## JUMO DICON touch

## Two-channel process and program controller with touchscreen 8.9 cm (3.5 ")


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## 1 Introduction

### 1.1 Safety information

## General information

This manual contains information that must be observed in the interest of your own safety and to avoid damage to assets. This information is supported by symbols which are used in this manual as indicated.
Please read this manual before commissioning the device. Keep the manual in a place accessible to all users at all times.
If difficulties occur during commissioning please refrain from carrying out any manipulations that could jeopardize your warranty rights.

### 1.1.1 Warning symbols



## DANGER!

This symbol indicates that personal injury caused by electrical shock may occur if the respective precautionary measures are not carried out.


## WARNING!

This symbol in connection with the signal word indicates that personal injury may occur if the respective precautionary measures are not carried out.

## CAUTION!

This symbol in connection with the signal word indicates that damage to assets or data loss will occur if the respective precautionary measures are not taken.

## CAUTION!

This symbol indicates that components could be destroyed by electrostatic discharge (ESD = Electro Static Discharge) if the respective cautionary measures are not taken.
Only use the ESD packages intended for this purpose to return device inserts, assembly groups, or assembly components.

## READ DOCUMENTATION!

This symbol - placed on the device - indicates that the associated device documentation has to be observed. This is necessary to recognize the kind of the potential hazards as well as the measures to avoid them.

### 1.1.2 Note signs



## NOTE!

This symbol refers to important information about the product, its handling, or additional use.

REFERENCE!
This symbol refers to further information in other sections, chapters, or manuals.

## 1 Introduction

## FURTHER INFORMATION!

This symbol is used in the tables and refers to further information in connection with the table.


## DISPOSAL!

This device and the batteries (if installed) must not be disposed in the garbage can after use! Please ensure that they are disposed properly and in an environmentally friendly manner.

### 1.1.3 Representation

## Menu structure

The > symbol between words indicates a menu structure and enables the parameters to be quickly detected in the configuration level or for navigation in the setup program, such as the software version of the devices, for example:
Device menu > General > Version > SW version

## Active input

The device has no buttons and is operated using a finger or a pen.
The following instructions will therefore make references to "touching" and the images displayed will show a hand operating the device.


## 1 Introduction

### 1.2 Description

The DICON touch is a two-channel universal process and program controller that displays information on a vibrant screen. The device is easy to operate via a touchscreen.
Both control channels use the tried-and-tested JUMO control algorithm with two possible optimization options. These enable a simple and highly-accurate startup. It also enables multiple zone control, cascade control, or other complex control tasks.
The block diagram below illustrates the various different hardware options offered by the modular hardware concept. Four analog universal inputs and up to eight external inputs can record a variety of physical measured values with high precision. The actuators can be controlled directly in the device with either an analog or digital setup. These can be expanded further through external digital outputs. Interfaces such as Modbus (master/slave), PROFIBUS, or Ethernet with Web server can be used for the communication with higher-order systems.
To ensure secure process operation, the device has a password-protected user administration with individual assignment of rights for different levels or control commands. Screen masks for controllers, program generators, recording, and for overview screens are ready-made and available. An individual process screen can be created using the configuration software. Using the extra-code recording function, important analog and digital process values can be saved so that they are tamper-proof, so that they can be graphically visualized, and so that they can be exported via interface or USB stick in a tamper-proof fashion to the PC.
The configuration software ensures that the process controller can be easily programmed, that math or logical coherences can be described, and that customer-specific linearizations can be created. In addition, tools for simulating external signals or control paths are included. These tools can also record for the duration of the startup.
A comprehensive alarm and limit-value concept as well as a flexible digital signal administration complete the "all-in-one" device.

## 1 Introduction

### 1.3 Block diagram



## 2 Identifying the device version

### 2.1 Order details

| (1) | Basic type |
| :---: | :---: |
| 703571 | JUMO DICON touch - two-channel process and program controller with RS485 interface |
| (2) | Version |
| 8 | Standard with factory settings |
| 9 | Customer-specific configuration (specifications in plain text) |
| (3) | National language of display texts |
| 01 | German |
| 02 | English |
| 03 | French |
| (4) | Input 3 (IN10) |
| 00 | Not used |
| 10 | Analog input (universal) |
| (5) | Input 4 (IN11) |
| 00 | Not used |
| 10 | Analog input (universal) |
| (6) | Output 3 (OUT3/4) |
| 00 | None |
| 11 | 1 relay (changeover contact) |
| 12 | 2 relays (N/O contact) |
| 13 | 1 solid-state relay $230 \mathrm{~V}, 1 \mathrm{~A}$ |
| 14 | 1 logic output 0/22 V |
| 15 | 2 logic outputs 0/12 V, 20 mA |
| 16 | 1 analog output |
| 17 | 2 PhotoMOS® relays $®^{1}$ |
| (7) | Output 4 (OUT5/6) |
| 00 | None |
| 11 | 1 relay (changeover contact) |
| 12 | 2 relays (N/O contact) |
| 13 | 1 solid-state relay $230 \mathrm{~V}, 1 \mathrm{~A}$ |
| 14 | 1 logic output 0/22 V |
| 15 | 2 logic outputs 0/12 V, 20 mA |
| 16 | 1 analog output |
| 17 | 2 PhotoMOS® relays |
| (8) | Output 5 (OUT7/8) |
| 00 | None |
| 11 | 1 relay (changeover contact) |
| 12 | 2 relays (N/O contact) |

## 2 Identifying the device version

| 13 | 1 solid-state relay $230 \mathrm{~V}, 1 \mathrm{~A}$ |
| :---: | :---: |
| 14 | 1 logic output 0/22 V |
| 15 | 2 logic outputs $0 / 12 \mathrm{~V}, 20 \mathrm{~mA}$ |
| 16 | 1 analog output |
| 17 | 2 PhotoMOS® relays |
|  | Output 6 (OUT9/10) |
| 00 | None |
| 11 | 1 relay (changeover contact) |
| 12 | 2 relays (N/O contact) |
| 13 | 1 solid-state relay $230 \mathrm{~V}, 1 \mathrm{~A}$ |
| 14 | 1 logic output 0/22 V |
| 15 | 2 logic outputs $0 / 12 \mathrm{~V}, 20 \mathrm{~mA}$ |
| 16 | 1 analog output |
| 17 | 2 PhotoMOS® relays |
| (10) | Output 7 (OUT11/12) |
| 00 | None |
| 11 | 1 relay (changeover contact) |
| 12 | 2 relays (N/O contact) |
| 13 | 1 solid-state relay $230 \mathrm{~V}, 1 \mathrm{~A}$ |
| 14 | 1 logic output 0/22 V |
| 15 | 2 logic outputs 0/12 V, 20 mA |
| 16 | 1 analog output |
| 17 | 2 PhotoMOS® relays |
| (11) | Supply voltage |
| 23 | AC 110 to $240 \mathrm{~V}+10 /-15 \%, 48$ to 63 Hz |
| 25 | AC/DC 20 to $30 \mathrm{~V}, 48$ to 63 Hz |
| (12) | COM2 interface |
| 00 | Not used |
| 08 | Ethernet |
| 54 | RS422/485 Modbus RTU |
| 64 | PROFIBUS-DP |
| (13) | DIN-tested |
| 000 | Without approval |
| 056 | With DIN approval |
| (14) | GL-tested |
| 000 | Without approval |
| 062 | With GL approval |
| (15) | Extra codes |
| 000 | Without extra code |
| 213 | Recording function |

## 2 Identifying the device version

| 214 | Math and logic module |
| :--- | :--- |
| 223 | Program controller |

${ }^{1}$ PhotoMOS is a registered trademark of Panasonic Corporation
(1) $/(2)-(3)-(4)(5)-(6)(7)(8)(9)(10-(11)-(12) /(13),(14),(15)$
)
Order code

Order exam-



 ple
${ }^{1}$ List extra codes in sequence, separated by commas.

### 2.2 Scope of delivery

- 1 controller in the ordered version
- 1 Operating Manual B 703571.0
- 1 panel seal 4 retaining elements for panel installation


### 2.3 General accessories

| Article | Part no. |
| :--- | :--- |
| Program editor/startup | 00607139 |
| Setup/program editor | 00606496 |
| PCA3000/PCC JUMO software package 709701/709702 | 00431884 |
| USB cable A-connector mini B-connector 3 m | 00506252 |

## 2 Identifying the device version

### 2.4 Accessories



[^0]
## 2 Identifying the device version

### 2.5 Nameplate

## Position

The nameplate is affixed to the case.


## Contents

The nameplates contain important information. This includes:

| Description | Designation on the nameplate |
| :--- | :--- |
| Device type (A) | Type |
| Voltage supply, power consumption (B) |  |
| Fabrication number (C) | F-No. |
| Part no. (D) | TN |

## Device type

Compare the specifications on the nameplate with the order.
Identify the supplied device version using the order details (order code).

## Part no. (PN)

The part no. clearly identifies an article in the catalog. It is important for communication between the customer and the sales department.

## Fabrication number (F-No.:)

Among other things, the fabrication number contains the date of production (year/week).
Example: F-No. $=1234567801013010000$
The figures in question are in positions 12, 13, 14, and 15 (from the left).
The device was therefore produced in the 1st calendar week of 2013.

