

G9SR Safety Relays

OPERATION MANUAL

OMRON

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G9SR Safety Relays: G9SR-BC□-□ G9SR-AD□-□ G9SR-EX□-T90-□

Operation Manual

Revised October 2014

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INTRODUCTION

Thank you for purchasing a G9SR Safety Relay. This manual contains information required to use the G9SR Safety Relay. Please thoroughly read and understand this manual before you use the G9SR Safety Relay.

Intended Audience

This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent).

- Personnel in charge of introducing Factory Automation (FA) and safety systems into production facilities
- Personnel in charge of designing FA and safety systems
- Personnel in charge of managing FA facilities
- Personnel who have the qualifications, authority, and obligation to provide safety during each of the following product phases: mechanical design, installation, operation, maintenance, and disposal



The G9SR system must be installed, configured, and incorporated into a machine control system by a sufficiently trained and qualified person. An unqualified person may not be able to perform these operations properly, which may result in serious injury.



All actions that change the setup, modify the settings of switches or involve testing must be managed. These actions may cause serious injury when applied incorrectly.

Manual Configuration

Information on the operation of G9SR Safety Relays is provided in this manual. There are no related manuals.

Read and Understand this Manual

Please read and understand this manual before using the product. Please consult your OMRON representative if you have any questions or comments.

WARRANTY AND LIMITATIONS OF LIABILITY

WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON.

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LIMITATIONS OF LIABILITY

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In no event shall the responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted.

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APPLICATION CONSIDERATIONS

SUITABILITY FOR USE

OMRON shall not be responsible for conformity with any standards, codes, or regulations that apply to the combination of products in the customer's application or use of the products.

At the customer's request, OMRON will provide applicable third party certification documents identifying ratings and limitations of use that apply to the products. This information by itself is not sufficient for a complete determination of the suitability of the products in combination with the end product, machine, system, or other application or use.

The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products:

- Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this manual.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
- Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

DISCLAIMERS

CHANGE IN SPECIFICATIONS

Product specifications and accessories may be changed at any time based on improvements and other reasons.

It is our practice to change model numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the products may be changed without any notice. When in doubt, special model numbers may be assigned to fix or establish key specifications for your application on your request. Please consult with your OMRON representative at any time to confirm actual specifications of purchased products.

DIMENSIONS AND WEIGHTS

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

PERFORMANCE DATA

Performance data given in this manual is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

ERRORS AND OMISSIONS

The information in this manual has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.

SAFETY PRECAUTIONS

Definition of Precautionary Information

The following notation is used in this manual to provide precautions required to ensure safe usage of a G9SR Safety Relay. The safety precautions that are provided are extremely important to safety. Always read and heed the information provided in all safety precautions. The keywords and their definitions are as given below.



WARNING!

Indicates a potentially hazardous situation which, if not avoided, will result in minor or moderate injury, or may result in serious injury or death. Additionally there may be significant property damage.



Caution!

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or in property damage.



Precautions for Safe Use

Indicates precautions on what to do and what not to do to ensure using the product safely.



Precautions for Correct Use

Indicates precautions on what to do and what not to do to ensure proper operation and performance.

Symbols



The circle and slash symbol indicates operations that you must not do. The specific operation is shown in the circle and explained in text.



The filled circle symbol indicates operations that you must do. The specific operation is shown in the circle and explained in text. This example shows a general precaution for something that you must do.

In order to use the G9SR system safely, the precautions listed in this manual indicated by alert symbols and descriptions must be followed. Failure to follow all precautions and alerts may result in an unsafe use or operation.

The design of a safety control function follows the requirements of:

- the risk assessment acc. EN ISO 12100-1.
 This step defines the measures needed in risk reduction.
- the basic principles of machinery safety acc. EN ISO 13849-1
- the basic principles for electrical safety acc. EN 60204-1

In addition it is required to check the structure of the entire safety system (EN ISO 13849-1), the diagnostic coverage and the robustness against common cause failures. This all is needed to check the calculation of the safety system reliability.

The customer must implement measures to ensure compliance with these standards.

After installation, a comparison between the specified and the installed safety function is mandatory. This final step is verifying the function of the safety system. Make sure that in the final step that all requirements defined based on the risk assessment are met. Detailed information about validation can be found in ISO 13849-2.

Important Safety warnings



Read and understand this section prior to installing a G9SR system.

Whether a specific machine application and G9SR system installation complies with applicable directives and standards depends on the proper application, installation, maintenance and operation of the G9SR system. These items are the responsibility of the purchaser, installer and employer. The employer is responsible for the selection and training of personnel to properly install, operate and maintain the machine and its safeguarding systems. A G9SR system should only be installed verified and maintained by a qualified person. A qualified person is defined as "an individual who understands, is trained on, and demonstrates competence with the construction, operation or maintenance of the machinery and the hazards involved."

To use the G9SR system the following requirements must be met:

- Observe the instructions in this manual regarding test regulations (e.g. on use, mounting, installation or integration into the existing machine control system) carefully.
- Periodic tests must be carried out by specialist personnel or specially qualified and authorized personnel and must be recorded and documented to ensure that the tests can be reconstructed and retraced at any time.
- The operating instructions must be made available to the operator of the machine where the G9SR system is installed.
- The machine operator is to be instructed in the use of the device by specialist personnel and must be instructed to read the operating instructions.
- The guarded machine must have a consistent stopping time and adequate control mechanisms.

This manual refers to FW release 1.0.0 and HW release 1.0 and 2.0.



This is the *Operation Manual* for the G9SR Safety Relays.

Obey the following warnings during system construction to ensure that safety-related components are configured to enable the system functions to sufficiently operate.

Risk Assessment

The proper use of the safety devices described in this manual as they relate to installation conditions and mechanical performance and functions is a prerequisite for its use.

When selecting or using the safety devices, risk assessment must be performed during the development stage of the equipment or facilities to identify potential danger factors in equipment or facilities in which the safety devices are to be applied. Suitable safety devices must be selected under the guidance of a sufficient risk assessment system. An insufficient risk assessment system may result in the selection of unsuitable safety devices.

 Typical related international standards: EN ISO 12100-1, Safety of Machinery --Principles of Risk Assessment

Safety Measures

When using this safety device to build systems containing safety-related components for equipment or facilities, the system must be designed with the full understanding of and conformance to international standards, such as those listed below, and/or standards in related industries.

Typical related international standards: EN ISO 12100-1, Safety of Machinery -Basic Concepts and General Principles for Design EN 61508, Safety Standard for
Safety Instrumented Systems (Functional Safety of Electrical/Electronic/
Programmable Electronic Safety-related Systems)

Role of Safety Devices

The safety devices are provided with safety functions and mechanisms as stipulated in relevant standards, but suitable designs must be used to enable these functions and mechanisms to operate properly inside system constructions containing safety-related components. Build systems that enable these functions and mechanisms to perform properly, based on a full understanding of their operation.

Typical related international standards: ISO 14119, Safety of machinery -Interlocking devices associated with guards -- Principles for design and selection

riangle WARNING

Installation of Safety Devices

The construction and installation of systems with safety-related components for equipment or facilities must be performed by technicians who have received suitable training.

Typical related international standards: EN ISO 12100-1, Safety of Machinery -Basic Concepts and General Principles for Design EN 61508, Safety Standard
for Safety Instrumented Systems (Functional Safety of Electrical/Electronic/
Programmable Electronic Safety-related Systems)

Compliance with Laws and Regulations

This safety device conforms to the relevant regulations and standards, but make sure that it is used in compliance with local regulations and standards for the equipment or facilities in which it is applied.

 Typical related international standards: EN 60204, Safety of Machinery --Electrical Equipment of Machines

Observing Precautions for Use

When putting the selected safety device to actual use, heed the specifications and precautions in this manual and those in the instruction manual that comes with the product. Using a product in a manner that deviates from these specifications and precautions will lead to unexpected failures in equipment or devices, and to damage resulting from such failures, due to insufficient operating functions in safety-related components.

Moving or Transferring Devices or Equipment

When moving or transferring devices or equipment, be sure to include this manual to ensure that the person to whom the device or equipment is being moved or transferred will be able to operate it properly.

Typical related international standards: EN ISO 12100-1, Safety of Machinery -Basic Concepts and General Principles for Design EN 61508, Safety Standard
for Safety Instrumented Systems (Functional Safety of Electrical/Electronic/
Programmable Electronic Safety-related Systems)

- P	
△ WARNING	
Electric shock may occur. Do not touch any terminals while power is being supplied.	0
Serious injury may possibly occur due to loss of required safety functions. Do not use the G9SR Safety Relay's test outputs or standard outputs as safety outputs.	0
Serious injury may possibly occur due to loss of required safety functions. Do not use indicators on the G9SR Safety Relay for safety operations.	
Serious injury may possibly occur due to breakdown of safety outputs or test outputs. Do not connect loads beyond the rated values to the safety outputs and test outputs.	
Serious injury may possibly occur due to loss of required safety functions. Wire the G9SR series Controller properly so that the 24VDC line does NOT touch the outputs accidentally or unintentionally.	
Do not try to disassemble, repair, or modify this product. Doing so may cause the safety functions to stop working properly.	
Do not use the G9SR Safety Relays in environments where flammable or explosive gases are present. Doing so may result in an explosion.	\bigcirc
Do not use the auxiliary output for safety applications.	\bigcirc
Do not connect the 0V line to PE. Serious injury may possibly occur due to loss of required safety functions.	
Serious injury may possibly occur due to loss of required safety functions. Perform user testing and confirm that all of the G9SR Safety Relay's configuration data and operation is correct before starting system operation.	•
Serious injury may possibly occur due to loss of required safety functions. When replacing a G9SR Safety Relay, confirm the model of the Controller is correct and configure the replacement Controller suitably and confirm that it operates correctly.	0
Serious injury may possibly occur due to loss of required safety functions. Use devices and parts related to safety functions according to legal regulations in the applicable country. Use certified items compliant with safety standards corresponding to the intended application.	0
Perform daily and 6-monthly inspections for the G9SR Safety Relays. Otherwise, the system may fail to work properly, resulting in serious injury.	0

△ CAUTION	
Connect the AD201-□ and EX031-□ units to the same power supply.	0
Do not remove a terminal block while the unit is powered ON. It may damage the unit.	
Do not remove the 0V connection while the unit is powered ON. It may damage the unit.	

PRECAUTIONS FOR SAFE USE

Handling

Do not drop the G9SR Safety Relay or subject it to excessive vibration or mechanical shock. The G9SR Safety Relay may be damaged and may not function properly.

Installation and Storage Environment

Do not use or store the G9SR Safety Relay in any of the following locations:

- Locations subject to direct sunlight
- Locations subject to temperatures or humidity outside the range specified in the specifications
- Locations subject to condensation as the result of severe changes in temperature
- Locations subject to corrosive or flammable gases
- Locations subject to dust (especially iron dust) or salts
- · Locations subject to water, oil, or chemicals
- Locations subject to shock or vibration
- The information of section 'Operating Environment' (§2.1 on page 4) is also applicable for storage and transport of G9SR products.

Take appropriate and sufficient measures when installing systems in the following locations. Inappropriate and insufficient measures may result in malfunction.

- Locations subject to static electricity or other forms of noise
- · Locations subject to strong electromagnetic fields
- · Locations subject to possible exposure to radioactivity
- Locations close to power supplies

This is a class A product designed for use in industrial environments. In residential areas it may cause radio interference, in which case the user may be required to take adequate measures to reduce interference

Installation and Mounting

- After unpacking and before installing the G9SR system please check the mechanical
 condition of the system carefully. Do not install a mechanically damaged product.
 Return this to your OMRON service for inspection or repair. Failure to do so may
 result in serious injury.
- Do not drop the products. Dropping the products may lead to internal or external damage. Please return a G9SR system that was dropped on the floor to your OMRON service for inspection or repair. Failure to do so may result in serious injury.
- Make sure to test the operation of the G9SR system after installation to verify that the G9SR system operates as intended. Make sure to stop the machine until the test is completed. Unintended function settings may cause serious injury.
- Configure the system with an interlock function that prevents the machine from being restarted. Failure to do so may result in serious injury.
- Install the interlock switch in a location that provides a clear view of the entire hazardous area and where it cannot be activated from within the hazardous area.

