging currents from the capacitors in the integrated EMC filter can lead to the residual current devices tripping without delay. We recommend the use of residual current circuit breakers with a trip threshold of 300 mA and delayed tripping (super-resistant, characteristic K).

4.2.5 Leakage current



For asymmetrical power systems or if a phase fails, the leakage current can increase to a multiple of the nominal value.

4.2.6 Locked-rotor protection



Due to the locked-rotor protection, the starting current (LRA) is equal to or less than the nominal current (FLA).

4.3 Connecting the cables

The device has external leads.

- ⇒ First connect the "PE" (protective earth).
- Connect the cables according to your application. When doing so, observe Chapter 4.4 Connection diagram.

4.3.1 Cable routing

Water must be prevented from reaching the cable exit along the cable.

Fans installed lying flat

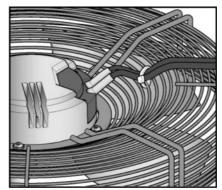


Fig. 1: Fan installed lying flat, cable routed in a U-shaped loop.

- ⇒ Make sure the cable is routed in a U-shaped loop.
- ⇒ Avoid kinks or bends in the bushing.





Fans installed upright

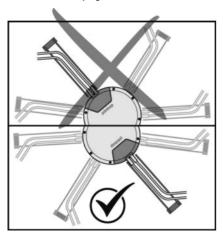
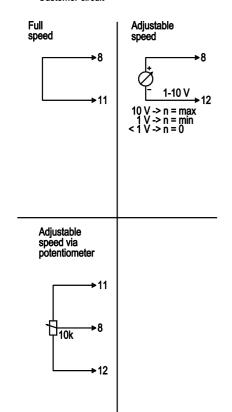


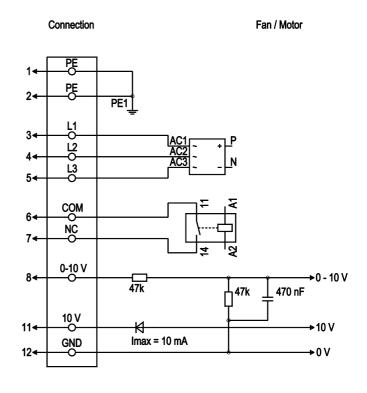
Fig. 2: Cable routing for fans installed upright. The cables must always be routed downward.



4.4 Connection diagram

Customer circuit





Drawing preliminary!

No.	Conn.	Designation	Color	Function/assignment
1	1, 2	PE	green/	Protective earth
			yellow	
1	3, 4, 5	L1, L2, L3	black	Power supply 50 / 60 Hz
1	6	COM	white 1	Floating status contact, break for failure (2A, max. 250 VAC, min. 10 mA, AC1)
1	7	NC	white 2	Floating status contact, break for failure
2	8	0 - 10 V	yellow	Control input, set value 0-10 VDC, impedance 100 kOhm, SELV
2	11	+ 10 V	red	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g.
				potentiometers), SELV
2	12	GND	blue	Reference ground for control interface, SELV



4.5 Checking connections

- ⇒ Ensure isolation from supply (all phases).
- ⇒ Make sure a restart is impossible
- Check the cables for proper fit.

4.6 Switching on the device

The device may only be switched on if it has been installed properly and in accordance with its intended use, including the required safety mechanisms and professional electrical hookup. This also applies for devices which have already been equipped with plugs and terminals or similar connectors by the customer.



WARNING Hot motor housing

Risk of fire

- → Ensure that no combustible or flammable materials are located close to the fan.
- ⇒ Before switching on, check the device for visible external damage and make sure the protective devices are functional.
- Check the fan's air flow paths for foreign matter and remove any foreign matter found.
- Apply the nominal supply voltage.
- Start the device by changing the input signal.

4.7 Switching off the device

Switching off the device during operation:

- ⇒ Switch off the device via the control input.
- Do not switch the motor (e.g. in cyclic operation) on and off via power supply.

Switching off the device for maintenance:

- ⇒ Switch off the device via the control input.
- Do not switch the motor (e.g. in cyclic operation) on and off via power supply.
- ⇒ Disconnect the device from the power supply.
- ⇒ When disconnecting, be sure to disconnect the ground connection last.

5. INTEGRATED PROTECTIVE FEATURES

The integrated protective functions cause the motor to switch off automatically in the event of the faults described in the table.

Fault	Safety feature description/ function
Rotor position detection error	An automatic restart follows.
Blocked rotor	⇒ After the blockage is
	removed, the motor restarts
	automatically.
Line undervoltage (line voltage	⇒ If the line voltage returns to
outside of permitted nominal	permitted values, the motor
voltage range)	restarts automatically.
Phase failure	A phase of the supply voltage
	fails for at least 5 s.
	⇒ When all phases are
	correctly supplied again, the
	motor automatically restarts after
	10-40 s.

6. MAINTENANCE, MALFUNCTIONS, POSSIBLE CAUSES AND REMEDIES

Do not perform any repairs on your device. Send the device to ebmpapst for repair or replacement.

WARNING

Live terminals and connections even with device switched off

Electric shock

→ Wait five minutes after disconnecting the voltage at all poles before opening the device.