## Identifying the optional modules

The device type also contains information about optional default modules, as in the following example of the Ethernet interface (Figure 08):
703571/8-01-00-00-00-00-00-00-00-25-08... (see type key)
Further information on identifying optional modules is included in this chapter:
$\Rightarrow$ B 703571.0 - Chapter 9.2 "Slots", page 51

### 3.1 Mounting site and climatic conditions

The mounting site should be free from vibration, dust and corrosive media. Install controllers as far away as possible from sources of electromagnetic fields, such as those created by frequency converters or high-voltage ignition transformers. Conditions at the mounting site must correspond to the following environmental influences:

### 3.1.1 Environmental influences

| Ambient/storage temperature range | -5 to $+55^{\circ} \mathrm{C} /-30$ to $+70^{\circ} \mathrm{C}$ |
| :--- | :--- |
| Resistance to climatic conditions | Humidity 3 K 3 (DIN EN $60721-3-3$ ) with extended temperature <br> range, <br> rel. humidity $\leq 95 \%$ mid-year without condensation |

### 3.1.2 Case

| Case type | Plastic front frame with metal case barrel |
| :--- | :--- |
| Front frame dimensions | $96 \mathrm{~mm} \times 96 \mathrm{~mm}$ |
| Panel cut-out | $92^{+0.8} \mathrm{~mm} \times 92^{0.8} \mathrm{~mm}$ according to DIN IEC 61554 |
| Close mounting | Spacing between the panel cut-outs, min. 35 mm horizontally and <br> min. 80 mm vertically |
| Panel thickness | Max. 5 mm |
| Depth behind panel | Max. 130 mm |
| Mounting | Four mounting brackets |
| Operating position <br> (including the viewing angle of the TFT color <br> screen) | Any <br> Horizontal $\pm 65^{\circ}$, vertical +40 to $-65^{\circ}$ <br> Protection type |
| Weight (fully fitted) | approx. IP66, rear IP20, according to DIN EN 60529 |

## 3 Mounting

### 3.1.3 Electrical data

| Voltage supply <br> Connection <br> Voltage | At the back via screw terminals AC/DC $20 \ldots 30 \mathrm{~V}, 48$ to 63 Hz or AC 110 to $240 \mathrm{~V}+10 /-15 \%, 48$ to 63 Hz |  |
| :---: | :---: | :---: |
| Power consumption | At voltage supply 230 V : max. 38.1 VA/11.5 W At voltage supply 24 V : max. 21.9 VA/11.5 W |  |
| Inputs and outputs <br> Connection <br> Conductor cross section | At the back via screw terminals Max. $2.5 \mathrm{~mm}^{2}$, wire or strand with end sleeve |  |
| Electrical safety | According to DIN EN 61010-1 Overvoltage category III, pollution degree 2 |  |
| Electromagnetic compatibility Interference emission Interference immunity | According to DIN EN 61326-1 Class A - For industrial applications only Industrial requirements |  |
| Memory data recorder | Memory cycle | Recording interval |
| When recording: 4 analog signals 3 digital signals | 1 s | approx. 44 days |
|  | 3 s | approx. 220 days |
|  | 10 s | approx. 441 days |
|  | 60 s | approx. 2646 days (7 years, 91 days) |

### 3.2 Dimensions


(20) USB host interface
(21) USB device interface for setup
(22) Panel cut-out

### 3.3 Close mounting

If several devices are mounted on a switch board above or next to each other, the panel cutouts must be positioned 35 mm horizontally and at least 80 mm vertically away from each other.

## 3 Mounting

### 3.4 Insertion in panel cut-out



| Step | Activity |
| :--- | :--- |
| 1 | Affix delivered panel seal (1) on the device from the rear |
| 2 | Insert the device into the panel cut-out from the front and ensure the panel seal is correctly <br> positioned so that no water or dirt can penetrate the case. |
| 3 | From the panel rear, slide the mounting brackets into the guides on the sides of the case. In <br> doing so, the flat faces of the mounting brackets must make contact with the case. |
| 4 | Place the mounting brackets against the panel rear and tighten evenly with a screwdriver <br> until the controller housing is firmly positioned in the panel cut-out. |

### 3.5 Care and treatment of the front cover

The front plate can be cleaned with commercial detergents and cleaning agents.

## NOTE!

The resistive touchscreen cover reacts to finger pressure or can be operated using commercially available pens with a rounded plastic tip.

## CAUTION!

Sharp tools can scratch and damage the cover.
The front plate is not resistant to corrosive acids or lyes, abrasives, or cleaning with highpressure cleaners.
Do not use sharp objects near the device.

3 Mounting

### 4.1 Installation notes




#### Abstract

CAUTION! The delivery status of the device at the first startup does not necessarily correspond to the intended application (for example, Controller 2 inactive). This may result in undefined plant behavior. Therefore, where possible during startup, no actuators should be connected and load current circuits should be isolated. The plant installer is essentially responsible for the startup process.


### 4.1.1 Cables, shielding, and grounding

When selecting the electrical wiring material as well as when installing and connecting the controller electrically, comply with the requirements of DIN VDE 0100 "Low-voltage electrical installations" and the applicable country-specific regulations (for example, based on IEC 60364).

- Where possible, route input, output, and supply cables separately and not parallel to one another.
- Only use shielded and twisted probe and interface cables and where possible, route them at a distance from components or lines that are live.
- For temperature probes, ground the shielding on one side in the control cabinet.
- Do not perform loopthroughs on the grounding cables, but route the cables individually to a shared grounding point in the control cabinet; in doing so, ensure that the cables are as short as possible.
- Ensure potential equalizer is correctly routed.


### 4.1.2 Electrical safety

- The primary fuse protection for the voltage supply should not exceed a value of 20 A (passive) and should not be less than 2 A .
- In order to prevent the destruction of the relay or solid state relay outputs in the event of an external short circuit in the load circuit, the load circuit should be fused to the maximum admissible output current.
- In addition to a faulty installation, incorrectly set values on the controller could also impair the correct function of the following process. Therefore, ensure that safety devices independent of the controller (for example, overpressure valves or temperature limiters/monitors) are available and that it is only possible for qualified personnel to define settings. Please observe the corresponding safety regulations in this context.
- Since not all existing control paths can be controlled with the setting function, the stability of the actual value reached should be monitored.


### 4.1.3 Intended use, misuse

- The controller is intended for use in the industrial sector.



## WARNING!

The controller is not suitable for installation in areas with an explosion hazard There is the risk of an explosion.
The device must only be used outside of areas with an explosion hazard.

## 4 Electrical connection

### 4.2 Galvanic isolation



### 4.3 Connection diagram

## DANGER!

Works involving dangerous electrical voltage ( 230 V ) are performed here.
There is a risk of electric shock.
Switch off all voltage circuits before routing. The electrical connection must only be carried out by qualified personnel.

### 4.3.1 Connection elements


(1) Analog input IN8
(3) Expansion slot for analog input IN10
(5) Voltage supply

AC $240 \mathrm{~V}+10 /-15 \%$, 48 to 63 Hz , max. 38.1 VA
AC/DC 20 to $30 \mathrm{~V}, 48$ to 63 Hz ,
max. 21.9 VA / 11.5 W
(7) Relay output OUT1
(9) Expansion slot for outputs OUT5/6
(11) Expansion slot for outputs OUT9/10
(13) COM1 interface RS485
(15) Digital inputs IN1 to 7
(15) Digtal in 1 I 1 to 7
(8) Expansion slot for outputs OUT3/4
(10) Expansion slot for outputs OUT7/8
(12) Expansion slot for outputs OUT11/12
(14) Expansion slot for COM2 interface
(2) Analog input IN9
(4) Expansion slot for analog input IN11
(6) Relay output OUT2

## 4 Electrical connection

### 4.3.2 Analog inputs

Input IN8, IN9 as standard
Two analog inputs can be added to input (IN10), (IN11) optional boards

| Connection | (Connection element) Input | Symbol and terminal designation |  |
| :---: | :---: | :---: | :---: |
| Thermocouple | (1) IN8 <br> (2) IN9 <br> (3) IN10 | $\longrightarrow_{-}^{+}$ |  |
| RTD temperature probe Two-wire circuit |  |  | $2$ |
| RTD temperature probe Three-wire circuit |  |  | $2$ |
| Voltage DC 0 (2) to 10 V |  | $0$ |  |
| Voltage DC 0 to 1 V |  | $\qquad$ |  |
| Voltage DC 0 to 100 mV |  | $\begin{aligned} & + \\ & U_{X} \end{aligned}$ |  |
| Current DC 0(4) to 20 mA |  | $+\longrightarrow$ |  |
| Resistance transmitter $\begin{aligned} & \text { A = Start } \\ & \text { E = End } \\ & \text { S = Slider } \end{aligned}$ |  |  | $2$ |

## 4 Electrical connection

### 4.3.3 Analog outputs

One analog output can be added to output OUT 3/4 to 11/12 using optional boards

| Connection | (Connection ele- <br> ment) <br> Input | Symbol and terminal designation |  |
| :--- | :--- | :--- | :--- |
| One analog output <br> DC $0 / 2$ to 10 V or DC 0/ <br> 4 to 20 mA <br> (configurable) | (8) OUT3/4 <br> (9) OUT5/6 | $+\cdots$ |  |

### 4.3.4 Digital inputs

Input IN1 to 7 as standard (cannot be extended)

| Connection | (Connection ele- <br> ment) <br> Input | Symbol and terminal designation |
| :--- | :--- | :--- |
| Digital input, potential-free <br> contact <br> as standard | (15) IN1 to 7 |  |