• External indicators (if applicable) must be installed where they are clearly visible to workers from all the operating positions.

- Make sure that the G9SR system is securely mounted and its cables and connectors are properly connected.
- Make sure that foreign objects such as water, oil, or dust do not enter the inside of the G9SR system.
- Perform an inspection for all G9SR systems (as described in section 3 *Test* on page 7) when using series connections, perform inspections for every connected G9SR system.
- Use the G9SR Safety Relay within an enclosure with IP54 protection or higher according to IEC/ EN 60529.
- Use DIN Track (TH35-7.5/TH35-15 according to IEC 60715) to install the G9SR Safety Relay into the control panel.
- Mount the G9SR Safety Relay to the DIN Track using PFP-M End Plates (not included with the G9SR Safety Relay) to prevent it from falling off the DIN Track because of vibration. Correctly mount all Units to the DIN Track.
- Install the G9SR Safety Relay in the vertical direction to ensure adequate cooling. See also § 2.2 *Step 2: Mechanical installation* on page 4.
- Space must be provided around the G9SR Safety Relay, at least 25 mm from its side surfaces and at least 50 mm from its top and bottom surfaces, for ventilation, wiring and Unit replacement.
- Be sure to lock all locking mechanisms, such as those on I/O terminal blocks and connectors, before attempting to use the G9SR Safety Relay.

Turn OFF the power supply before performing any of the following.

- · Connecting or disconnecting Expansion I/O Units, Option Boards, or any other Units
- · Assembling the G9SR Safety Relay
- · Connecting cables or wiring
- Connecting or removing terminal blocks

Installation and Wiring

- Disconnect the G9SR Safety Relay from the power supply before starting wiring. Devices connected to the G9SR Safety Relay may operate unexpectedly.
- Properly apply the specified voltage to the G9SR Safety Relay inputs. Applying an inappropriate DC voltage or any AC voltage may result in a product failure, reduced safety functions, damage to the product.
- Be sure to separate the communications cables and I/O cables from high-voltage/high-current lines.
- Be cautious not to get your fingers caught when attaching terminal blocks to the G9SR Safety Relay.
- Incorrect wiring may lead to loss of safety functions. Wire conductors correctly and verify the operation of the G9SR Safety Relay before using the system in which the G9SR Safety Relay is incorporated.
- Connect no more than the specified number of additional G9SR-BC units and/or G9SR-EX units to a G9SR-AD unit

• Do not short-circuit the output line to the +24V line of the G9SR-BC□-□ because it will set the output to (always) ON.

- Do not connect the 0V of the power supply to Protective Earth (PE).
- Ensure the configuration of the system complies with the required performance level (PLr) of the safety control system that is defined during the risk assessment for the machine according EN ISO 12100-1.
- Do not connect any of the input lines to a DC power supply of more than 24V DC+20%. Do not connect the input lines to an AC source. An AC power supply (>30 VAC) may damage the unit.
- Ensure that the AD201-□ and EX031-□ units are connected to the same power supply.
- Do not use the auxiliary output for safety applications.

Power Supply Selection

Use a DC power supply satisfying the following requirements.

- The secondary circuit of the DC power supply must be isolated from the primary circuit by double insulation or reinforced insulation.
- The output characteristic requirements defined in UL 508 for class 2 circuits or control voltage current circuits are satisfied.
- The output hold time must be 20ms or longer.
- The DC power supply must be an SELV power supply that satisfies the requirements of IEC/EN 60950-1 and EN 50178.
- The power supply must be limited to a maximum current of 8A.

Periodic Inspections and Maintenance

- Disconnect the G9SR Safety Relay from the power supply before replacing the Relay. Devices connected to the G9SR Safety Relay may operate unexpectedly.
- Do not disassemble, repair, or modify the G9SR Safety Relay. Doing so may lead to loss of safety functions.

Disposal

Be cautious not to injure yourself when dismantling the G9SR Safety Relay. This product has been designed to minimize environmental impact. For this reason please note that disposal of irreparable/unserviceable devices has to be in compliance with your local/national rules and regulations.

PRECAUTIONS FOR COMPLIANCE WITH UL STANDARDS AND CSA STANDARDS

Use the following installation information instead of the general information in the instruction manual in order to use the product under certified conditions of UL and CSA when the product is installed in the USA or Canada. These conditions are required by NFPA 70 (National Electrical Code in the USA) and Part 1 of the Canadian Electrical Code in Canada and may vary from information given in the product manuals or safety precautions.

- Surrounding air temperature: 55°C
- The DC power supply must satisfy the requirements for an isolated power supply with external 8 A overcurrent protection.

Ratings

G9SR Safety Relay	Standards	
G9SR-BC	Source:	24V DC, 5A max
	Input:	24V DC, 6mA
	Output:	24V DC/2A max each OSSD
	_	24V DC for AUX max 0.5A
G9SR-AD	Source:	24V DC, 1A max
	Input:	24V DC, 6mA
	Output:	24V DC for AUX only max 0.5A
	Relay output:	see detailed specifications
G9SR-EX	Source:	24V DC, 1A max
	Input:	24V DC, 6mA
	Output:	24V DC for AUX only max 0.5A
	Relay output:	see detailed specifications

REGULATIONS AND STANDARDS

The G9SR Safety Relays conform to the requirements in compliance with the following standards:

Certifying body	Standards
TÜV SUED	• EN ISO 13849-1:2008
	• EN 61508 parts 1-4:2010
	• IEC/EN 62061/A1 2013
	• IEC 61496-1/A1 2008 Type 4
Others	CE Marking
	CSA Marking

The G9SR Safety Relays are applicable in applications up to Performance level e. The hardware is designed according to the requirements for a category 4 system. Do not use the G9SR Safety Relays in situations where the risk assessment requires higher values than mentioned in the following table:

Pl	e	EN ISO 13849-1:2008
Cat.	4	EN ISO 13849-1:2008
Туре	4	IEC 61496-1: ed 2 2004
PFHd G9SR-BC	5.7*10 ⁻⁹	EN ISO 13849-1:2008
PFHd G9SR-AD	5.7*10 ⁻⁹	EN ISO 13849-1:2008
PFHd G9SR-EX	3.1*10-9	EN ISO 13849-1:2008
MTTFD G9SR-BC	351 Year	EN ISO 13849-1:2008
MTTFD G9SR-AD	379 Years	EN ISO 13849-1:2008
MTTFD G9SR-EX	1120 Years	EN ISO 13849-1:2008
DCavg	97%	EN ISO 13849-1:2008
SIL	3	EN 61508:2010
Proof test interval:	20yr	IEC 62061: 2005
MTTR	8h	EN61508-1:2008
Туре	Type B	EN61508:2010
HFT	1	EN61508:2010

Using a G9SR Safety Relay enables building a safety control system that satisfies the following:

- Requirements for SIL 3 (Safety Integrity Level 3) in EN 61508, IEC/EN 62061, Safety Standard for Safety Instrumented Systems (Functional Safety of Electrical/ Electronic/Programmable Electronic Safety-related Systems)
- Requirements for PLe (Performance Level e) and for safety category 4 in EN ISO13849-1

COMPLIANCE WITH EC DIRECTIVES

APPLICABLE DIRECTIVES

The national/international rules and regulations apply to the installation, use and periodical technical inspections of the safety system, in particular:

- Machinery Directive (2006/42/EC)
- EMC Directive (2004/108/EC)

Concepts

EMC Directive

OMRON electrical devices are built into other components or equipment. OMRON therefore pursues compliance with the related EMC standards so that they can be more easily built into other devices or the equipment.*

OMRON cannot confirm compliance in the customer's actual application; however, because the customer may use a variety of components and equipment, and EMC performance depends on the configuration, wiring, and arrangement of the equipment and control panel into which a product applicable to EC Directives is incorporated. Therefore, whether the products conform to the standards in the system used by the customer, they must be checked by the customer.

* Applicable EMC (Electromagnetic Compatibility) standards are as follows: EN 61000-6-2 for EMS (Electromagnetic Susceptibility) and EN 61000-6-4 for Electromagnetic Interference (10-m regulations applied for EN 61000-6-4 radiated emission).

Conformance to EC Directives

The G9SR Safety Relays complies with EC Directives. To ensure that the machine or device in which the G9SR Safety Relay is used complies with EC Directives, the following requirements must be met.

- Make sure that the DC power supply connected to a DC Power Supply Unit or I/O Unit satisfies the following conditions.
 - There is double insulation or reinforced insulation between the primary circuit and secondary circuit.
 - An isolated power supply that is limited to a current of 8 A or lower must be used.
 - The output hold time is 20ms min.
 - The power supply is a SELV power supply that satisfies requirements in IEC/ EN 60950-1 and EN 50178.
 - Provide external measures to ensure appropriate overvoltage protection to a maximum of 30V DC.
- G9SR-series products that comply with the EC Directives also comply with the Generic Emission Standard (EN 61000-6-4) for EMI. The radiated emission characteristics (10-m regulations), however, may depend on the configuration of the control panel that is used and the relation to and wiring with other connected devices. Even through the G9SR Safety Relay complies with EC Directives; the customer must confirm that the overall machinery and equipment in which the G9SR Safety Relay is used complies with the EC Directives.

The customer must implement measures to ensure compliance with these standards.

CE conformity declaration available at: http://industrial.omron.eu

Machinery Directive

The Machinery Directive requires ensuring the required safety for safety components used for machinery safety.

Applicable standards: EN ISO 13849-1:2008 and IEC/EN 62061 SIL CL3

GLOSSARY, DEFINITIONS, ABBREVIATIONS

Aux.: Auxiliary. E.g. Auxiliary Outputs

Dynamic Input testing:

Test if the separate input channels are connected (shorted).

Applicable to G9SR-BC \square - \square and G9SR-AD \square - \square

EDM: External Device Monitoring;

Active checking of the correct behavior of external connected units

like safety relays.

ESPE: Electro Sensitive Protective Equipment

Assemblies of · a sensing device

· controlling/monitoring devices

· Output Signal Switching Device (OSSD)

FA: Factory Automation

G9SR-BC□-□: A Basic unit (BC) of the G9SR series.

G9SR-AD□-□: An Advanced unit (AD) of the G9SR series.

G9SR-EX□-**T90-**□: An Extension unit (EX) of the G9SR series.

Input: Signal going into the unit. Input signals can come from e.g. safety

sensors, E-stop switches or SLCs.

Lock out State: A forced OFF state, the OSSDs are OFF. This state can be reached

when an error occurs in the complete system.

Power cycle the unit to exit this State.

MPU: Micro Processing Unit.

NO / NC: Normally Opened / Normally Closed

The contact situation of switching devices (switches, relays,...)

when not powered/activated.

OSSD: Output Signal Switching Device.

OSSD can be safety relays with mechanical contacts or solid state

outputs such as PNP-transistors.

PFHd: Probability Failures per Hour that are **D**angerous

PL: Performance Level as defined in ISO 13849-1

RESTART: A sequence of the total system to come from a non-powered

situation to an operational situation. In an operational situation OSSDs can be activated (ON) when a valid input signal is received.

Safe State: A forced OFF state, the OSSDs are OFF.

SLC: Safety Light Curtain.