CAUTION

If control voltage or a stored speed set value is applied, the motor will restart automatically, e.g. after a power failure.

Risk of injury

- \rightarrow Keep out of the device danger zone.
- → When working on the device, switch off the line voltage and ensure that it cannot be switched back on.
- → After working on the device, remove any tools or other objects from the device.



If the device is out of use for some time, e.g. when in storage, we recommend switching it on for at least two hours to allow any condensation to evaporate and to move the bearings.

Malfunction/fault	Possible cause	Possible remedy
Impeller not running smoothly	Imbalance in rotating parts	Clean the device; replace it if imbalance persists after cleaning. Make sure no weight clips are removed during cleaning.
Motor not turning	Mechanical blockage	Switch off, isolate from supply and remove mechanical blockage.





Line voltage faulty	Check line voltage, restore power supply. Attention! The error message resets automatically. Device restarts automatically without warning.
Faulty connection	Isolate from supply, correct connection; see connection diagram.
Broken motor winding	Replace device
Thermal overload protector activated	Allow motor to cool off, locate and rectify cause of error, release restart lockout if necessary
Deficient cooling	Improve cooling. Let the device cool down. To reset the error message, switch off the line voltage for at least 25 s and then switch it on again. Alternatively, reset the error message by applying a control signal of < 0.5 V to Din1 or by shorting Din1 to GND.
Ambient temperature too high	Reduce the ambient temperature. Let the device cool down. To reset the error message, switch off the line voltage for at least 25 s and then switch it on again. Alternatively, reset the error message by applying a control signal of < 0.5 V to Din1 or by shorting Din1 to GND.
Impermissible point of operation (e.g. back pressure too high)	Correct the operating point. Let the device cool down. To reset the error message, switch off the line voltage for at least 25 s and then switch it on again. Alternatively, reset the error message by applying a control signal of < 0.5 V to Din1 or by shorting Din1 to GND.



In the event of further malfunctions, contact ebm-papst.

6.1 Cleaning

NOTE

Damage to the device during cleaning

Malfunction possible

→ Do not clean the device using a water jet or high-pressure cleaner.# Do not use any acid, alkali or solventbasedcleaning agents.# Do not use any pointed or sharpedged objects for cleaning

6.2 Safety inspection

NOTE

High-voltage test

The integrated EMC filter has Y capacitors. The tripping current is exceeded when AC testing voltage is applied.

→ Test the device with DC voltage when you perform the legally required high-voltage test. The voltage to be used corresponds to the peak value of the AC voltage required by the standard.

What to check	How to check	How often	What action?
Contact protection cover for intactness or damage	Visual inspection	At least every 6 months	Repair or replacement of device
Device for damage to blades and housing	Visual inspection	At least every 6 months	Replacement of device
Fastening the cables	Visual inspection	At least every 6 months	Fasten
Insulation of cables for damage	Visual inspection	At least every 6 months	Replace cables
Condensation drainage holes for clogging, where necessary	Visual inspection	At least every 6 months	Open holes
Welds for crack formation	Visual inspection	At least every 6 months	Replace device

6.3 Disposal

For ebm-papst, environmental protection and resource preservation are top priority corporate goals.

ebm-papst operates an environmental management system which is certified in accordance with ISO 14001 and rigorously implemented around the world on the basis of German standards.

Right from the development stage, ecological design, technical safety and health protection are fixed criteria.

The following section contains recommendations for ecological disposal of the product and its components.





6.3.1 Country-specific legal requirements



NOTE

Country-specific legal requirements

Always observe the applicable country-specific legal regulations with regard to the disposal of products or waste occurring in the various phases of the life cycle. The corresponding disposal standards are also to be heeded.

6.3.2 Disassembly

Disassembly of the product must be performed or supervised by qualified personnel with the appropriate technical knowledge. The product is to be disassembled into suitable components for disposal employing standard procedures for motors.



WARNING

Heavy parts of the product may drop off. Some of the product components are heavy. These components could drop off during disassembly.

This can result in fatal or serious injury and material damage.

→ Secure components before unfastening to stop them falling.

6.3.3 Component disposal

The products are mostly made of steel, copper, aluminum and plastic. Metallic materials are generally considered to be fully recyclable. Separate the components for recycling into the following categories:

- Steel and iron
- Aluminum
- Non-ferrous metal, e.g. motor windings
- Plastics, particularly with brominated flame retardants, in accordance with marking
- Insulating materials
- Cables and wires
- Electronic scrap, e.g. circuit boards

Only ferrite magnets and not rare earth magnets are used in external rotor motors from ebm-papst Mulfingen GmbH & Co. KG.

Ferrite magnets can be disposed of in the same way as normal iron and steel.

Electrical insulating materials on the product, in cables and wires are made of similar materials and are therefore to be treated in the same manner.

The materials concerned are as follows:

- · Miscellaneous insulators used in the terminal box
- Power cables
- Cables for internal wiring
- Electrolytic capacitors

Dispose of electronic components employing the proper procedures for electronic scrap.



→ Please contact ebm-papst for any other questions on disposal.