### 4.3.5 Digital outputs

## OUT1 and OUT2 as standard

The controller is fitted with two relay outputs (changeover contacts) as standard.

| Connection | (Connection <br> element) <br> Output | Symbol and terminal designation |  |
| :--- | :--- | :--- | :--- |
| Relay output (changeover <br> contact) | (6) OUT2 <br> (7) OUT1 |  |  |

## 4 Electrical connection

Outputs OUT 3/4 to 11/12 can be extended using the following optional boards

| Connection | (Connection element) Output | Symbol and terminal designation |
| :---: | :---: | :---: |
| 1 relay output (changeover contact) | (8) OUT3/4 <br> (9) OUT5/6 <br> (10) OUT7/8 <br> (11) OUT9/10 <br> (12) OUT11/12 |  |
| 2 relay outputs (N/O contact) ${ }^{1}$ |  |  |
| 1 solid state relay AC $230 \mathrm{~V}, 1 \mathrm{~A}$ |  |  |
| 1 logic output DC 0/22 V max. 30 mA (short-circuit proof) |  | $U_{x}, I_{x}$ |
| 2 logic outputs <br> DC 0/12 V max. 20 mA <br> (short-circuit proof, not galvanically isolated from each other) |  |  |
| 2 PhotoMOS® relays ${ }^{2}$ max. DC $50 \mathrm{~V}, 200 \mathrm{~mA}$ max. AC $35 \mathrm{~V}, 200 \mathrm{~mA}$ (galvanically isolated) |  |  |

## 4 Electrical connection


${ }^{1}$ Combining a mains voltage circuit with a protective low-voltage circuit on a 2-way normally open contact option is not admissible.
${ }^{2}$ PhotoMOS is a registered trademark of Panasonic Corporation.

### 4.3.6 Digital outputs

## Standard

Two relay outputs (changeover contact)
Switching capacity
Contact life

3 A at AC 250 V , resistive load 150,000 operations at rated load

Per optional board

| One relay output (changeover contact) <br> Switching capacity <br> Contact life | 3 A at AC 250 V resistive load 150,000 operations at rated load |
| :---: | :---: |
| Two relay outputs (N/O contact) ${ }^{1}$ <br> Switching capacity <br> Contact life | 3 A at AC 250 V , resistive load 150,000 operations at rated load |
| One solid state relay <br> Switching capacity <br> Protection circuitry | 1 A at AC 230 V , resistive load Varistor |
| 1 logic output (voltage supply for transmitter) | DC 0/22 V max. 30 mA (short-circuit proof) |
| 2 logic outputs | DC 0/12 V max. 20 mA (short-circuit proof, not galvanically isolated) |
| 2 PhotoMOS® relays ${ }^{2}$ | DC 50 V , max. 200 mA , (galvanically isolated from each other, not short-circuit proof) <br> AC 35 V , max. 200 mA , (galvanically isolated from each other, not short-circuit proof) |

${ }^{1}$ Combining a mains voltage circuit with a protective low-voltage circuit on the "dual normally open contact" option is not permissible.
${ }^{2}$ PhotoMOS is a registered trademark of Panasonic Corporation.

## 4 Electrical connection

### 4.3.7 Voltage supply (according to nameplate)

AC 230V (DC 24V)


### 4.3.8 Interfaces

USB device, USB host and COM1 interfaces as standard

| Connection | (Connection element) | Symbol and terminal designation |
| :---: | :---: | :---: |
| USB device interface (setup) | (21) |  |
| USB host (firmware update) | (20) | - |
| COM1 serial interface RS485 (galvanically isolated) | (13) | 1 TxD+/RxD+ Transmission/ <br> 2 TxD-/RxDreceived data + Transmission/ received data - |

COM2 interface can be expanded using optional boards

| Connection | (Connection element) | Symbol and terminal designation |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Ethernet | (14) |  | $\begin{aligned} & 1 \mathrm{TX}+ \\ & 2 \mathrm{TX}- \\ & 3 \mathrm{RX}+ \\ & 6 \mathrm{RX}- \end{aligned}$ | Transmission data + <br> Transmission data - <br> Received data + <br> Received data - |
| Serial interface RS422 (galvanically isolated) |  |  | $\begin{aligned} & 1 \text { RxD+ } \\ & 2 \text { RxD- } \\ & 3 \text { TxD+ } \\ & 4 \text { TxD- } \end{aligned}$ | Received data + <br> Received data - <br> Transmission data + <br> Transmission data - |
| Serial interface RS485 (galvanically isolated) |  |  | $\begin{aligned} & 3 \text { TxD+/RxD+ } \\ & 4 \text { TxD-/RxD- } \end{aligned}$ | Transmission/ received data + Transmission/ received data - |
| PROFIBUS-DP |  |  | 3 RxD/TxD-P <br> (B) <br> 5 DGND <br> 6 VP (+5 V) <br> 8 RxD/TxD-N <br> (A) | Transmission/ received data + Ground Voltage supply Transmission/ received data - |

## 4 Electrical connection

### 5.1 Display and operating concept

The DICON touch is operated via a resistive touchscreen and also reacts to finger pressure. Commercially available pens with plastic tips can also be used.


## 5 Operation

### 5.2 Device menu

All the functions in the device menu are described in the following sections of the B703571.0de operating manual.


### 5.3 Alarm and event list

In these lists, alarms and events appear that are partly confirmed.
Additional entries can be configured to appear in the lists.
$\Rightarrow$ B 703571.0-Chapter 12.9.5 "Alarm", page 105
$\Rightarrow$ B 703571.0-Chapter 12.5.1 "Alarms", page 76


### 5.4 Function buttons, history and channel changeover

Both these function buttons are set and configurable by default at "Operating level" and "Home" (back to Main view).
$\Rightarrow$ B 703571.0-Chapter 12.10.1 "General configuration", page 106
The "History"(H) and "Channel changeover"(Ch) buttons enable navigation in the recorder image and change their meaning according to the dialog.
$\Rightarrow$ Chapter 5.5.4 "Recording image", page 40

## 5 Operation

### 5.5 Images in the operating loop

## Start screen

After switch-on, the globe appears until the device software is started up.


Then Controller screen 1 appears (default setting).
Using the icon in the bottom right-hand corner, all the images defined in the operating loop can be called up one after another.
$\Rightarrow$ For the screen settings see B 703571.0-Chapter 12.10 "Screen", page 106
$\Rightarrow$ To view the images displayed see B 703571.0 - Chapter 12.10.4 "Operating loop", page 108

### 5.5.1 Controller screen 1, Controller screen 2 and Controller overview

You can change the color of these screens in the setup program.
The basic structure cannot be changed however.
default
Fixed-setpoint controller and Controller 1 are set up.
In order to function properly, the controller requires an actual value, a setpoint value, and an output to influence the actual value (for example, a heat source via a relay as a two-state controller). Self-optimization can only detect new parameters using a closed control loop.
$\Rightarrow$ Chapter 12.6.3 "Self-optimization controller", page 82


If lines or arrows appear, check the configuration or the connection.
$\Rightarrow$ Chapter 16 "Error and alarm messages", page 165
Enter setpoint values on the device for the fixed-setpoint controller
$\Rightarrow$ Chapter 11.4 "Setpoint values", page 62
Enter setpoint values for the fixed-setpoint controller with the setup program
$\Rightarrow$ Chapter 11.4 "Setpoint values", page 62

## 5 Operation

## Start manual mode

In manual mode, the controller is fixed at a particular output level. First of all, the screens show the active controller, where the output is at approx. $40 \%$.

| Step | Activity |
| :---: | :---: |
| 1 | Touch the hand symbol (pencil appears at output level display) |
| 2 | Touch the pencil, enter the manual output level and confirm (green arrow) |
| 3 | The controller operation is interrupted and Controller 1 is now working with a fixed output level of $20 \%$ (the hand symbol appears next to the green setpoint value). You can view the difference between the fixed-setpoint controller and the program controller at the automatic operation icon in the top right-hand corner. The green setpoint value continues, as programmed. |

$\Leftrightarrow$ You can now manually influence the output level (by hand)

## Exit manual mode

By touching the screen below the hand, you can exit manual mode and return to normal controller operation.

## Self-optimization

$\Rightarrow$ B 703571.0- Chapter 12.6.3 "Self-optimization controller", page 82

### 5.5.2 Program controller

## NOTE!

i
This screenshot is not available by default and only appears if the extra code for the program controller is enabled and configured.
$\Rightarrow$ Chapter 2.1 "Order details", page 14
default
There are no programs available. The following options are available for ordering a program:


## Enter setpoint curves on the device

$\Rightarrow$ Chapter 8.1.1 "On the device", page 47

## Enter setpoint curves using the setup program

$\Rightarrow$ Chapter 8.1.2 "About the setup program", page 48

## Start, Stop

The black arrow starts an available program. A request appears asking which program should be started and the programmed setpoint curves are then synchronized for both controller channels. The symbol for automatic operation appears in the center. Touching the black rectangle stops the program, adopting the conditions prior to the program starting.

## Pause

Pauses the time base of a program in operation, whereby the current setpoint values and the conditions of the control contacts are maintained. Touching the pause button again resumes program operation.

## Next section, previous section

The program in operation jumps to the next or previous section.

## Temporary alteration

Allow one-time changes to the setpoint values for a program without storing it permanently in the program table. When you next run the program, the original setpoint values will be reactivated.