1 Product family – General information

1.1 Intended use

The G9SR units are intended for the functions listed in the table below:

	G9SR-BC	G9SR-AD	G9SR-EX
E-Stop function	Yes	Yes	No
Door monitoring (safety limit switches)	Yes	Yes	No
Door monitoring (key operated switches)	Yes	Yes	No
Door monitoring (non-contact switches)	Yes	Yes	No
ESPE monitoring	Yes	Yes	No
Additional safety outputs	No	No	Yes

Note on the G9SR-EX unit:

The extra outputs realised with the G9SR-EX units have an ON-delay timer and an OFF-delay timer for additional control of your outputs.

1.2 Family Overview

The product family G9SR consists of a G9SR-BC \square - \square (BC = Basic), a G9SR-AD \square - \square (AD = Advanced) and a G9SR-EX \square -T90- \square unit (EX = Extension) to give you flexibility when configuring your specific system.

1.2.1 G9SR-BC

The G9SR-BC has a double channel safety input that can be used in E-Stop, door monitoring applications or applications with opto-electronic safety sensors.

The G9SR-BC has solid state safety outputs for DC loads of up to 2A and with a peak current up to 5A.

The G9SR-BC can operate standalone or as an additional input with a G9SR-AD.

See also:

Chapter 6 G9SR unit: $G9SR-BC\Box - \Box$ on page 19.



1.2.2 G9SR-AD

The G9SR-AD has a double channel safety input that can be used in E-Stop, door monitoring applications or applications with opto-electronic safety sensors.

The G9SR-AD has safety relay outputs for

Max. 4A AC1 @ 250V *

Max. 5A AC15 @ 250V

Max. 4A DC1 @ 30V *

Max. 5A DC13 @ 30V

* See also § 4.2 Derating curve.

For more details see also:

Chapter 4 Technical specifications on page 10.

The G9SR-AD can operate standalone or in a system with

- up to two additional G9SR-BC as input expansion
- up to three G9SR-EX as additional safety relay outputs.

See also:

Chapter 7 G9SR unit: $G9SR-AD\Box - \Box$ on page 26.

1.2.3 G9SR-EX

The G9SR-EX operates as an output extension to a G9SR-AD.

The G9SR-EX has safety relay outputs for

Max. 4A AC1 @ 250V *

Max. 5A AC15 @ 250V

Max. 4A DC1 @ 30V *

Max. 5A DC13 @ 30V

* See also § 4.2 Derating curve.

For more details see also:

Chapter 4 Technical specifications on page 10.

The output signals of the G9SR-EX□-T90-□ unit can be switched with 16 timing presets for an ON-delay and 16 timing pre-sets for an OFF-delay.

See also:

Chapter 8 *G9SR unit:* $G9SR-EX\Box-T90-\Box$ on page 33.





1.3 Mechanical dimensions

Unit	G9SR-BC□-□	G9SR-AD□-□	G9SR-EX□-□-□
Height	114,5 mm	114,5 mm	114,5 mm
Thickness	17,6 mm	22,5 mm	22,5 mm
Width without	99,0 mm	99,0 mm	99,0 mm
terminal blocks			
Width with spring	117,0 mm	117,0 mm	117,0 mm
type terminal blocks			
Width with	107,0 mm	107,0 mm	107,0 mm
screw type terminal			
blocks			

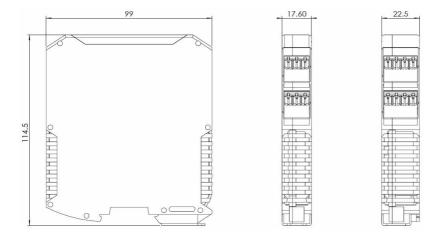


Figure 1 – Unit dimensions excluding connectors [mm]

2 Installation and configuration

To install G9SR units:

2.1 Step 1: Installation environment

Disconnect all electrical power sources before installing and connecting a G9SR unit.

Ensure the environment is with the specifications as mentioned in Chapter 4 *Technical specifications* on page 10.

See also:

- § Precautions for Safe Use
 - Installation and Mounting on page 18

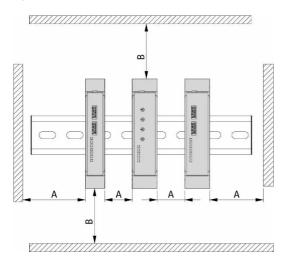
2.2 Step 2: Mechanical installation

The installation should be carried out by qualified personnel only.

Mount each G9SR unit on a DIN-rail in a vertical position as shown in the figure below. All other mounting directions might cause heating problems.

To apply rated current outputs of G9SR and for enough ventilation and wiring space, allow following free space around the G9SR unit:

- A) At least 25 mm at the left and at the right side of each G9SR.
- B) At least 50 mm above each G9SR and below each G9SR.



The fixing clip of the housing must be in the locked position.

2.3 Step 3: Electrical installation

The electrical installation should be carried out by qualified personnel only.

Electrical installation requirements and configurations are the outcome of the machinery risk assessment.



WARNING

Remove the power from your system before installing a G9SR



Caution!

Prevent wire clippings from entering the unit.

See also:

§ Precautions for Safe Use

- *Installation and Wiring* on page 19
- Power Supply Selection on page 20

Chapter 4 Technical specifications on page 10 for wiring details.

Chapter 11 Appendix A: Wiring examples on page 52

- § 10.1 Input loop on page 49
- § 10.2 Output loop on page 50
- § 10.3 Input loop and Output loop on page 51

2.3.1 Install fuses for G9SR units

G9SR units require external protection of the power supply lines. If several G9SR units are installed, each of the individual G9SR modules requires a separate fuse.



Caution

Install a fuse for each G9SR units.

for each G9SR-AD□-□ a
 for each G9SR-BC□-□ a
 for each G9SR-EX□-T90-□ a
 1A Fast fuse
 1A Fast fuse

2.3.2 Install fuses for output relays

Include a 5A Fast fuse for each power supply line to the output relays.

2.3.3 Install Power Supply

Add the power supply for the units and for the installed outputs.



Caution! Connect the AD201-□ and EX031-□ units to the same power supply.

2.3.4 **G9SR-BC** \square - \square solid state output



Caution! In accordance with EN-61131-2 G9SR-BC□-□ outputs are not compatible with type 1 inputs.



Caution! In accordance with EN-61131-2 G9SR-BC□-□ outputs are compatible with type 2 and type 3 outputs with an external load < 1 Kohm.

2.4 Step 4: Configure the G9SR units

The switches on the units are used to set the function of the safety control system.

Set the switches to achieve the desired behaviour of your system.

See also:

- § 6.3 Dip switches and functions of G9SR-BC \square - \square on page 20.
- § 7.3 Dip switches and functions of G9SR-AD \square - \square on page 27.
- § 8.3 Rotary switch functions of G9SR-EX \square -T90- \square on page 34.

2.5 Step 5: Test the installation

Check all functions of the installed system.

See also:

Section 3 Test on page 7

Document the test results using the test log.

See also:

Chapter 12 Appendix B: Logging of test results on page 77

3 Test

Perform the tests always:

- after installation
- after every system maintenance action
- after a change in settings (dip switches or rotary switches)
- periodically according to the local requirements (local standards and/or safety rules)



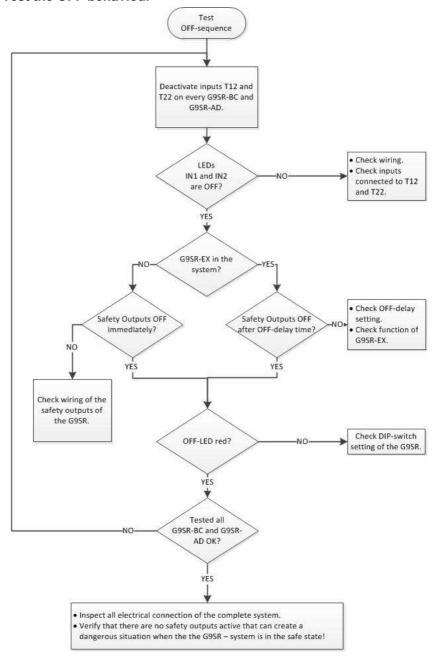
Incorrect testing can cause potentially hazardous situations which, if not avoided, could result in death or serious injury. Additionally, there may be severe property damage.

Test procedure:

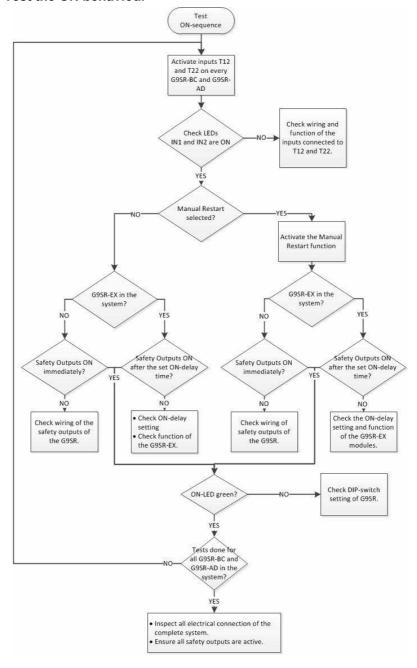
Test the OFF behaviour. See § 3.1 on page 8
 Test the ON behaviour. See § 3.2 on page 9

3. Log the test results. See *Appendix B: Logging of test results* on page 77

3.1 Test the OFF behaviour



3.2 Test the ON behaviour



4 Technical specifications

4.1 General specifications

Item	Value
Mounting	DIN rail
Housing Material & Connectors	Plastic (grey)
	Dimensions, see page 3
Connectors	Removable cage clamp terminals
Operating temperature range	-10° C to $+55^{\circ}$ C
Storage temperature range	-25°C to + 70°C
Humidity	0 to 95% RH. No icing or condensation
Enclosure rating (EN 60529)	IP20 (mount in a IP54 cabinet or higher
	according to IEC/ EN 60529)
Resistance to	
Vibration (to IEC 68-2-6)	0,375mm 10 to 70 Hz
Shock (to IEC 68-2-27)	30G 18ms
Operating voltage	24V DC ± 20%
Current consumption	<0.15A
excluding auxiliary output	
Minimum EDM and RESTART	6mA
input current	
Minimum EDM and RESTART	19V DC
voltage for an ON signal	
Minimum voltage for T12 and	17V DC
T22 for an ON signal	
Minimum input current for T12	6mA
and T22	11V DC
Maximum T12, T22, EDM and RESTART voltage for an OFF	ITV DC
signal	
Power-ON delay	< 2 sec.
Outputs static	2A continuous for OSSD
outputs state	0.5A for Auxiliary output
G9SR-BC Output voltage High	Unit supply voltage -1V
G9SR-BC Output voltage Low	0V
,	Max. 4A AC1*
Output relay on -AD and -EX	Max. 5A AC15
•	Max. 4A DC1*
	Max. 5A DC13
	*See also § 4.2 Derating curve.

