

# CE

#### **Model Number**

#### UB500-F54-E5-V15

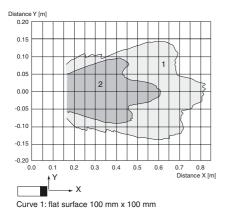
Single head system

#### **Features**

- Switch output
- 5 output modes
- **Program input**
- Synchronization options
- **Deactivation option**
- **Temperature compensation**

## **Curves**

#### Characteristic response curve



Curve 2: round bar, Ø 25 mm

# **Technical data**

General	specifications

Sensing range 30 ... 500 mm 50 ... 500 mm Adjustment range 0 ... 30 mm Unusable area Standard target plate 100 mm x 100 mm approx. 380 kHz Transducer frequency Response delay ≤ 50 ms

#### Indicators/operating means

LED green permanently green: monitoring system green flashing: program function

LED yellow indication of the switching state

flashing: program function object detected LED red flashing:

normal mode: error Program function: no object detected

permanently:
Program mode, object uncertain

**Electrical specifications** 

Operating voltage U<sub>B</sub> 10 ... 30 V DC , ripple 10 %SS

No-load supply current I<sub>0</sub> ≤ 55 mA

Input/output

1 synchronous input Synchronization

0 level: U<sub>B...+1</sub> V 1 level: +4 V...+U<sub>B</sub>

input impedance: > 12 KOhm synchronization pulse: 0.1 ... 8 ms

Synchronization frequency

Common mode operation

Multiplex operation ≤ 100 / n Hz, n = number of sensors

Input

Input type

1 program input, switching point A1: -U  $_{B}\dots$  +1 V, switching point A2: +4 V  $\dots$ 

input impedance: > 4.7 k $\Omega$ , program pulse:  $\geq$  1 s

Output Output type 1 switch output E5, pnp NO/NC

Rated operational current Ie 200 mA, short-circuit/overload protected

Voltage drop U<sub>d</sub> ≤ 3 V

Repeat accuracy ≤ 1 % of full-scale value

Switching frequency f max. 10 Hz

Range hysteresis H ≤ 1 % of the set operating distance

Temperature influence ± 1.5 % of full-scale value Ambient conditions

Ambient temperature

-25 ... 70 °C (248 ... 343 K) -40 ... 85 °C (233 ... 358 K) Storage temperature

Mechanical specifications

Protection degree

Connection connector V15 (M12 x 1), 5 pin

Material

ABS Housing

Transducer epoxy resin/hollow glass sphere mixture; polyurethane foam

Mass

Compliance with standards and directives

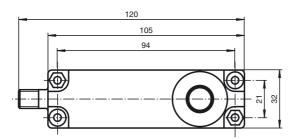
Pepperl+Fuchs Group • Tel.: Germany +49 621 776-0 • USA +1 330 4253555 • Singapore +65 67799091 • Internet http://www.pepperl-fuchs.com

Standard conformity

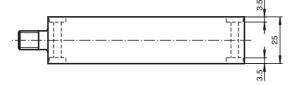
Standards EN 60947-5-2:2007

IEC 60947-5-2:2007

#### **Dimensions**

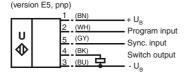


Bore hole and countersinking for screws/hexagon M4



#### **Electrical Connection**

#### Standard symbol/Connections:



Wire colors in accordance with EN 60947-5-2

#### **Pinout**

## **Connector V15**



## Synchronisation

The sensor features a synchronisation input for the suppression of mutual interference. If this input is not used, the sensor will operate using an internally generated clock rate. The synchronisation of multiple sensors can be realised as follows:

## External synchronisation

The sensor can be synchronised by the external application of a square wave voltage. A synchronisation pulse at the synchronisation input starts a measuring cycle. The pulse must have a duration greater than 100  $\mu s$ . The measuring cycle starts with the falling edge of a synchronisation pulse. A low level >1 s or an open synchronisation input will result in the normal operation of the sensor. A high level at the synchronisation input disables the sensor.

Two operating modes are available

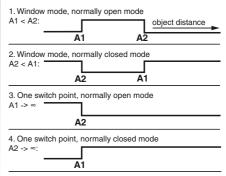
- Multiple sensors can be controlled by the same synchronisation signal. The sensors are synchronised.
- 2. The synchronisation pulses are sent cyclically to individual sensors. The sensors operate in multiplex mode.

## Internal synchronisation

The synchronisation connections of up to 5 sensors capable of internal synchronisation are connected to one another. When power is applied, these sensors will ope-

#### **Additional Information**

#### Programmable output modes



5. A1 -> ∞, A2 -> ∞: Object presence detection mode Object detected: Switch output closed No object detected: Switch output open

## **Accessories**

#### **UB-PROG2**

Programming unit

V15-G-2M-PVC

Cable connector

V15-W-2M-PUR

Cable connector

rate in multiplex mode. The response delay increases according to the number of sensors to be synchronised. Synchronisation cannot be performed during TEACH-IN and vice versa. The sensors must be operated in an unsynchronised manner to teach the switching point.

#### Note:

If the option for synchronisation is not used, the synchronisation input has to be connected to ground (0V) or the sensor has to be operated via a V1 cable connector (4-pin).

#### Adjusting of switching points

The ultrasonic sensor features a switch output with two teachable switching points. These are set by applying the supply voltage  $-U_B$  or  $+U_B$  to the TEACH-IN input. The supply voltage must be applied to the TEACH-IN input for at least 1 s. LEDs indicate whether the sensor has recognised the target during the TEACH-IN procedure. Switching point A1 is taught with  $-U_B$ , A2 with  $+U_B$ .

#### Five different output functions can be set

- 1. Window mode, normally-open function
- 2. Window mode, normally-closed function
- 3. One switching point, normally-open function
- 4. One switching point, normally-closed function
- 5. Detection of object presence

#### TEACH-IN window mode, normally-open function

- Set target to near switching point
- TEACH-IN switching point A1 with -U<sub>B</sub>
- Set target to far switching point
- TEACH-IN switching point A2 with +U<sub>B</sub>

#### TEACH-IN window mode, normally-closed function

- Set target to near switching point
- TEACH-IN switching point A2 with +U<sub>B</sub>
- Set target to far switching point
- TEACH-IN switching point A1 with -U<sub>B</sub>

## TEACH-IN one switching point, normally-open function

- · Set target to near switching point
- TEACH-IN switching point A2 with +U<sub>B</sub>
- Cover sensor with hand or remove all objects from sensing range
- TEACH-IN switching point A1 with -UB

#### TEACH-IN one switching point, normally-closed function

- Set target to near switching point
- TEACH-IN switching point A1 with -U<sub>B</sub>
- Cover sensor with hand or remove all objects from sensing range
- TEACH-IN switching point A2 with +U<sub>B</sub>

## TEACH-IN detection of object presence

- Cover sensor with hand or remove all objects from sensing range
- TEACH-IN switching point A1 with -U<sub>B</sub>
- TEACH-IN switching point A2 with +U<sub>B</sub>

## Default setting of switching points

A1 = unusable area

A2 = nominal sensing range

#### **LED Displays**

Displays in dependence on operating mode	Red LED	Yellow LED	Green LED
TEACH-IN switching point:			
Object detected	off	flashes	flashes
No object detected	flashes	off	flashes
Object uncertain (TEACH-IN invalid)	on	off	flashes
Normal operation	off	switching	on
		state	
Fault	flashes	previous state	off