Start/stop manual mode (for program controller)
Manual mode is performed exactly as for a fixed-setpoint controller.
$\Rightarrow$ Chapter 5.5.1 "Controller screen 1, Controller screen 2 and Controller overview", page 37

## Self-optimization

$\Rightarrow$ B 703571.0- Chapter 12.6.3 "Self-optimization controller", page 82

## 5 Operation

### 5.5.3 General screen 1.2

default
Two general screens are available that do not contain any variables.


The variables displayed can be configured.
$\Rightarrow$ B 703571.0- Chapter 12.10.8 "General screens 1, 2", page 112

### 5.5.4 Recording image

default
Here the device is displaying up to four analog and three digital channels, like a line recorder. Extra code 213 is required for data to be recorded and evaluated.


You can view historical data (from previous recordings) with the H button and switch channels with the CH button. If the channels displayed are configured, the screen must still be active for the operating loop display.
$\Rightarrow$ B 703571.0 - Chapter 12.11 "Recording", page 113

## 5 Operation

### 5.5.5 Process screen

default
This screen can be freely configured and is empty by default. A background image of your plant can be stored and animated with all the process values for the device.


The setup program is required to design the graphics.
$\Rightarrow$ B 703571.0 - Chapter 13.11 "Process screen", page 129

## 5 Operation

## 6 Login

Some of the levels in the device menu are username- and password-protected. The level protection is defined in the user list by the setup program, using five different users. On entering the password, each user is entitled to use the "rights" available.



If permitted, the rights and passwords can also be changed on the device.


Touching the screen in the bottom left-hand corner opens the device menu window. Touching the 'Login' function opens the Login window.

### 6.1 Logging on

This sequence shows the logon process as the master user (with the default password 9200):


User 1 is now logged on and is permitted to access all functions listed under "Rights".

### 6.2 Logging out

As soon as you are logged on, the Log-Out button is no longer grayed out and touching it will enable you to log out. Consequently, your user rights will be limited.


### 6.3 Changing the password

You can change the user password that you are currently logged in with here.
To do this, you must first enter the old password (for the master user) and then the new one. If the password is incorrect, the change will not be accepted.


## 7 User level (Log-In)

## NOTE!

This level is empty by default and parameters can only be defined using the setup program to appear in the device.

Up to 25 parameters of any type from the configuration or parameter level can be included in this level. These parameters, for example, often need to be changed or made available to operating personnel.

## Only setup > User level

## Setup dialog

| User level |  |  |  | $x$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | Description | Limit value mi... | Limit value m... |  | - |
| 1 Configuration selector \Setpoint values)Controlle... | Setpoint value 1 | -99999.0 | 85.0 |  |  |
| 2 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 3 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 4 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 5 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 6 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 7 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 8 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 9 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 10 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 11 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 12 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 13 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 14 Configuration selector Wo selection |  | 0 | 100 |  |  |
| 15 Configuration selector Wo selection |  | 0 | 100 |  | - |
| Edit |  |  | OK | Cancel |  |

### 7.1 Example 4 Transferring controller setpoint values to the user level

The four reversible controller setpoint values should be transferred to the user level. Doubleclicking on the empty entry opens the selector window.

## Setup dialog



## 7 User level (Log-In)

## Device display

Once the setup data has been transferred to the device, the setpoint values can be entered on the device.

| User level |  |
| :---: | :---: |
| OK | XCancel |
| Setpoint value 1 | $+33,000^{\circ} \mathrm{C}$ |
| Setpoint value 2 | $+20,000^{\circ} \mathrm{C}$ |
| Setpoint value 3 | $+55,000^{\circ} \mathrm{C}$ |
| Setpoint value 4 | $+101,00^{\circ} \mathrm{C}$ |

### 8.1 Enter program curves

Ten programs can be entered on the device or in the setup program.

### 8.1.1 On the device

| Step | Activity |
| :---: | :---: |
| 1 | Enter program names and icons |
| 2 | Enter first section: <br> If the program memory is empty, the section will be highlighted in red. <br> Each section consists of: target values 1 and 2 , section time, control contacts, tolerance band, number of repetitions from start section, and parameter block. |
| 3 | Repeat section entries until the table is complete |
| 4 | Touching the pencil symbol enables additional editing functions. <br> - Editing the program header <br> - Copying and deleting the program <br> - Creating a new section |

$\Leftrightarrow$ Two program curves have now been programmed.
They can be started at any section at an adjustable time and run in parallel.

## 8 Program administration

### 8.1.2 About the setup program

| Step | Activity |
| :---: | :---: |
| 1 | Start the setup program and click on Program editor > Program administration in the menu |
| 2 | Enter sections in the table |
| 3 | The table is displayed as a graphic with the program simulation |

## 8 Program administration

| Step | Activity |
| :---: | :---: |
| 4 | Save the setup file and transfer the setup data to the device |
| 5 | If a green icon (smiley) appears, then the programs have been successfully transferred. |

$\Rightarrow$ Two program curves are now saved in the device and can be started at any section at an adjustable time and run in parallel.

### 8.1.3 Section run time

The period of time between sections.
Setpoint values varying from section to section create a ramp-like setpoint curve (with a negative or positive slope).

### 8.1.4 Setpoint values 1 and 2

Each program contains 2 setpoint value profiles which can be used to create 2 program controllers.

### 8.1.5 Control contacts

Eight control contacts can be set at any one time. They are available in the digital selector and can switch on relays, for instance.
$\Rightarrow$ Setup program:
Configuration level > Digital outputs


They can also be logically linked or can initiate internal device functions.

## 8 Program administration

### 8.1.6 Tolerance band

$\Rightarrow$ B 703571.0 - Chapter 12.6.7 "Ramp function", page 95

### 8.1.7 Number of repetitions

The number of repetitions is entered for a specific start section.

### 8.1.8 Start section

Repetition begins from this section.

## Example



### 8.1.9 Parameter block

For each controller channel, parameter blocks 1 to 4 are available and can be switched in any combination

## 9 Device information

The device information function enables hardware and software modules to be displayed.

### 9.1 General information

The type extra codes enabled in the device are displayed next to the device names.


### 9.1.1 Version, motherboard, Ethernet information

Software version, fabrication number, and testing ID are displayed.
Displays the hardware on the motherboard.
MAC address, IP address, gate address, DNS address, and transfer rate.



### 9.2 Slots

Assignment of expansion slots is displayed in the device.


### 9.3 Inputs/outputs

The switching statuses and measurement values are displayed here.

## 9 Device information

9．3．1 Digital and analog inputs，digital and analog outputs，external digital， and external analog inputs


## 9．4 Functions

9．4．1 Mathematics，logic signal，limit value outputs

| Functions |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Mathematics |  | Logic sig |  | ， |
| No． | Mathematics | No． | Mathema |  |
| 1 | ＜＜＜＜＜ | 5 | く＜＜＜＜ |  |
| 2 | ＜＜＜＜＜ | 6 | く＜＜＜＜ |  |
| 3 | くくくくく | 7 | くくくくく |  |
| 4 | ＜＜＜＜＜ | 8 | く＜＜＜＜ |  |
| 13／03／04 | $\begin{array}{r\|c\|} \hline 01: 37: 05 & - \\ 678 & - \\ \hline \end{array}$ |  |  | 5 |


| Functions |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Logic signal |  | Limit value c |  |  |  |  |
| No．． | Logic signal | No．． | Logic signal |  |  |  |
| 1 | 0 | 5 | 0 |  |  |  |
| 2 | 0 | 6 | 0 |  |  |  |
| 3 | 0 | 7 | 0 |  |  |  |
| 4 | 0 | 8 | 0 |  |  |  |


| Functions |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Limit value outputs |  |  | Timer sig | 4 |
| No． | Output | No．． | Output |  |
| 1 | 0 | 9 | 0 |  |
| 2 | 0 | 10 | 0 |  |
| 3 | 0 | 11 | 0 |  |
| 4 | 0 | 12 | 0 |  |
| 5 | 0 | 13 | 0 |  |
| $13 / 03 / 04$ | $\begin{array}{r} 01: 39: 12 \\ 678 \end{array}$ |  |  |  |