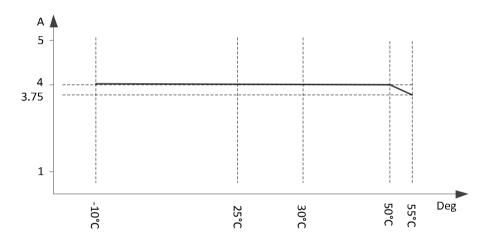
Item	Value
Output relay circuit protection	No internal protection
	External fuse (5A) required.
Relay life time	Electrical @ maximum allowed load: 100.000
	cycles. Mechanical: 10.000.000 cycles.
Unit power supply circuit	External fuses: $G9SR-AD\Box-\Box=1AF$,
protection	G9SR-EX \square -T90- \square = 1A F, G9SR-BC \square - \square = 5A F
Input circuit protection	Over voltage protection.
input en cuit protection	Short circuit creates an error situation.
	Incorrect polarity creates an error situation.
Input test pulse duration	1ms
Response timing:	11115
Stand-alone G9SR-BC	< 54ms
Stand-alone G9SR-AD Stand-alone G9SR-AD	< 52ms
Stand-alone Gysk-ADU-U	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
1 G9SR-BC□-□ & G9SR-AD□-□	< 214ms for system
2 G9SR-BC & G9SR-AD	< 214ms for system < 294ms for system
2 U95K-DC□-□ & U95K-ADŪ-□	~ 254IIIS IOI SYSICIII
COCD AD % 1 COCD EV	< 58ms
G9SR-AD□-□ & 1 G9SR-EX□-□-□ G9SR-AD□-□ & 2 G9SR-EX□-□-□	< 61ms
	< 64ms
G9SR-AD□-□ & 3 G9SR-EX□-□-□	< 64ms
1 BC & AD & 1 EX	< 218ms
2 BC & AD & 1 EX	
	< 298ms
1 BC & AD & 2 EX	< 222ms
2 BC & AD & 2 EX	< 302ms
1 BC & AD & 3 EX	< 225ms
2 BC & AD & 3 EX	< 306ms
Restart time (OFF→ON)	< 150ms
Insulation resistance	> 20MOhm
Dielectric voltage strength	2500V AC, 50/60 Hz for 1 minute
Operating modes	Automatic/manual restart, EDM, Input Loop
	chain and Output Loop chain.
Maximum cabling length	Maximum length < 100m
for safety inputs	and total cable impedance < 250Ohm
Maximum capacitance for BC	330nF
model OSSD	
Maximum peak current BC model	5A
OSSD	
Cable terminal requirements:	
• 3 poles connector:	0,2mm ² to 2.5mm ² (AWG 24 to AWG 12)
• 4 poles connector:	0,2mm ² to 2.5mm ² (AWG 24 to AWG 12)
• 5 poles connector:	0,2mm ² to 1,5mm ² (AWG 24 to AWG 16)
Cable types allowed:	Stranded, Fixed, Ferrules.
Cubic types anomea.	

Item	Value
Power supply requirement	Double insulation acc. EN 60950

4.2 Derating curve of relay contact current

The temperature of the modules is influenced by Load Current [A] and the distance [25 mm] between units.

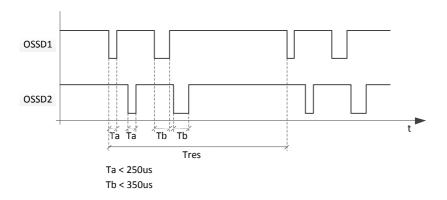
Use the derating curve to determine the maximum allowed relay contact current for the actual operating temperature of the unit. This applies to each single relay contact.



Note:

The graph is valid for an environment temperature of 21 °C and with each contact driving the same current at the same time.

Test pattern for OSSD Testing

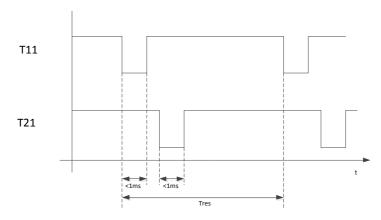


Ta = OSSD1 test pulse1 with a duration of <250 micro second Tb = OSSD1 test pulse2 with a duration of <350 micro second

Tres = Cycle time of the complete G9SR unit

4.3 Test pattern for Dynamic Input testing

Test pattern with an input channel test pulse of 1 $\,\mathrm{ms}.$



Tres = Cycle time of the complete G9SR unit

5 Restart modes

There are two possible restart modes:

Manual Restart
 See § 5.1 on page 14
 Automatic Restart
 See § 5.3 on page 17

5.1 Manual Restart

If *Manual restart* is selected and there is an intervention then the system will not restart automatically. To restart the system, activate the restart signal manually.

Operating modes for Manual Restart input

The wiring of the G9SR Restart input is depending on the DIP-switch setting.

1) DIP-switch 2 = "ON"

The G9SR monitors to detect unexpected signals between all terminals and/or power supply for full diagnosis and error detection.

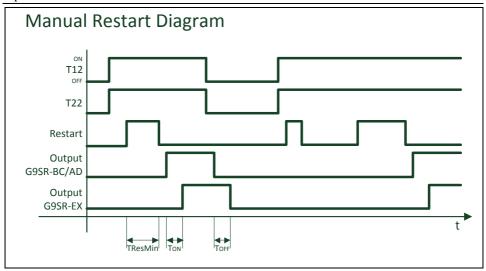
- The source for the Restart input T31 is the terminal T11.
- The Restart function will not be enabled if the source for T31 is any other terminal than T11.

1) DIP-switch 2 = "OFF"

The G9SR is not monitoring unexpected signals to power supply or other terminals of the unit.

• The source for the Restart input T31 is +24VDC.

See also: Chapter 11 Appendix A: Wiring examples on page 52



TOn = On-delay time set on the G9SR-EX
TOff = OFF-delay time set on the G9SR-EX
TResMin = Minimum Restart input pulse 300ms

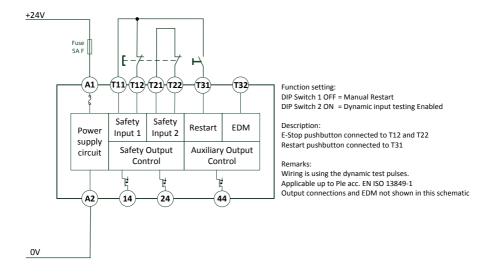


Make sure that the source of the restart signal is complementing the requirements for the safety control system. Improper use of the restart input may lead to a dangerous situation due to unintended restart of the machine

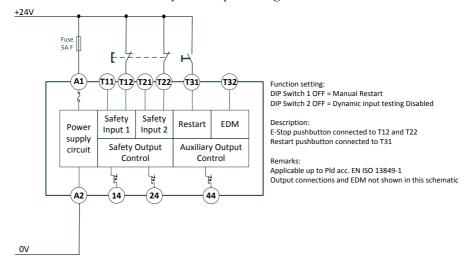
5.2 Wiring examples Manual Restart

Wiring of the Restart function is similar for the G9SR-BC and the G9SR-AD units. Two wiring examples for Manual Restart:

5.2.1 Manual Restart with dynamic input testing

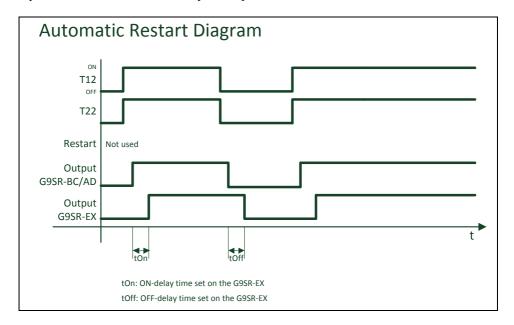


5.2.2 Manual Restart without dynamic input testing



5.3 Automatic Restart

If automatic restart is selected, the safety outputs will be activated as soon as the safety inputs are active and the ON-delay has expired.



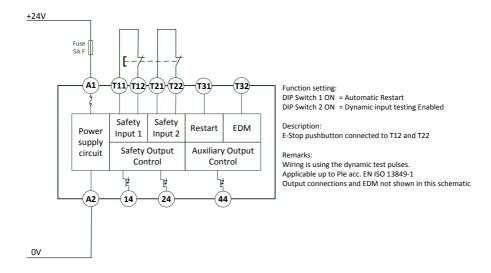


The Automatic Restart option shall only be used when it is guaranteed that activation of the OSSDs cannot create a dangerous situation. Do not use this option in any other case.

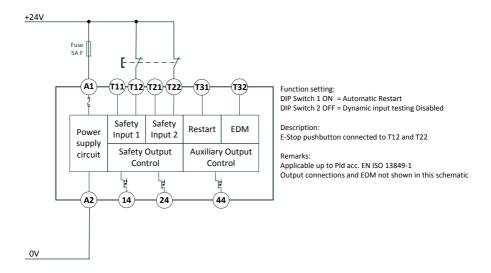
5.4 Wiring examples Automatic Restart

Wiring of the Restart function is similar for the G9SR-BC and the G9SR-AD units. Two wiring examples for Automatic Restart:

5.4.1 Automatic Restart with dynamic input testing



5.4.2 Automatic Restart without dynamic input testing



6 G9SR unit: G9SR-BC□-□

6.1 Introduction

The G9SR-BC□-□ unit can handle one double-channel input device and 2 output signals. The outputs have to be DC loads with a maximum of 2A switching current each.

This unit can be used stand-alone or as an additional Input unit for the $G9SR-AD\Box -\Box$.

See also § 10.1 Input loop on page 49



6.2 Internal connections of G9SR-BC□-□

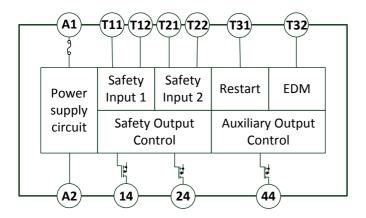


Figure 2 - Internal connections of G9SR-BC \square - \square

6.3 Dip switches and functions of G9SR-BC□-□

The DIP-Switches are used to configure the G9SR-BC unit for the application.

There are two banks of DIP-switches in the G9SR-BC. Both DIP-switch banks have eight switches. To select a function, the switches on both DIP-switch banks have to be set identically.

Example:

DIP SWITCH 3, BANK1 = "OFF"

and

DIP SWITCH 3, BANK2 = "OFF" => OK

DIP SWITCH 3, BANK1 = "OFF"

and

DIP SWITCH 3, BANK2 = "ON" => ERROR



Do not change the setting of the DIP switches during operation of the G9SR-BC. In this case, the G9SR-BC will change the outputs to "OFF" and will enter a lockout state.

Use the switches to configure following functions:

Function	Switch	G9SR-BC□-□
Restart	1	ON = Auto Restart
		OFF = Manual Restart
Dynamic Input Testing	2	ON = Enabled
		OFF = Disabled
EDM	3	ON = Enabled
		OFF = Disabled
INPUT LOOP	4	ON = input loop enabled.
		This disables the OSSDs and Aux out.
		OFF = input loop disabled
AUX OUT STATUS	5	ON = Aux out status consistent with OSSD
		OFF = Aux out status inverted.
	6/7/8	Reserved

6.4 LEDs of the G9SR-BC□-□

LEDs show the unit status and indicate errors.

An LED can be OFF shown as

ON shown as

FLASHING shown as

Not applicable shown as



6.4.1 POWER LED = POWER

Color: Green

ON when power supply is correctly applied to the unit.

OFF when no power is supplied IN1 LED = Input 1

Color: Yellow

ON when T12 receives a valid input signal.

OFF when no valid input signal is received at T12.

6.4.2 IN2 LED = Input 2

Color: Yellow

ON when T22 receives a valid input signal.

OFF when no valid input signal is received at T22.

6.4.3 RESTART LED = Restart

Color: Yellow

ON when the Restart pushbutton is activated.

FLASH when an error occurs.

Fast blinking & ERR fast blinking = Communication error of another unit Slow blinking & ERR slow blinking = Communication error of this unit See also § 6.5.2*Error situations - LEDs G9SR-BC*□-□ on page 24

OFF when restart action is not required / not allowed.

6.4.4 EDM LED = External Device Monitoring

Color: Yellow

ON when EDM function is enabled.

FLASH when any error on External Device Monitoring occurs. See also § 6.5.2 Error situations - LEDs G9SR-BC□-□ on page 24

OFF EDM function is disabled.

6.4.5 ON LED = Outputs

Color: Green

ON when the outputs are activated = ON.

FLASH fast (3 per second) when input-loop chain is OK.

OFF when the outputs are de-activated = OFF.