## 9 Device information

### 9.4.2 Timer signal, digital controller signals, control contacts, controller, analog flag, digital flag

| Functions |  |  |  |  |  | Functions |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Timer signals |  | Digital contro |  |  | - | Digital control signals |  | Control oc 4 |  |  | - |
| No. | Timer run time | Timer output |  |  |  | No. | Output | No. | Outpu |  |  |
| 1 | 00:00:00 | 0 |  |  |  | 1 | 0 | 5 | 0 |  |  |
| 2 | 00:00:00 | 0 |  |  |  | 2 | 0 | 6 | 0 |  |  |
|  |  |  |  |  |  | 3 | 0 | 7 | 0 |  |  |
|  |  |  |  |  |  | 4 | 0 | 8 | 0 |  |  |
| $\overline{13 / 03 / 04}$ |  |  |  |  | 5 | 13/03/04 | 02:03:25 $678 \times 5$ |  |  |  | $5 \sqrt{5}$ |
| Functions |  |  |  |  |  | Functions |  |  |  |  |  |
| Control contact |  | Control |  |  | , | Controller |  | Analog f |  |  | - |
| No. | Control contact | No.. Pontrol contact |  |  |  | Oontroller Parameter set |  |  | letpoint value: |  |  |
| 1 | 0 | 5 | 0 |  |  |  | 1 |  | 1 |  |  |
| 2 | 0 | 6 | 0 |  |  |  | 1 |  | 1 |  |  |
| 3 | 0 | 7 | 0 |  |  |  |  |  |  |  |  |
| 4 | 0 | 8 | 0 |  |  |  |  |  |  |  |  |
| 13/03/04 | $\begin{array}{\|c\|c\|} \hline 02: 0413 \\ 678 & =\leq \\ \hline \end{array}$ |  |  |  | 5 | 13/03/04 | $\begin{array}{\|c\|c\|} \hline 02: 05: 23 \\ 67 x & =\mathrm{S} \\ \hline \end{array}$ |  |  |  | 51. |
| Functions |  |  |  |  |  | Functions |  |  |  |  |  |
| Analog flag |  | Digital f |  |  | - | Digital flag |  | 1 |  |  | - |
| No. | Analog flag | No.. Analog flag | Analog flag |  |  | No.. Digital flag No.. ${ }^{\text {N }}$ Digital flag |  |  |  |  |  |
| 1 | 0.0000 | 5 | 0.0000 |  |  | 1 | 0 | 5 | 0 |  |  |
| 2 | 0.0000 | 6 | 0.0000 |  |  | 2 | 0 | 6 | 0 |  |  |
| 3 | 0.0000 | 7 | 0.0000 |  |  | 3 | 0 | 7 | 0 |  |  |
| 4 | 0.0000 | 8 | 0.0000 |  |  | 4 | 0 | 8 | 0 |  |  |
| $13 / 03 / 04$ $02: 05: 58$  <br>  678 -C |  |  |  |  | $5{ }_{5}$ | $13 / 03 / 04$ $02: 00: 36$ <br>  678 |  |  |  |  | $5 \sqrt{5}$ |

### 9.5 Status

### 9.5.1 Ethernet status 1 to 9



## 9 Device information

### 10.1 General information

## NOTE!

The functional level is faded out by default and must be activated using the setup program.

### 10.1.1 Activate functional level

The functional level is activated in the screen menu and subsequently appears in the device menu.
$\Rightarrow$ Chapter 12.10 "Screen", page 106


The functional level is used primarily for testing and diagnostic purposes. Analog and binary values of the outputs can be controlled manually here. This may be useful, for instance, for checking an individual piece of equipment in a plant. For maintenance and repair works, for example, the timer, ramp function, and limit value monitoring can be operated and switching operation can be acknowledged.

## Example for the timer



## 10 Functional level

## 11 Parameterization

## NOTE!

The parameters described in this section can be entered either in the setup program or in DICON touch. This is where the parameters that are directly linked to the alignment of the controller with the control path are set, after the system has been commissioned.

You must be logged in to change the parameters.
$\Rightarrow$ Device menu section > Login
$\Rightarrow$ Chapter 7 "User level (Log-In)", page 45

## Setup dialog



| > MustKoff3_für englisch. 266 - altered - <br> - File-Info-Header <br> (3) Configuration level Parameter level <br> - Date and Time <br> - Parameter sets <br> - Setpoint values Setup only Program editor <br> - Program administration <br> - Program simulation Online parameters <br> - Fine adjustment <br> - Ethemet <br> - Date and time <br> - Screenshot <br> - Delete intemal measurement data। <br> - Enabling of extra codes <br> - Calibrating / Testing <br> - Different process value <br> - File-Info-Text |
| :---: |



### 11.1 Date and time

The following table shows the time settings for the device.

| Parameter | Setting | Description |
| :--- | :--- | :--- |
| Current date | $2011 / 01 / 01$ | Enter the date here. |
|  | $2083 / 12 / 31$ | Enter the time here. |
| Current time | $\mathbf{0 0 : 0 0 : 0 0}$ |  |

### 11.2 Daylight saving time

The following table shows the settings for daylight saving time.

| Parameter | Setting | Description |
| :--- | :--- | :--- |
| Synchronization | No function <br> Digital selector | A digital signal can be selected here to syn- <br> chronize the time. |
| Switch daylight saving time | Automatic <br> Inactive | Enables you to set the time to change auto- <br> matically. |

## 11 Parameterization

| Parameter | Setting | Description |
| :--- | :--- | :--- |
| Start DST | Month: March <br> Week: last week <br> Day: Sunday <br> Time: 02:00:00 |  |
| End DST | Month: October <br> Week: last week <br> Day: Sunday <br> Time: 03:00:00 |  |

### 11.3 Controller/parameter blocks

## Setup dialog



The following table shows the parameters in a parameter block. These parameters are also available for the other three parameter blocks. Two parameter blocks can be defined for each of the two controller channels. Switching the parameter blocks is performed separately for each controller channel via a digital signal.
Depending on the controller type configured, certain parameters may be omitted or ineffective. Parameters that appear in pairs such as Proportional band 1 and 2 refer to the first and second controller outputs (for instance, with three-state controllers).
The parameter blocks are assigned to both controllers in the configuration level.
$\Rightarrow$ B 703571.0 - Chapter 12.6.2 "Controller inputs", page 80

## 11 Parameterization

| Parameter | Setting | Description |
| :---: | :---: | :---: |
| $\begin{aligned} & \text { Proportional band } \\ & 1 \\ & (X p 1) \end{aligned}$ | 0 ... 9999 | Value for the proportional band The controller structure has no effect if $X p=0$ (behavior identical to limit value monitoring)! <br> For a continuous controller, Xp must be $>0$. |
| Proportional band <br> 2 <br> $(X p 2)$ | 0 ... 9999 |  |
| Derivative time 1 <br> (Tv1) | 0 ... 80 ... 9999 s | The derivative time influences the differential component (D component) of the controller output signal. |
| Derivative time 2 (Tv2) | 0 ... 80 ... 9999 s | The greater the derivative time, the more effect the D component has. |
| Reset time 1 <br> (Tn1) | 0 ... $350 . . .9999$ s | The reset time influences the integral component (I component) of the controller output signal. |
| Reset time 2 <br> (Tn2) | 0 ... $350 . . .9999$ s | The greater the reset time, the less effect the I component has. |
| Cycle time 1 <br> (Cy1) | 0 ... 20 ... 999.9 s | When using a switched output, the cycle time should be chosen so that the energy supply to the process is as continuous as possible without overloading the switching elements. |
| Cycle time 2 (Cy2) | 0 ... 20 ... 999.9 s |  |
| Contact spacing (Xsh) | 0 ... 999.9 | Spacing between the two control contacts for a three-state controller, modulating controller, and continuous controller with integrated position controller |
| Switching differential 1 <br> (Xd1) | 0 ... 1 ... 999.9 | Hysteresis for a switching controller with proportional band $\mathrm{Xp}=0$ |
| Switching differential 2 <br> (Xd2) | 0 ... 1 ... 999.9 |  |
| Actuator time (TT) | 5 ... $60 \ldots 3000$ s | Control valve running time range used for a modulating controller and continuous controller with integrated position controller |
| Working point (YO) | -100 to 0 to +100 \% | Working point correction for a P or PD controller (correction value for the output level) <br> If the actual value ( x ) has reached the setpoint value (w), the output level ( y ) corresponds to the working point (YO). |
| Max. output level limit <br> (Y1) | 0 to $100 \%$ | Admissible maximum output level (only effective if $X p>0$ ) |

## 11 Parameterization

| Parameter | Setting | Description |
| :--- | :--- | :--- |
| Min. output level <br> limit <br> (Y2) | $\mathbf{- 1 0 0}$ to $+100 \%$ | Admissible minimum output level (only <br> effective if $\mathrm{Xp}>0$ ) |
| Minimum relay <br> ON period 1 <br> (Tk1) | $\mathbf{0}$ to 60 s | Limits the frequency of switching for <br> switched outputs |
| Minimum relay <br> ON period 2 <br> (Tk2) | $\mathbf{0}$ to 60 s |  |

## 11 Parameterization

## Transmission behavior

The transmission behavior (controller structure) is determined by the configuration of the parameters for the proportion band ( P component), derivative time ( D component), and reset time (I component).

## Two-state controller

This controller has a switched output and can be parameterized with P, PI, PD, or PID transmission behavior. The proportional band Xp must be greater than 0 for the controller structure to take effect.
If $X p=0$, the behavior corresponds to the function of limit value monitoring with switching differential Xd1 (working point Y0 $=0 \%$ ):


Influence of working point YO on the switching behavior


$$
\text { YO = } 100 \%
$$


$Y 0=-100 \%$


## 11 Parameterization

## Three-state controller

This controller has two outputs, which can be configured as continuous (analog output) or switched (digital output). In both cases, the controller can be parameterized with P, PI, PD, or PID transmission behavior. The proportional bands Xp 1 and Xp 2 must be greater than 0 for the controller structure to take effect.
If $\mathrm{Xp} 1=0$ and $\mathrm{Xp} 2=0$, the behavior corresponds to the function of limit value monitoring with switching differential Xd 1 and Xd 2 , and contact spacing Xsh (working point $\mathrm{Y} 0=0 \%$ ):


## Modulating controller

This controller has two switched outputs and can be parameterized with PI or PID transmission behavior. The proportional band Xp must be greater than 0 for the controller structure to take effect.
The modulating controller is used for actuator drives with three switching statuses (actuator open, closed, hold). If output level feedback is available, the active output is deactivated when the output level limits are reached.