6.4.6 OFF/ERR LED = OFF & Error

Color: Red

ON when OSSDs are OFF

FLASH when an error occurs (EDM and Restart leds provide error code).

Fast blinking & RES or COM fast blinking

= Communication error of another unit

Slow blinking = OSSD error.

Slow blinking & RES or COM slow blinking

= Communication error of this unit.

See also § 6.5.2 *Error situations - LEDs G9SR-BC* \square - \square on page 24.

OFF when all internal diagnostics are successfully passed and OSSDs are activated = ON.

6.5 LED examples G9SR-BC□-□

6.5.1 Normal operation - LEDs G9SR-BC \square - \square

		LEI) signa					
ID	OFF/ERR	NO	ЕДМ	RESTART	IN2	INI	POWER	Description
1.		#	\		#	#	#	T12 ON, T22 ON. EDM enabled. Output active.
2.	#			\	#	#	\	Waiting for restart. EDM disabled. Output not active.
3.	#		#				\	T12 OFF, T22 OFF. EDM enabled. Output not active.
4.		#	<u> </u>	<u> </u>	#	#	尸	T12 ON, T22 ON. EDM disabled. Input loop function activated, module running OK. 1)
5.		#	0	0	0	0	尸	T12 OFF, T22 OFF. EDM disabled. Input loop function activated, module running OK. 1)
6.	\mathbf{x}			$\overline{+}$	\otimes	\otimes		Restart LED blinks slow, waiting for Input loop.

¹⁾ The ON green led flashes quickly to indicate the input loop function is enabled and operates correctly.

6.5.2 Error situations - LEDs G9SR-BC□-□

		LE	D sign					
II)	OFF/ERR	NO	ЕDМ	RESTART	IN2	INI	POWER	Description
1.	$\widetilde{\mathbb{H}}$				\otimes	\otimes		Error on EDM input
2.	#			#	\otimes	\otimes		Error during cyclic test. Error because other module is connected when G9SR-BC is configured with input loop.
3.	$\widetilde{\mathbb{H}}$			$\not\equiv$	\otimes	\otimes		DIP switch settings incorrect.
4.	$\not\parallel$				\otimes	\otimes		Error on solid state safety outputs (overload).
5.	#	#		#	0	<u> </u>	#	ERR and RES fast blinking (3 per sec.) = communication error of another unit ERR and RES slow blinking (1 per sec.) = communication error of this unit

6.6 Terminal and signal names G9SR-BC□-□

- T12 Input Channel 1
- 44 Output Auxiliary (Status)
- A1 Power Supply
- T31 Restart Input
- T11 Test Signal 1
- A2 Power Supply GND
- T32 EDM Input
 - or Input Loop IN (depending on dip switches)
- T21 Test Signal 2
- 14 Output 1 OSSD1 or Input Loop OUT (depending on dip switches)
- 24 Output 2 OSSD2
- T22 Input Channel 2

See also:

§ 11.1 Wiring examples $G9SR-BC \square - \square$ unit on page 52.



7 G9SR unit: G9SR-AD□-□

7.1 Introduction

The G9SR-AD□-□ unit can handle one double-channel input device and 2 output signals.

The outputs are switched with relays designed for 250V AC with

switching currents: Max. 4A AC1*

Max. 5A AC15

Max. 4A DC1*

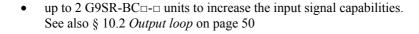
Max. 5A DC13

* See also § 4.2 *Derating curve*.

This unit can be expanded with:

• up to 3 G9SR-EX□-□-□ units to increase the output signal capabilities.

See also § 10.1 Input loop on page 49



7.2 Internal connections of G9SR-AD□-□

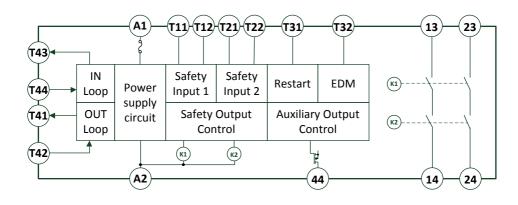


Figure 3 - Internal connections of G9SR-AD□-□



Dip switches and functions of G9SR-AD --7.3

The DIP-Switches are used to configure the G9SR-AD unit for the application.

There are two banks of DIP-switches in the G9SR-AD. Both DIP-switch banks have eight switches. To select a function, the switches on both DIP-switch banks have to be set identically.

Example:

DIP SWITCH 3, BANK1 = "OFF"

DIP SWITCH 3, BANK2 = "OFF" => OK

DIP SWITCH 3, BANK1 = "OFF" and

DIP SWITCH 3, BANK2 = "ON" => ERROR



BANK



Do not change the setting of the DIP switches during operation of the G9SR-AD. In this case, the G9SR-AD will change the outputs to "OFF" and will enter a lockout state

Use the switches to configure following functions:

Function	Switch	G9SR-AD□-□
Restart	1	ON = Auto restart
		OFF = Manual restart
Dynamic Input Testing	2	ON = Enabled
		OFF = Disabled
EDM	3	ON = Enabled
		OFF = Disabled
INPUT LOOP	4/5	OFF/OFF = No G9SR-BC□-□ connected
		OFF/ON = Setting not allowed
		$ON/OFF = 1 G9SR-BC_{\square}-\square connected$
		$ON/ON = 2 G9SR-BC_{\square}-\square$ connected
OUTPUT LOOP	6/7	OFF/OFF = No G9SR-EX□-T90-□ connected
		$OFF/ON = 1 G9SR-EX_{\square}-T90{\square} connected$
		$ON/OFF = 2 G9SR-EX_{\square}-T90{\square} connected$
		$ON/ON = 3 G9SR-EX_{\square}-T90{\square} connected$
	8	Reserved

7.4 LEDs of the G9SR-AD□-□

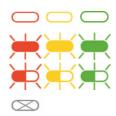
LEDs show the unit status and indicate errors.

An LED can be OFF shown as

ON shown as

FLASHING shown as

Not applicable shown as



 $7.4.1 \quad POWER\ LED = Power$

Color: Green

ON when power supply is correctly applied to the unit.

OFF when no power is supplied.

7.4.2 IN1 LED = Input 1

Color: Yellow

ON when T12 receives a valid input signal.

OFF when no valid input signal is received at T12.

7.4.3 IN2 LED = Input 2

Color: Yellow

ON when T22 receives a valid input signal.

OFF when no valid input signal is received at T22.

7.4.4 RESTART LED = Restart

Color: Yellow

ON when Restart input activated.

FLASH when any error occurs.

Fast blinking & ERR fast blinking = Communication error of another unit Slow blinking & ERR slow blinking = Communication error of this unit See also § 7.5.2 *Error situations - LEDs G9SR-AD* \Box - \Box on page 31.

OFF when restart action is not required / not allowed.

7.4.5 EDM LED = External Device Monitoring

Color: Yellow

ON when EDM function is enabled.

FLASH when any error on External Device Monitoring occurs.

OFF EDM function is disabled.

7.4.6 ON LED = Outputs

Color: Green

ON when the outputs are ON.

OFF when the outputs are OFF.

7.4.7 $OFF/ERR\ LED = Error$

Color: Red

ON when OSSDs are OFF

System startup internal testing failed

FLASH when an error occurs (EDM and Restart leds provide error code).

Fast blinking & RES or COM fast blinking

= Communication error of another unit

Slow blinking & RES or COM slow blinking

= Communication error of this unit

See also § 7.5.2 Error situations - LEDs G9SR-AD \square - \square on page 31.

OFF when all internal diagnostics are successfully passed and OSSDs are ON.

7.5 LED Examples G9SR-AD --

7.5.1 Normal operation - LEDs G9SR-AD \square - \square

		LEI) signa					
II)	OFF/ERR	ON	EDM	RESTART	IN2	INI	POWER	Description
1.		#		0	#	#	/ \	T12 ON, T22 ON. EDM disabled. Output active.
2.		#	#	0	#	#		T12 ON, T22 ON. EDM enabled. Output active.
3.	\mathbf{H}			#	#	#		T12 ON, T22 ON. EDM disabled. Waiting for restart.
4.	#		#	0	0		Λ I 2	T12 OFF, T22 OFF. EDM enabled. Outputs not active.
5.				<u> </u>				T12 OFF, T22 OFF. EDM disabled. Outputs not active.

7.5.2 Error situations - LEDs G9SR-AD□-□

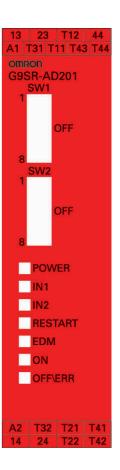
		LEI) signa					
II)	OFF/ERR	NO	ЕDМ	RESTART	IN2	INI	POWER	Description
1.	$\widetilde{\mathbb{H}}$		$\not \equiv$		\otimes	\otimes	黨	Error on EDM input
2.	$\widetilde{\mathbb{H}}$			$\not\equiv$	\otimes	\otimes	$\not =$	Error during cyclic test
3.	$\widetilde{\mathbb{H}}$		$\not\equiv$	$\not \equiv$	\otimes	\otimes	¥	DIP switch settings incorrect.
4.	#	0		#	\otimes	\otimes	#	ERR and RES fast blinking (3 per sec.) = communication error of another unit ERR and RES slow blinking (1 per sec.) = communication error of this unit

7.6 Terminal and signal names of the G9SR-AD□-□ unit

- 13 Relay Output 1.1 (NO)
- 23 Relay Output 2.1 (NO)
- T12 Input Channel 1
- 44 Output Auxiliary (Status)
- A1 Power Supply
- T31 Restart Input
- T11 Test Signal 1
- T43 Input loop IN
- T44 Input loop OUT
- A2 Power Supply GND
- T32 EDM input
- T21 Test Signal 2
- T41 Output loop OUT
- 14 Relay Output 1.2 (NO)
- 24 Relay Output 2.2 (NO)
- T22 Input Channel 2
- T42 Output loop IN

See also:

§ 11.2 Wiring examples $G9SR-AD\Box -\Box$ unit on page 62.



8 G9SR unit: G9SR-EX₋T90-

8.1 Introduction

The G9SR-EX \square -T90- \square unit can be connected to the G9SR-AD \square - \square unit as an Output extension unit.

The outputs are switched with relays designed for 250V AC with

switching currents: Max. 4A AC1*

Max. 5A AC15 Max. 4A DC1* Max. 5A DC13



The output signals of the G9SR-EX \square -T90- \square unit can be switched with 16 timing presets for an ON-delay and 16 timing pre-sets for an OFF-delay.

See also § 10.2 Output loop on page 50

8.2 Internal connections of G9SR-EX - T90-

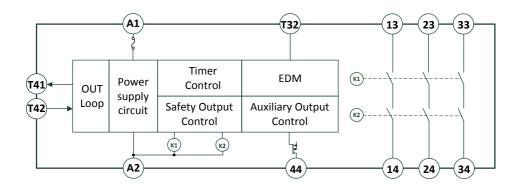


Figure 4 - Internal connections of G9SR-EX□-T90-□

^{*} See also § 4.2 Derating curve.

8.3 Rotary switch functions of G9SR-EX□-T90-□

The rotary switches are used to configure the G9SR-EX for the application. The OFF- and ON-delay time can be set independently.











Do not change the setting of the switches during operation of the G9SR-EX. In this case, the G9SR-EX will change the outputs to "OFF" and will enter a lockout state.

There are four rotary switches in the G9SR-EX to configure the ON- and OFF-delay time setting. Switch 1 and 3 define the ON-delay time setting. Switch 2 and 4 define the OFF-delay time setting.

The rotary switch settings represent following time delays:

0	1	2	3	4	5	6	7
0s	0.1s	0.2s	0.5s	1s	1.5s	2s	2.5s

8	9	A	В	С	D	Е	F
5s	10s	20s	30s	45s	60s	75s	90s

8.3.1 *ON-delay*

To select an ON-delay time, use switch 1 and switch 3. They have to be set identically for a valid ON-delay time setting.

8.3.2 OFF-delay

To select an OFF-delay time, use switch 2 and switch 4. They have to be set identically for a valid OFF-delay time setting.

8.4 LEDs of the G9SR-EX□-T90-□

LEDs show the unit status and indicate errors.

An LED can be OFF shown as

ON shown as

FLASHING shown as

Not applicable shown as



8.4.1 $POWER\ LED = Power$

Color: Green

ON when power supply is correctly applied to the unit.

OFF when no power is supplied.

8.4.2 COM LED = Input

Color: Yellow

ON when the communication line sends or receives a valid signal.

FLASH when an ONdelay or OFFdelay is in progress.

Fast blinking & ERR fast blinking = Communication error of another unit Slow blinking & ERR slow blinking = Communication error of this unit

OFF when no valid input signal is received on T42.

8.4.3 EDM LED = External Device Monitoring

Color: Yellow

ON when EDM function is enabled.

FLASH when any error on External Device Monitoring occurs.

OFF EDM function is disabled.

8.4.4 *ON LED* = *Outputs*

Color: Green

ON when the outputs are ON.

OFF when the outputs are OFF.

8.4.5 $OFF/ERR\ LED = Error$

Color: Red

ON when OSSDs are OFF

System startup internal testing failed

FLASH when an error occurs.

Fast blinking & RES or COM fast blinking

= Communication error of another unit

Slow blinking & RES or COM slow blinking

= Communication error of this unit

OFF when all internal diagnostics are successfully passed and OSSD are ON.

8.5 LED Examples G9SR-EX₋-T90-

8.5.1 Normal operation - LEDs G9SR-EX \square -T90- \square

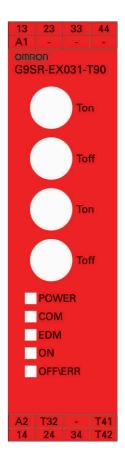
		LED sign	al Pattern			
ID	OFF/ERR	NO	EDM	COM	POWER	Description
1.		#		#		Outputs active. Output loop active.
2.		#	#	#		Outputs active. Output loop active. EDM enabled.
3.	\otimes	\otimes		$\not\equiv$		Ton or Toff expiring.
4.				#	#	Outputs not active. Output loop active.

8.5.2 Error situations - LEDs G9SR-EX \square -T90- \square

		LED sigr	nal Patterr	ı		
ID	OFF/ERR	NO	ЕБМ	СОМ	POWER	Description
1.	$\widetilde{\mathbb{H}}$		$\not\equiv$	\otimes	#	Error on EDM input
2.	#		0	#	#	Error during cyclic test. Error due to other unit connected via output loop. Wrong type of unit connected to the output loop.
3.	$\widetilde{\mathbb{H}}$		$\not\equiv$	#	#	Delay time selection incorrect.
4.	#			#	#	ERR and COM fast blinking (3 per sec.) = communication error of another unit ERR and COM slow blinking (1 per sec.) = communication error of this unit

8.6 Terminal and signal names of the G9SR-EX₋T90-

- **13** Relay Output 1.1 (NO)
- **23** Relay Output 2.1 (NO)
- **33** Relay Output 3.1 (NO)
- 44 Output Auxiliary (Status)
- A1 Power Supply
- A2 Power Supply GND
- T32 EDM Input
- T41 Output Loop OUT
- **14** Relay Output 1.2 (NO)
- **24** Relay Output 2.2 (NO)
- **34** Relay Output 3.2 (NO)
- T42 Output Loop IN



9 Stand-alone operation of a G9SR unit

The G9SR-BC and G9SR-AD can operate stand alone. The G9SR-EX can only operate in combination with a G9SR-AD.

The G9SR units are intended for the functions listed in the table below:

	G9SR-BC	G9SR-AD	G9SR-EX
E-Stop function	Yes	Yes	No
Door monitoring (safety limit switches)	Yes	Yes	No
Door monitoring (key operated switches)	Yes	Yes	No
Door monitoring (non-contact switches)	Yes	Yes	No
ESPE monitoring	Yes	Yes	No
Additional safety outputs	No	No	Yes

Note on the G9SR-EX unit:

The extra outputs realised with the G9SR-EX units have an ON-delay timer and an OFF-delay timer for additional control of your outputs.

9.1 Wiring examples stand-alone G9SR-BC

9.1.1 G9SR-BC wiring with dynamic testing with EDM

Function setting:

DIP Switch 1 OFF = Manual Restart

DIP Switch 2 ON = Dynamic input testing Enabled

DIP Switch 3 ON = EDM Enabled

Description:

E-Stop pushbutton connected to T12 and T22 Restart pushbutton connected to T31 KM1 and KM2: Motor Contactors Feedback loop (EDM) connected to T32

Remarks:

Wiring is using the dynamic test pulses.

Applicable up to PLe acc. EN ISO 13849-1

Motor circuit (contacts of VM1 and VM2) not sh

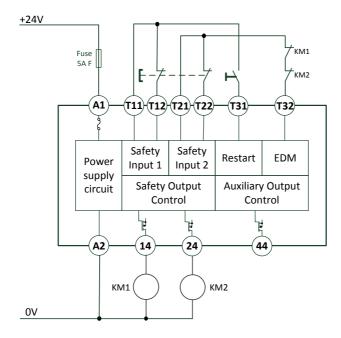


Figure 5 - G9SR-BC wiring with dynamic testing with EDM

9.1.2 G9SR-BC wiring without dynamic testing with EDM

Function setting:

DIP Switch 1 OFF = Manual Restart

DIP Switch 2 OFF = Dynamic input testing Disabled

DIP Switch 3 ON = EDM Enabled

Description:

E-Stop pushbutton connected to T12 and T22

Restart pushbutton connected to T31 KM1 and KM2: Motor Contactors

Feedback loop (EDM) connected to T32

Remarks:

Applicable up to PLd acc. EN ISO 13849-1

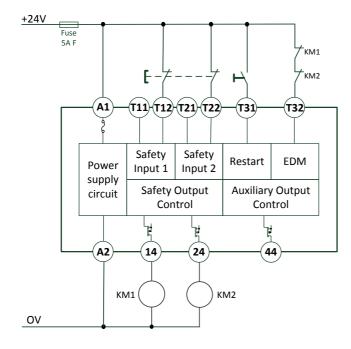


Figure 6 - G9SR-BC wiring without dynamic testing with EDM

9.1.3 G9SR-BC wring with dynamic testing without EDM

Function setting:

DIP Switch 1 OFF = Manual Restart

DIP Switch 2 ON = Dynamic input testing Enabled

DIP Switch 3 OFF = EDM Disabled

Description:

E-Stop pushbutton connected to T12 and T22 $\,$

Restart pushbutton connected to T31

KM1 and KM2: Motor Contactors

Remarks:

Wiring is using the dynamic test pulses. Applicable up to PLd acc. EN ISO 13849-1

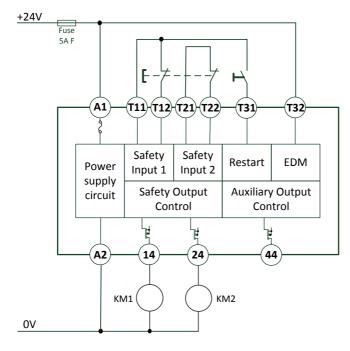


Figure 7 - G9SR-BC wiring with dynamic testing without EDM

9.1.4 G9SR-BC wiring without dynamic testing without EDM

Function setting:

DIP Switch 1 OFF = Manual Restart

DIP Switch 2 OFF = Dynamic input testing Disabled

DIP Switch 3 OFF = EDM Disabled

Description:

E-Stop pushbutton connected to T12 and T22

Restart pushbutton connected to T31

KM1 and KM2: Motor Contactors

Remarks:

Applicable up to PLd acc. EN ISO 13849-1 Motor circuit (contacts of KM1 and KM2) not shown.

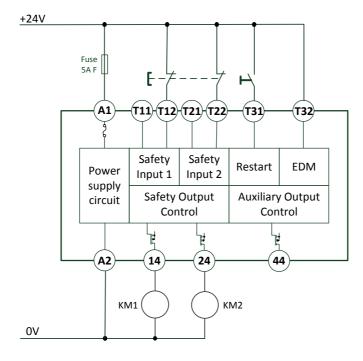


Figure 8 - G9SR-BC wiring without dynamic testing without EDM

9.2 Stand-alone G9SR-AD

9.2.1 G9SR-AD wiring with dynamic testing with EDM

Function setting:

DIP Switch 1 OFF = Manual Restart

DIP Switch 2 ON = Dynamic input testing Enabled

DIP Switch 3 ON = EDM Enabled

Description:

E-Stop pushbutton connected to T12 and T22 Restart pushbutton connected to T31 KM1 and KM2: Motor Contactors Feedback loop (EDM) connected to T32

Remarks:

Wiring is using the dynamic test pulses. Applicable up to PLe acc. EN ISO 13849-1

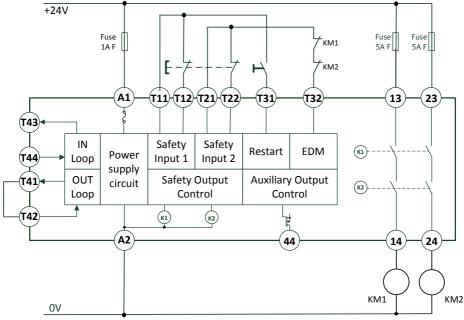


Figure 9 - G9SR-AD wiring with dynamic testing with EDM

9.2.2 G9SR-AD wiring with dynamic testing without EDM

Function setting:

DIP Switch 1 OFF = Manual Restart

DIP Switch 2 ON = Dynamic input testing Enabled

DIP Switch 3 OFF = EDM Disabled

Description:

E-Stop pushbutton connected to T12 and T22

Restart pushbutton connected to T31 KM1 and KM2: Motor Contactors

Remarks:

Wiring is using the dynamic test pulses. Applicable up to PLd acc. EN ISO 13849-1

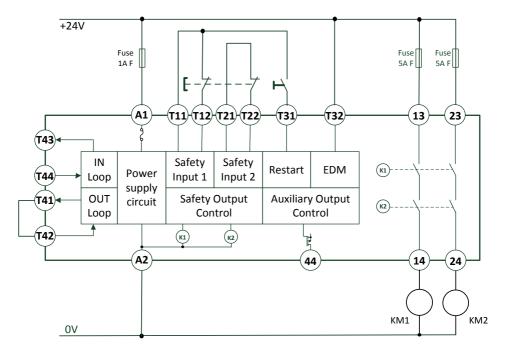


Figure 10 - G9SR-AD wiring with dynamic testing without EDM

9.2.3 G9SR-AD wring without dynamic testing with EDM

Function setting:

DIP Switch 1 OFF = Manual Restart

DIP Switch 2 OFF = Dynamic input testing Disabled

DIP Switch 3 ON = EDM Enabled

Description:

E-Stop pushbutton connected to T12 and T22

Restart pushbutton connected to T31 KM1 and KM2: Motor Contactors Feedback loop (EDM) connected to T32

Remarks:

Applicable up to PLd acc. EN ISO 13849-1

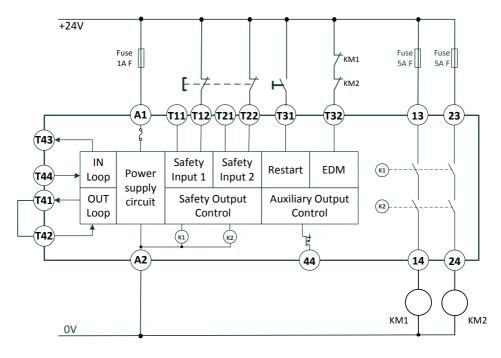


Figure 11 - G9SR-AD wring without dynamic testing with EDM

9.2.4 G9SR-AD wiring without dynamic testing without EDM

Function setting:

DIP Switch 1 OFF = Manual Restart

DIP Switch 2 OFF = Dynamic input testing Disabled

DIP Switch 3 OFF = EDM Disabled

Description:

E-Stop pushbutton connected to T12 and T22

Restart pushbutton connected to T31 KM1 and KM2: Motor Contactors

Remarks:

Applicable up to PLd acc. EN ISO 13849-1

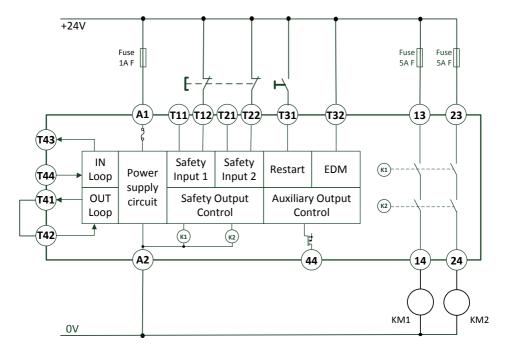


Figure 12 - G9SR-AD wiring without dynamic testing without EDM

10 Combining G9SR units

The G9SR-AD□-□ unit can be combined with G9SR-BC□-□ and G9SR-EX□-T90-□ units.