## Continuous controller

This controller has a continuous output (analog output) and can be parameterized with P, PI, PD, or PID transmission behavior. The proportional band Xp must be greater than 0 for the controller structure to take effect (the setting $X p=0$ is normally used in practice).

## Position controller

This controller is a continuous controller with integrated position controller and two switched outputs (digital outputs) with PI or PID transmission behavior.
The position controller is used for actuator drives with three switching statuses (actuator open, closed, hold). An output level feedback is required.

### 11.4 Setpoint values

Four switchable setpoint values are assigned to a fixed-setpoint controller and can be entered on the device or in the setup program.
The following table shows the setpoint changeover for fixed-setpoint controllers using two digital signals that can be Chapter 12.6.6 "Controller setpoint values", page 93 set.

## For program controllers

$\Rightarrow$ Chapter 8.1 "Enter program curves", page 47

## 11 Parameterization

| Type | Signal 2 (Bit 1) setpoint changeover | Signal 1 (Bit 0) setpoint changeover | Setpoint value, Controller 1 |  |  | Setpoint value, Controller 2 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Fixed-setpoint | 0 | 0 | Setpoint value 1 |  |  | Setpoint 1 |  |  |
| controller | 0 | 1 | Setpoint value 2 |  |  | Setpoint value 2 |  |  |
|  | 1 | 0 | Setpoint value 3 |  |  | Setpoint value 3 |  |  |
|  | 1 | 1 | Setpoint value 4 |  |  | Setpoint value 4 |  |  |
| Program controller |  |  | W1 and W2 are predefined by the program generator |  |  |  |  |  |
|  |  |  | JUMO TEST |  |  |  |  |  |
|  |  |  | OK |  | X Cancel |  | $8$ | - |
|  |  |  |  | W4 | W2 | Runtime | SK |  |
|  |  |  | 1 | 20,000 | 100,00 | 00:20:00 | 00000001 |  |
|  |  |  | 2 | 60,000 | 160,00 | 00:40:00 | 00000000 |  |
|  |  |  | 3 | 60,000 | 160,00 | 00:15:00 | 00000001 |  |
|  |  |  | 4 | 90,000 | 220,00 | 00:30:00 | 00000001 |  |
|  |  |  | 5 | 40,000 | 220,00 | 00:55:00 | 00000000 |  |

### 11.4.1 Entered on the device

The setpoint values in the parameter level are entered on the device.


### 11.4.2 Entered using the setup program

The setpoint values are entered in the setup dialog parameter level.


## 12 Configuration

## NOTE!

The parameters described in this section can be edited using either the setup program or DICON touch. The settings (for example, measured value recording, outputs, Ethernet, and controller type) that are required immediately for commissioning in a specific plant and therefore that seldom need to be changed, are set here.
Depending on the configuration, signals which are not in use are grayed out. Functions available in both selectors are highlighted in a specific color.

### 12.1 Analog selector

The analog selector contains all analog signals available in the configuration dialogs of a tree structure in the DICON touch.
All analog signals are shown in the following table. The entry in the "Type" column indicates the source of the signal:

- Internal: Internal signal for the DICON touch (including signals from the analog inputs)
- External: External input, for example, one that can be transmitted via an interface

| Category | Signal | Type | Description |
| :---: | :---: | :---: | :---: |
| No function |  |  | No signal selected |
| Analog inputs | Analog input (IN8) <br> Analog input (IN9) <br> Analog input (IN10) <br> Analog input (IN11) | Internal | Measured values for analog inputs 1 to 4 <br> $\Rightarrow$ Siehe 7312.5Analog inputs IN8, IN9, IN10, IN11 |
| External analog inputs | External analog inputs 1 to 8 | External | Analog value for the external analog input 1 to 8 <br> $\Rightarrow$ Siehe 13512.18External analog inputs |
| Mathematics | Mathematics 1 to 8 | Internal | Result of mathematical function 1 to 8 <br> $\Rightarrow$ Siehe 13012.15Mathematics/ logic |
| Controller 1 | Actual value for Controller 1 <br> Setpoint value, Controller 1 <br> Controller differential, Controller 1 <br> Output level display, Controller 1 <br> Output 1, Controller 1 <br> Output 2, Controller 1 <br> Cascade output level, Controller 1 | Internal | $\Rightarrow$ Siehe 7712.6.1Controller configuration |
| Controller 2 | Actual value, Controller 2 <br> Setpoint value, Controller 2 <br> Controller differential, Controller 2 <br> Output level display, Controller 2 <br> Output 1, Controller 2 <br> Output 2, Controller 2 <br> Cascade output level, Controller 2 |  |  |

## 12 Configuration

| Category | Signal | Type | Description |
| :--- | :--- | :--- | :--- |
| Setpoint values | Ramp end value, Controller 1 <br> Setpoint specification, Controller 1 <br> Setpoint value 1 to 4, Controller 1 <br> Ramp end value, Controller 2 <br> Setpoint specification, Controller 2 <br> Setpoint value 1 to 4, Controller 2 | Internal | Setpoint value for controller <br> channel 1 to 2 <br> as fixed setpoint controller <br> Siehe 9312.6.6Controller set- <br> point values |
| Program setpoint | Program setpoint 1, 2 | Internal | Setpoint value for controller <br> channel 1 to 2 <br> as program controller <br> $\Rightarrow$ Siehe 11612.12Program con- <br> troller |
| Section end val- <br> ues | Section end value 1 to 2 | Internal | Internal |
| Flags | Flags 1 to 8 | Analog value of the analog flag <br> Siehe 13212.16Flags/service |  |
| Service | Terminal temperature | Internal | Measured value (internal Pt100) |
| Sampling rate | Sampling rate | Internal | Measured value, sampling rate |

### 12.2 Digital selector

Digital selector

-     - Controller (4). Controler
(1). Digital inputs
(1)- Digital inputs
$\stackrel{\text { ( }+1-\text { - External digital inputs }}{\text { ( }+ \text { - Digital control signals }}$
(1). Digital control signals
(-). Limit value outputs
(1)- - - -imimer value
+!- Timer
(1)-Ramp signals
( $\oplus$ - Program controller
+     +         - Control contacts

The digital selector contains all digital signals that are available in the configuration dialogs of a tree structure in the DICON touch.
All the digital signals are shown in the following table. The entry in the "Type" column indicates the source of the signal:

- Internal: Internal signal for the DICON touch (including digital input signals)
- External: External value is transferred via the interface, for example

| Category | Signal | Type | Description |
| :--- | :--- | :--- | :--- |
| No function |  |  | No signal selected |

## 12 Configuration

| Category | Signal | Type | Description |
| :---: | :---: | :---: | :---: |
| Digital inputs | Digital input 1 to 7 | Internal | Logic level for connected floating contacts 1 to 7 <br> $\Rightarrow$ Siehe 7212.4Digital inputs IN1 to 7 |
| External digital inputs | External digital input 1 to 8 | External | Logic level for the external digital inputs 1 to 8 <br> $\Rightarrow$ Siehe 13412.17External digital inputs |
| Digital controller signals | Digital controller signals 1 to 8 | Internal | Logic level for the defined digital controller signals 1 to 8 <br> $\Rightarrow$ Siehe 12612.14Digital controller signals |
| Limit value outputs | Limit value output 1 to 16 | Internal | Logic level of the limit value monitoring 1 to 16 <br> $\Rightarrow$ Siehe 10012.9Limit value monitoring |
| Timer | Timer output 1 <br> Timerendsignal 1 <br> Timertoleranceband 1 <br> Timerstopsignal 1 <br> Timeroutput 2 <br> Timerendsignal 2 <br> Timertoleranceband 2 <br> Timerstopsignal 2 | Internal | Logic level of the output signals for Timer 1, 2 <br> Logic level "0", function inactive Logic level "1", function inactive <br> $\Rightarrow$ Siehe 12412.13Timer or time switch |
| Logic output | Logic output 1 to 8 | Internal | Result of logic function 1 to 8 $\Rightarrow$ Siehe 13012.15Mathematics/ logic |
| Ramp signals | Rampendsignal 1 <br> Tolerancebandsignal 1 <br> Rampendsignal 2 <br> Tolerancebandsignal 2 | Internal | Logic level " 0 ", function inactive Logic level "1", function inactive $\Rightarrow$ Siehe 9512.6.7Ramp function |
| Program controller | Program end signal <br> Programautosignal <br> Tolerancebandsignal <br> Programstopsignal | Internal | Logic level " 0 ", function inactive Logic level "1", function inactive $\Rightarrow$ Siehe 11612.12Program controller |
| Control contacts | Control contacts 1 to 8 | Internal | Logic level of the control contacts, for example in automatic mode. <br> $\Rightarrow$ Siehe 498.1.5Control contacts |
| Flags | Digital flags 1 to 8 | Internal | Logic level of the digital flag $\Rightarrow$ Siehe 13212.16Flags/service |
| Service | Service signal | Internal | Logic level of the service signal $\Rightarrow$ Siehe 13212.16Flags/service |