Combinations possible are:

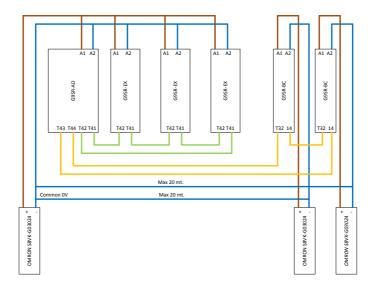
- 1) Extending a G9SR-AD with up to two G9SR-BC to create an input loop. See also § 10.1 *Input loop* on page 49
- 2) Extending a G9SR-AD with up to three G9SR-EX to create an output loop. See also § 10.2 *Output loop* on page 50
- 3) Extending a G9SR-AD with up to two G9SR-BC plus up to three G9SR-EX. This creates an input loop and an output loop. See also § 10.3 *Input loop and Output loop* on page 51



Use a single power supply for AD and EX units.

For BC units separate power supplies can be used connecting the 0V of all power supplies together.

Below an example of G9SR system with multi power supplies connections

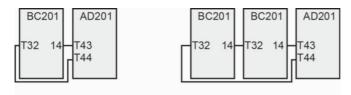


10.1 Input loop

An input loop increases the number of safety inputs.

- G9SR-AD□-□ units use terminals T43 and T44 for the Input loop.
- G9SR-BC□-□ units use terminals T32 (EDM input) and 14.

Connect the units according to following wiring schematic.





Caution !

Maximum cable length for each wire of the Input loop is 20 meters.



Maximum cable impedance for the safety input circuit must be less than 250 ohm.



When the G9SR-BC is operating as a safety input in an input loop configuration, the two output terminals "13" and "14" cannot be used to drive additional loads.

Make sure there is no load connected to these two terminals when the unit is in an input loop.

10.2 Output loop

An output loop increases the number of safety outputs available.

- G9SR-AD□-□ units use terminals T41 and T42 for the Output loop.
- G9SR-EX□-□ units use terminals T41 and T42 for the Output loop.

Connect 1, 2 or 3 G9SR-EX□-T90-□ units according to following wiring schematic:





Maximum cable length for each wire of the Output loop is 2 meters.

10.3 Input loop and Output loop

The maximum allowable system configuration is a G9SR-AD unit extended with a maximum of two G9SR-BC units as additional safety inputs and three G9SR-EX units as additional safety outputs.



Figure 13 - Maximum configuration

This configuration shows:

- * three safety inputs two on the G9SR-BCs
 - one on the G9SR-AD
- * one safety output with two NO contacts on the G9SR-AD
- * three safety outputs with three NO contacts on the G9SR-Exs



Maximum cable length for Input loop is 20 meters. Maximum cable length for Output loop is 2 meters. The maximum cable length impedance for the safety input circuit must be lower than 250 ohm.

11 Appendix A: Wiring examples

11.1 Wiring examples G9SR-BC□-□ unit

11.1.1 G9SR-BC \square - \square in E-stop application up to PLe

Settings G9SR-BC:

- Manual Restart
- Dynamic input testing Enabled
- EDM Enabled
- Aux inverted

Dip switch settings:

1	2	3	4	5	6	7	8
OFF	ON	ON	OFF	OFF	OFF	OFF	OFF

Description:

E-Stop pushbutton connected to T12 and T22

Restart pushbutton connected to T31

KM1 and KM2: Motor Contactors

Feedback loop (EDM) connected to T32

Remarks:

This setup can also be used with safety limit switches and key operated door switches. For door and gate monitoring applications please consider the requirements from ISO 14119.

Wiring is using the dynamic test pulses.

Applicable up to PLe acc. EN ISO 13849-1 (electrical system).

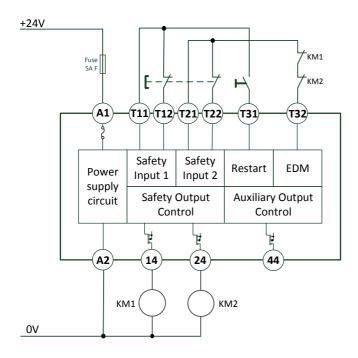


Figure 14 - G9SR-BC□-□ in E-stop application up to PLe

Note: Ensure the dip switch settings of your G9SR-BC are according to the requirements of your application.

See also § 6.3 Dip switches and functions of G9SR-BC \square - \square on page 20.

11.1.2 $G9SR-BC \square - \square$ in E-Stop application up to PLd

Settings G9SR-BC:

- Manual Restart enabled
- EDM enabled
- Dynamic Input Test disabled
- Aux inverted

Dip switch settings:

1	2	3	4	5	6	7	8
OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF

Description:

E-Stop pushbutton connected to T12 and T22 Restart pushbutton connected to T31

KM1 and KM2: Motor Contactors

Feedback loop (EDM) connected to T32

Remarks:

This setup can also be used with safety limit switches and key operated door switches. For door and gate monitoring applications please consider the requirements from ISO 14119.

Applicable up to PLd acc. EN ISO 13849-1 (electrical system).

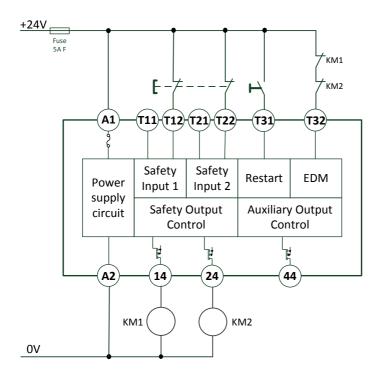


Figure 15 - G9SR-BC \square - \square in E-Stop application up to PLd

Note: Ensure the dip switch settings of your G9SR-BC are according to the requirements of your application.

See also § 6.3 Dip switches and functions of G9SR-BC \square - \square on page 20.

11.1.3 $G9SR-BC \square \neg \square$ for door interlocking up to PLe with F3S-TGR-N C

Settings G9SR-BC:

- Manual Restart enabled
- EDM enabled
- Dynamic Input Test enabled
- Aux inverted

Dip switch settings:

1	2	3	4	5	6	7	8
OFF	ON	ON	OFF	OFF	OFF	OFF	OFF

Description:

Non-contact switch connected to T12 and T22

Restart pushbutton connected to T31

KM1 and KM2: Motor Contactors

Feedback loop (EDM) connected to T32

Remarks:

This setup can also be used with safety limit switches and key operated door switches. For door and gate monitoring applications please consider the requirements from ISO 14119.

Wiring is using the dynamic test pulses.

Applicable up to PLe acc. EN ISO 13849-1 (electrical system).

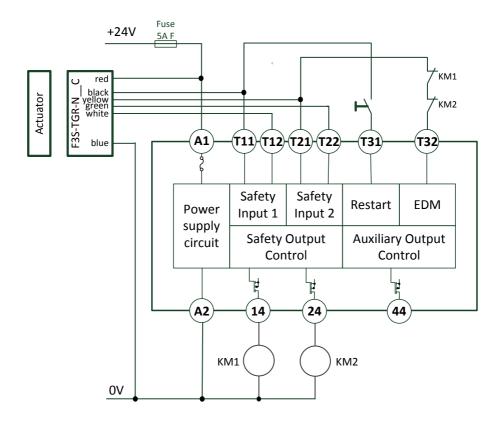


Figure 16 - G9SR-BC□-□ for door interlocking up to PLe with F3S-TGR-N_C

Note: Ensure the dip switch settings of your G9SR-BC are according to the requirements of your application.

See also § 6.3 Dip switches and functions of G9SR-BC \square - \square on page 20.

11.1.4 $G9SR-BC \square \neg \square$ for door interlocking up to PLd with F3S-TGR-N C

Settings G9SR-BC:

- Manual Restart enabled
- EDM enabled
- Dynamic Input Test disabled
- Aux inverted

Dip switch settings:

1	2	3	4	5	6	7	8
OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF

Description:

Non-contact switch connected to T12 and T22

Restart pushbutton connected to T31 KM1 and KM2: Motor Contactors

Feedback loop (EDM) connected to T32

Remarks:

This setup can also be used with safety limit switches and key operated door switches. For door and gate monitoring applications please consider the requirements from ISO 14119.

Applicable up to PLd acc. EN ISO 13849-1 (electrical system).

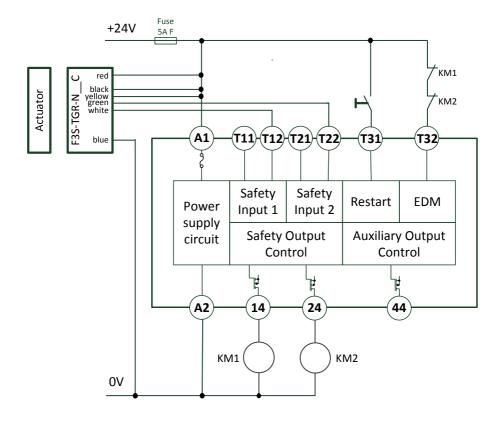


Figure 17 - G9SR-BC□-□ for door interlocking up to PLd with F3S-TGR-N_C

Note: Ensure the dip switch settings of your G9SR-BC are according to the requirements of your application.

See also § 6.3 Dip switches and functions of G9SR-BC \square - \square on page 20.

11.1.5 G9SR-BC \square - \square with Safety Sensors in applications up to PLe (F3S-TGR-CL)

Settings G9SR-BC:

Manual Restart enabled

- EDM enabled
- Dynamic Input Test disabled
- Aux inverted

Dip switch settings:

1	2	3	4	5	6	7	8
OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF

Description:

Safety Sensor connected to T12 and T22 Restart pushbutton connected to T31 KM1 and KM2: Motor Contactors Feedback loop (EDM) connected to T32

Remarks:

This setup can also be used for all sensors with solid state safety outputs Applicable up to PLe acc. EN ISO 13849-1 (electrical system). Motor circuit (contacts of KM1 and KM2) not shown.

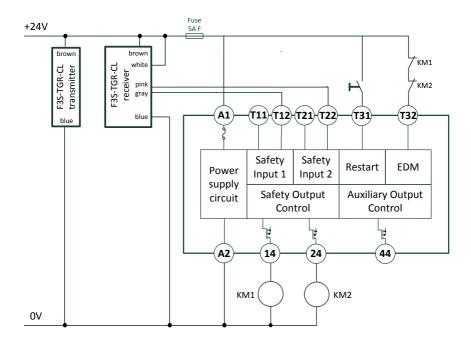


Figure 18 - G9SR-BC□-□ with Safety Sensors in applications up to PL=e (F3S-TGR-CL)

Note: Ensure the dip switch settings of your G9SR-BC are according to the requirements of your application.

See also § 6.3 Dip switches and functions of G9SR-BC \square - \square on page 20.

11.2 Wiring examples G9SR-AD□-□ unit

11.2.1 G9SR- $AD\Box$ - \Box in E-Stop application up to PLe

Settings G9SR-AD:

- Manual Restart enabled
- EDM enabled
- Dynamic Input Test enabled

Dip switch settings:

1	2	3	4	5	6	7	8
OFF	ON	ON	OFF	OFF	OFF	OFF	OFF

Description:

E-Stop pushbutton connected to T12 and T22

Restart pushbutton connected to T31

KM1 and KM2: Motor Contactors

Feedback loop (EDM) connected to T32

Remarks:

This setup can also be used with safety limit switches and key operated door switches. For door and gate monitoring applications please consider the requirements from ISO 14119.

Wiring is using the dynamic test pulses.

Applicable up to PLe acc. EN ISO 13849-1 (electrical system).

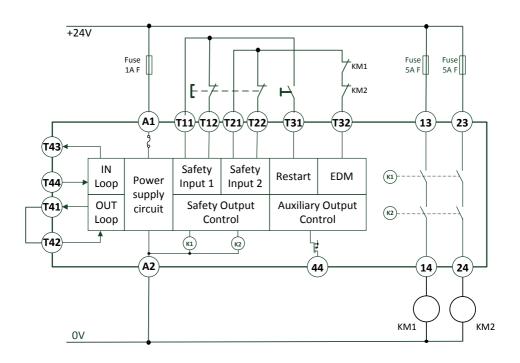


Figure 19 - G9SR-AD \square - \square in E-Stop application up to PLe

Note: Ensure the dip switch settings of your G9SR-AD unit are according to the requirements of your application.

See also § 7.3 Dip switches and functions of G9SR-AD \square - \square on page 27.

11.2.2 G9SR-AD□-□ in E-Stop application up to PLd

Settings G9SR-AD:

- Manual Restart enabled
- EDM enabled
- Dynamic Input Test disabled

Dip switch settings:

1	2	3	4	5	6	7	8
OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF

Description:

E-Stop pushbutton connected to T12 and T22

Restart pushbutton connected to T31

KM1 and KM2: Motor Contactors

Feedback loop (EDM) connected to T32

Remarks:

This setup can also be used with safety limit switches and key operated door switches. For door and gate monitoring applications please consider the requirements from ISO 14119.

Wiring is using the dynamic test pulses.

Applicable up to PLd acc. EN ISO 13849-1 (electrical system).

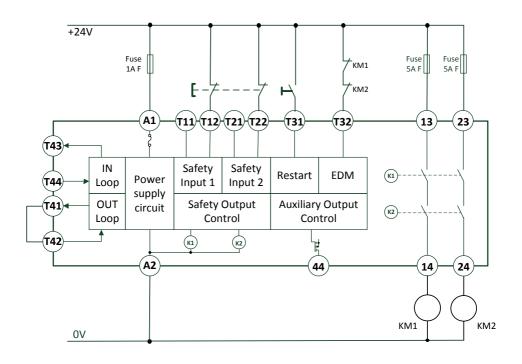


Figure 20 - G9SR-AD \square - \square in E-Stop application up to PLd

Note: Ensure the dip switch settings of your G9SR-AD unit are according to the requirements of your application.

See also § 7.3 Dip switches and functions of G9SR-AD \square - \square on page 27.

11.2.3 G9SR-AD \square \square with door interlocking up to PLe with F3S-TGR-N C

Settings G9SR-AD:

- Manual Restart enabled
- EDM enabled
- Dynamic Input Test enabled

Dip switch settings:

1	2	3	4	5	6	7	8
OFF	ON	ON	OFF	OFF	OFF	OFF	OFF

Description:

Non-contact switch connected to T12 and T22

Restart pushbutton connected to T31

KM1 and KM2: Motor Contactors

Feedback loop (EDM) connected to T32

Remarks:

This setup can also be used with safety limit switches and key operated door switches. For door and gate monitoring applications please consider the requirements from ISO 14119.

Wiring is using the dynamic test pulses.

Applicable up to PLe acc. EN ISO 13849-1 (electrical system).

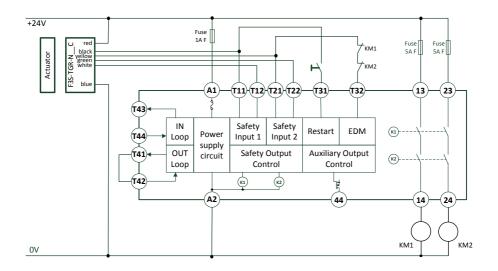


Figure 21 - G9SR-AD \square - \square with door interlocking up to PLe with F3S-TGR-N $_$ C

Note: Ensure the dip switch settings of your G9SR-AD unit are according to the requirements of your application.

See also § 7.3 Dip switches and functions of G9SR-AD \square - \square on page 27.

11.2.4 G9SR-AD \square \square with door interlocking up to PLd with F3S-TGR-N C

Settings G9SR-AD:

- Manual Restart enabled
- EDM enabled
- Dynamic Input Test disabled

Dip switch settings:

1	2	3	4	5	6	7	8
OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF

Description:

Non contact switch connected to T12 and T22

Restart pushbutton connected to T31

KM1 and KM2: Motor Contactors

Feedback loop (EDM) connected to T32

Remarks:

This setup can also be used with safety limit switches and key operated door switches. For door and gate monitoring applications please consider the requirements from ISO 14119.

Applicable up to PLd acc. EN ISO 13849-1 (electrical system).

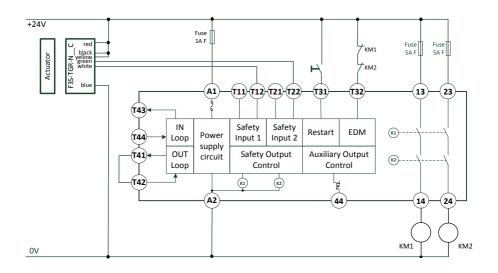


Figure 22 - G9SR-AD□-□ with door interlocking up to PLd with F3S-TGR-N_C

Note: Ensure the dip switch settings of your G9SR-AD unit are according to the requirements of your application.

See also § 7.3 Dip switches and functions of G9SR-AD \square - \square on page 27.

11.2.5 G9SR-AD□-□ with Safety Sensors in applications up to PLe

Settings G9SR-AD:

- Manual Restart enabled
- EDM enabled
- Dynamic Input Test disabled

Dip switch settings:

1	2	3	4	5	6	7	8
OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF

Description:

Safety Sensor connected to T12 and T22 Restart pushbutton connected to T31 KM1 and KM2: Motor Contactors Feedback loop (EDM) connected to T32

Remarks:

This setup can also be used for all sensors with solid state safety outputs Applicable up to PLe acc. EN ISO 13849-1 (electrical system). Motor circuit (contacts of KM1 and KM2) not shown.

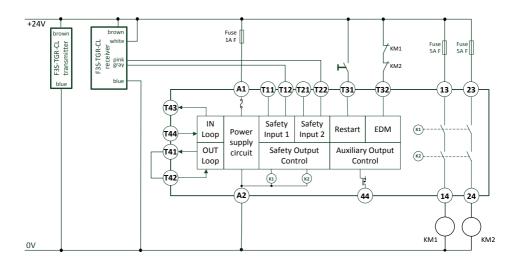


Figure 23 - G9SR-AD□-□ with Safety Sensors in applications up to PLe

Note: Ensure the dip switch settings of your G9SR-AD are according to the requirements of your application.

See also § 7.3 Dip switches and functions of G9SR-AD \square - \square on page 27.

11.3 Wiring examples G9SR-AD - unit with input loop and output loop

11.3.1 Machine example



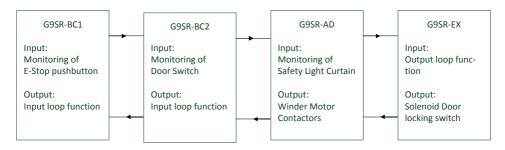
Figure 24 – Machine example

11.3.2 Description of the safety related control functions in this application

- 1. When the E-Stop is pushed, the winder stops immediately and the door is locked for another 30s.
- 2. When the Light Curtain detects a person, the winder stops immediately and the door is locked for another 30s.
- 3. The door is mechanically locked by a door locking switch. Unlocking is provided by electrical signal.
- 4. When the door is not locked, machine startup must be prevented.

11.3.3 Solution - block diagram

The solution is using 2 G9SR-BC, 1 G9SR-AD and 1 G9SR-EX



14.3.4 Function settings and DIP switch settings

G9SR-BC1: Dynamic input test Enabled

EDM Disabled Input loop Enabled

G9SR-BC2: Dynamic Input test Enabled

EDM Disabled Input loop Enabled

G9SR-AD Dynamic Input test Disabled

Manual Restart EDM Enabled Input loop Enabled Output loop Enabled

G9SR-EX: EDM Enabled

Output loop Enabled OFF-Delay time = 30s

	SW1	SW2	SW3	SW4	SW5	SW6	SW7	SW8
G9SR-BC1	ON	ON	OFF	ON	OFF	OFF	OFF	OFF
G9SR-BC2	ON	ON	OFF	ON	OFF	OFF	OFF	OFF
G9SR-AD	OFF	OFF	ON	ON	ON	OFF	ON	OFF

	SW1	SW2	SW3	SW4
G9SR-EX	0	В	0	В

Note:

Ensure the dip switch settings of all G9SR-units are according to the requirements of your application.

See also

- \S 6.3 Dip switches and functions of G9SR-BC $\neg \neg$ on page 20
- § 7.3 Dip switches and functions of G9SR-AD \square - \square on page 27
- § 8.3 Rotary switch functions of G9SR-EX□-T90-□ on page 34

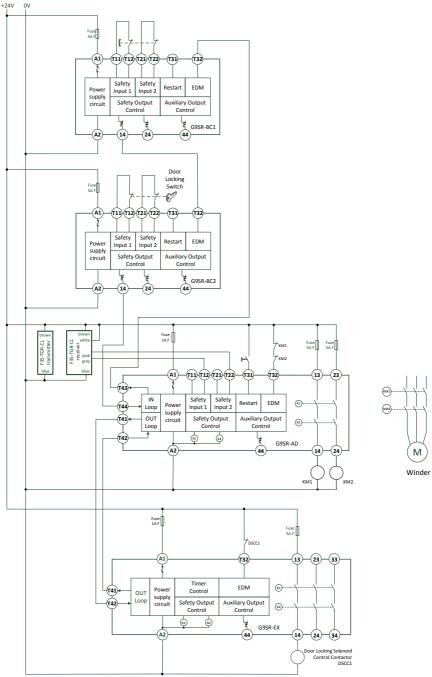


Figure 25 – Wiring diagram for machine example

My notes:

12 Appendix B: Logging of test results

MONTH: SYSTEM:

Date	Performed with good results. (OFF Test / ON Test / Both)	Technicians Signature:	Remarks:
1	(011 0100, 000, 1000, 1000)	~-8	
2			
3			
4			
5			
6			
7			
8			
9			
10			
11			
12			
13			
14			
15			
16			
17			
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20			
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25			
26			
27			
28			
29			
30			
31			

Logging of test results MONTH:

SYSTEM:

Date	Performed with good results.	Technicians	Remarks:
	(OFF Test / ON Test / Both)	Signature:	
1	(011 100)	~-8	
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