12 Configuration

| Category | Signal | Type | Description |
| :---: | :---: | :---: | :---: |
| Function buttons | Function button 1 to 2 | Internal | Logic level of the two function buttons <br> $\Rightarrow$ Siehe 355.1Display and operating concept |
| Analog input alarm | MinAlarm IN8 <br> MaxAlarm IN8 <br> MinAlarm IN9 <br> MaxAlarm IN9 <br> MinAlarm IN10 <br> MaxAlarm IN10 <br> MinAlarm IN11 <br> MaxAlarm IN11 | Internal | Min and max alarm signals of the analog inputs 1 to 4 <br> $\Rightarrow$ Siehe 7312.5Analog inputs IN8, IN9, IN10, IN11 |
| Ext. analog entry alarm | MinAlarm Ext. AE 1 <br> MaxAlarm Ext. AE 1 MinAlarm Ext. AE 2 MaxAlarm Ext. AE 2 MinAlarm Ext. AE 3 MaxAlarm Ext. AE 3 MinAlarm Ext. AE 4 MaxAlarm Ext. AE 4 MinAlarm Ext. AE 5 MaxAlarm Ext. AE 5 MinAlarm Ext. AE 6 MaxAlarm Ext. AE 6 MinAlarm Ext. AE 7 MaxAlarm Ext. AE 7 MinAlarm Ext. AE 8 MaxAlarm Ext. AE 8 | Internal | Min and max alarm signals for the ext. analog inputs 1 to 8 <br> $\Rightarrow$ Siehe 13512.18External analog inputs |
| Math alarm | MinAlarm Math 1 MaxAlarm Math 1 MinAlarm Math 2 MaxAlarm Math 2 MinAlarm Math 3 MaxAlarm Math 3 MinAlarm Math 4 MaxAlarm Math 4 MinAlarm Math 5 MaxAlarm Math 5 MinAlarm Math 6 MaxAlarm Math 6 MinAlarm Math 7 MaxAlarm Math 7 MinAlarm Math 8 MaxAlarm Math 8 | Internal | $\Rightarrow$ Siehe 13012.15Mathematics/ logic |

## 12 Configuration

| Category | Signal | Type | Description |
| :---: | :---: | :---: | :---: |
| Digital alarms | Digital alarm 1 to 7 | Internal | Alarms for connected floating contacts 1 to 7 <br> $\Rightarrow$ Siehe 7212.4Digital inputs IN1 to 7 |
| Ext. digital alarms | Ext. digital alarm 1 to 8 | External | Alarms for ext. digital inputs $\Rightarrow$ Siehe 13412.17External digital inputs |
| Digital control alarms | Digital control alarm 1 to 8 | Internal | Alarms for the defined digital controller signals 1 to 8 <br> $\Rightarrow$ Siehe 12612.14Digital controller signals |
| Limit value alarms | Limit value alarm 1 to 16 | Internal | Alarms for the limit value monitoring 1 to 16 <br> $\Rightarrow$ Siehe 10012.9Limit value monitoring |
| Logic alarms | Logic alarms 1 to 8 | Internal | Alarms for logic function 1 to 8 $\Rightarrow$ Siehe 13012.15Mathematics/ logic |
| Alarms and internal signals | Collective alarm | Internal | Collective alarm for the controller |
|  | Collective alarm acknowledged |  |  |
|  | Memory alarm |  | Memory alarm limit exceeded $\Rightarrow$ Siehe 7012.3Basic settings |
|  | Fault |  |  |
|  | Field bus error |  |  |
|  | Battery empty |  | Back-up battery must be replaced |
|  | Pre-alarm battery |  | Back-up battery voltage under 2.6 V |
|  | Login |  | Logic level "0", user not logged on <br> Logic level "1", user logged on |
|  | USB inserted |  | Logic level "0" USB not inserted Logic level "1", USB inserted |
|  | Temp. in Fahrenheit |  | Logic level " 0 ", temp. not ${ }^{\circ} \mathrm{F}$ Logic level "1", temp. in ${ }^{\circ} \mathrm{F}$ |
|  | Inside temperature too high |  | Logic level " 0 ", inside temperature not too high <br> Logic level "1", inside temperature too high |

## 12 Configuration

### 12.3 Basic settings

The settings are applicable for the entire device.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Device name | Name | 20 characters of editable text |
| Language | 1.German 2.English | The device can save up to two languages. Additional languages can only be added using the setup program: Edit > SETUP ONLY > COUNTRY SETTINGS. <br> $\Rightarrow$ Chapter 13.3 "Country settings", page 122 |
| Language selection after "power on" |  |  |
| \& | Not selected (empty); no Selected () ); yes | The device starts without language selection <br> The language selection appears |
| Supply frequency | $\begin{aligned} & 50 \mathrm{~Hz} \\ & 60 \mathrm{~Hz} \end{aligned}$ |  |
| Temp. of device | Deg. Celsius Deg. Fahrenheit | Temperature unit for displaying the temperature in the device |
| Temp. of interface | Deg. Celsius Deg. Fahrenheit | Temperature unit for displaying the temperature values using the interface |
| Read out data using: (only setup) | Interface USB | Secure recording data using the interface Secure recording data on the stick $\Rightarrow$ Chapter 12.11 "Recording", page 113 |
| Memory alarm limit (in the device) | 0 to 20 \% to 100 \% | If the enabled memory data recorder does not reach this limit in the device, an alarm will be issued. |
| Setup quick info | - | Any text may be transferred to the device during the data transfer. |

## 12 Configuration

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Online version vis. <br> (only setup) | Standard online visualization | Software version of the webserver soft- <br> ware |
|  | No online visualization |  |
|  | Example 333.01.01-13 | If relevant, additional versions are listed <br> that can be selected in the version library <br> and can be specifically selected for the <br> software update. |
| Comparison criteria <br> (only setup) | Compatible <br> Equal to or greater than | Setup software<->device software |
| Software version <br> (only setup) | Standard software | The device software version is available <br> here |

## Language selection after power ON

This setting means that language selection appears following "power on", which gives the user the opportunity to select their preferred language.


## Memory alarm limit

If $20 \%$ of the enabled memory is not used during recording, for example, an entry will be made in the alarm list. This enables the user to recover the recording data using the USB stick or the interface (as indicated).
The value of the free memory only returns to $100 \%$ when the data has been recovered. If the remaining $20 \%$ is used up, the oldest recorded data is overwritten and replaced with the new data. In this case, there will be a recording gap.

## 12 Configuration

### 12.4 Digital inputs IN1 to 7

A maximum of seven digital inputs (IN 1 to 7 ) are available for connecting to floating contacts with a common ground.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Channel description | Digital input 01 | (15 characters) of editable text that indicates, for example, what the signal will be used for. |
| Alarm type |  |  |
|  | Off | Alert switched off. |
|  | Alarm | A message will be entered in the alarm list depending on the signal level that has been set. |
|  | Event | A message will be entered in the events list depending on the signal level that has been set. |
| Polarity for alarm | Signal level that triggers an alarm or an event. |  |
| (only setup) | High <br> Low | Contact closed: high (logic "1") Contact open: low (logic "0") |
| Alarm text (only setup) | Digital input alarm 01 | 20 characters of editable text which is entered into the alarm or event list. |

## Polarity for alarm

An alarm is only displayed for as long as the signal level (closed contact) is also selected. If the contact is opened, the alarm entry disappears automatically.

## Alarm text

The setup program is required to view and edit the texts.

## 12 Configuration

### 12.5 Analog inputs IN8, IN9, IN10, IN11

Analog inputs IN8 and IN9 are installed by default as universal measuring inputs for RTD temperature probes, thermocouples, resistance transmitters/resistance potentiometers, and standard signals. Two additional analog inputs, IN10 and IN11, can be retrofitted.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Channel description | Analog input IN8, IN9, IN10, IN11 | (15 characters) of editable text |
| Probes | Selection of measuring probe for the relevant analog input |  |
|  | No function | No sensor selected |
|  | Res.three-wire | RTD temperature probe in three-wire circuit |
|  | Res.two-wire | RTD temperature probe in two-wire circuit |
|  | Int. thermocouple | Internal thermocouple Cold-junction temperature |
|  | Ext. thermocouple | External thermocouple Cold-junction temperature |
|  | Constant thermocouple | Constant thermocouple Cold-junction temperature |
|  | Resistance transmitter | Resistance transmitter |
|  | 0 to 20 mA | Standard signal |
|  | 0 to 10 V | Standard signal |
|  | 0 to 1 V | Standard signal |
|  | 0 ...to 100 mV | Standard signal |
|  | 4 to 20 mA | Standard signal |
|  | 2 to 10 V | Standard signal |


| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Linearization | Available options and default settings depend on the measuring probe selected. |  |
| RTD probe | Linear <br> Pt100 <br> Ni100 <br> Pt500 <br> Pt1000 <br> Ni1000 <br> Pt100J <br> Pt50 <br> Cu50 <br> KTY11-6 <br> Pt100 Gost <br> Pt50 Gost <br> Cu100 Gost <br> Cu50 Gost | DIN EN 60751 <br> DIN EN 60751 <br> DIN EN 60751 <br> DIN EN 60751 <br> JIS 1604 <br> GOST 6651-94 <br> GOST 6651-94 <br> Type KTY11-6 |
| Thermocouples | CRCopel Fe-CuNi L Gost Cu-CuNi T Fe-CUNi J Cu-CuNi U Fe-CuNi L NICr-Ni K Pt10Rh-Pt S Pt13Rh-Pt R Pt30Rh-Pt6Rh B NiCrSi-NiSi N NiCr-CuNi E W5Re-W26Re C W3Re-W25Re D In40-Rh Pt10Rh-Pt Customer-spec. 1 Customer-spec. 2 Customer-spec. 3 Customer-spec. 4 | Customer-specific linearization with 4th order polynomial |
| Unit | 5 characters (\%) | Unit for numerical representation of measured value |
| Decimal place | $\begin{aligned} & X X X X X . \\ & X X X X . X \\ & X X X . X X \\ & X X . X X X \\ & X . X X X X \end{aligned}$ | No decimal place <br> 1 decimal place <br> 2 decimal places <br> 3 decimal places <br> 4 decimal places |

12 Configuration

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Measured value offset <br> [1] | -100 to 0 to +100 | Parallel translation of all measured values |
| Measured value factor $\square$ | 1,000 | Slope |
| Filter time constant | 0 to 0.6 to 100 | Time constant for adjusting the digital input filter ( $0 \mathrm{~s}=$ filter off) |
| Start of scaling | Default setting depends on sensor and linearization. |  |
|  | -99999 to +99999 | Start value of display range for standard signals |
| Scaling end [1] | Default setting depends on sensor and linearization. |  |
|  | -99999 to +99999 | End value of display range for standard signals |
| Lead wire resistance | $0 \Omega$ | The lead wire resistance is entered here with a two-wire circuit. |
| Ext. compensation temperature | No selection Analog selector | The measurand used to record the coldjunction temperature is set here. |
| Fixed compensation temperature | 0 to 50 to $100{ }^{\circ} \mathrm{C}$ | If the cold junction has a fixed temperature, this is entered here. |
| $\begin{aligned} & \text { KTY } \\ & \text { at } 25^{\circ} \mathrm{C} / 77^{\circ} \mathrm{F} \end{aligned}$ | 0 to 2000 to $10000 \Omega$ | Basic resistance of a KTY probe at $20^{\circ} \mathrm{C}$ |
| Resistance measuring range | 0 to $400 \Omega$ <br> 0 to $4000 \Omega$ | The following measuring ranges are available for a customer-specific linearized resistance measurement |

## Linearization

Linearization is dependent upon the probe that is connected (measuring probe).
The predefined linearizations can be supplemented with customer-specific linearization.
$\Rightarrow$ Setup program:
Setup only > Customer-specific linearization

## Measuring value offset, measuring value factor

The value for the measuring value offset provides parallel translation of all measured values and the value for the measuring value factor influences the increase in the values displayed.

## Filter time constant

The filter time constant adjusts the digital input filter (2nd order filter). If the input signal changes suddenly, approx. $26 \%$ of the change is recorded following a period that corresponds to the filter time constant ( $2 \times$ filter time constant: approx. $59 \%$; $5 \times$ filter time constant: approx. $96 \%$ ). A large filter time constant means: high attenuation of interference signals, slow reaction to the actual value display, low limit frequency (low-pass filter).

## Scaling start, end

The maximum measuring range limits are displayed here, depending on the probe selected and the linearization. These limits only affect the recording. If, for example, the scaling end for a Pt 100 is reduced from $850^{\circ} \mathrm{C}$ to $400^{\circ} \mathrm{C}$, the recording only displays values up to $400^{\circ} \mathrm{C}$.

## 12 Configuration

## Lead wire resistance

On connecting a RTD temperature probe in a two-wire circuit, longer lines may lead to measuring errors. This value is used to compensate the resistance of the probe line and depends on the line length. Enter the ohmic resistance of the probe line here to achieve the best possible temperature measurement.

### 12.5.1 Alarms

Limit value monitoring with one or two alarms and various alarm types can be activated for each analog input. In addition, this function is required in order to trigger the collective alarm of the controller module if the event of deviation above or below the measuring range (out of range). This limit value monitoring is available in addition to the functions described in Chapter 12.9 "Limit value monitoring", page 100 and is independent of these.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| IN 8 Analog input 1, IN9 Analog input 2 | Monitoring is not active. <br> Alarm results in an entry in the alarm list. <br> Alarm results in an entry in the event list. |  |
| Minimum alarm | Off <br> Alarm <br> Event | Limit value at which an alarm is issued. |
| Minimum value | -99999 to 0 to +99999 | Text which is entered into the alarm or <br> event list in the event of deviation. |
| Minimum alarm <br> text | Underrange AE1 | Monitoring is not active. <br> Alarm results in an entry in the alarm list. <br> Alarm results in an entry in the event list. |
| Maximum alarm | Off <br> Alarm <br> Event | Limit value at which an alarm is issued. |
| Maximum value | -99999 to 0 to +99999 | Text which is entered into the alarm or <br> event list in the event of deviation. |
| Maximum alarm <br> text | Overrange AE1 |  |

## 12 Configuration

### 12.6 Controller1, 2

Two controllers (controller channels) are available. The parameters listed here can be configured independently of each other for controller 1 to controller 2.

### 12.6.1 Controller configuration

The controller type, the control direction, the output level for changeover to manual mode and for deviation above or below the measuring range, as well as the output level standardization and the deadband width are specified here.

## Setup dialog



## Parameter

| Parameter | Selection/settings ${ }^{\mathbf{1}}$ | Description |
| :--- | :--- | :--- |
| Controller 1, Controller 2 | Two-state controller | Controller channel is switched off <br> (default setting for Controller 2) <br> Controller with a switched output <br> (default setting for controller 1) <br> Controller with two continuous or switched outputs (for <br> example, for heating/cooling) <br> Controller with two switched outputs (for motor actuator) <br> Controller with a continuous output (analog signal) <br> Continuous controller with integrated position controller <br> (for motor actuator) |
| Three-state controller | Off | Modulating controller <br> Continuous controller <br> Position controller |
| Control direc- <br> tion <br> lad | Direct (2) | The controller output level is positive if the actual value <br> is greater than the setpoint value (cooling). |


| Parameter | Selection/settings ${ }^{1}$ | Description |
| :---: | :---: | :---: |
| Manual mode |  |  |
| [a] | Enabled Disabled | Manual mode possible on the device Manual mode disabled |
| Y in manual mode |  | Defines the output level (\%) that the controller should adopt after switching to manual mode. |
|  | Y manual mode Current value <br> Average value | The value set below for Y manual mode is adopted. <br> The current controller output level before switching to manual mode is adopted. <br> The average value calculated using the set time below is adopted. |
| Y with error |  | Defines the output level (in \%) that the controller should display, if one of the analog values relevant for the controller is invalid (incorrect actual value, setpoint value, output level feedback, etc). |
|  | Y substitute value Current value <br> Average value | The Y substitute value set below is adopted. <br> The current output level before deviation above or below the measuring range is adopted. <br> The average value calculated using the set time below is adopted. |
| Y manual mode | 0 to 100 \% |  |
| Y substitute value | 0 to 100 \% |  |
| Time for manual average value | 1 to 3600 min | Time for the average value when " Y in manual mode" average value is set |
| Time for substitute average value | 1 to 3600 min | Time for averaging of values if the " Y with error" average value is is set |
| Start of cascade standardization | 0 to 100 \% | The output level can be standardized here (only for cascade controllers). |
| End of cascade standardization | 0 to 100 \% |  |
| Deadband (neutral zone) [1] | 0.00 to 100 \% | Output level movements within the deadband are suppressed, for example by noisy signals. The deadband is only effective for controller structures with I-component. |
| Additional functions not selected (empty) |  |  |
| (only setup) | ( ) Expansion 1 | Reserved functions for service |
|  | () Expansion 2 |  |
|  | ( ) Expansion 3 |  |
|  | (1) Expansion 4 |  |

${ }^{1}$ Bold: default setting

## Control direction

Is set inversely by default (1) for heating mode.

## 12 Configuration



## Manual mode

If the setting is disabled, manual mode is not possible on the device and the button for manual mode will be grayed out.


Deadband
Default is 0 , i.e. no distance between heating and cooling contact.


## 12 Configuration

### 12.6.2 Controller inputs

The analog inputs for the controller are configured in this menu - including the signals for switching off the controller and switching on the parameter block - as well as the parameters for manual mode.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Controller 1, Controller 2 |  | IN8 analog input 1 <br> Analog selector |
| Controller actual value | Analog signal for actual value |  |
| Controller setpoint value | Setpoint specifica- <br> tion for Controller 1 <br> Analog selector | Analog signal for setpoint value |
| Output level feedback | No selection | Analog signal for output level feedback |
| Manual output level | Analog selector | Analog signal for manual output level |
| Additive variable disturbance |  | Analog signal for additive variable distur- <br> bance |
| Multiplicative variable distur- <br> bance |  | Analog signal for multiplicative variable <br> disturbance |

## 12 Configuration

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Manual signal/auto-switching | No selection Digital selector | This signal switches between manual mode and automatic mode. |
| Locking signal for manual mode |  | This signal locks manual mode |
| Signal 1 <br> Parameter block switching |  | The parameter blocks entered in the Chapter 11.3 "Controller/parameter |
| Signal 2 <br> Parameter block switching |  | blocks", page 58 are switched using both these signals. |
| Signal for actual value switching |  | The analog inputs (actual value inputs) are switched using this digital signal. |
| Controller signal off |  | The controller can be switched to On or |
| Controller signal on |  | Off using this signal. |

## Actual value switching

Provided that no signal is selected for switching the actual value, the actual values set from the analog selector for the controller configuration are active. If, however, a signal is set for switching the actual value, then the High signal level (logic "1"), is switched to the actual value outlined in red.
Controller 1 is then linked to IN9 (analog input 2) and Controller 2 to IN10 (analog input 3).


## 12 Configuration

### 12.6.3 Self-optimization controller

Self-optimization determines the optimum controller parameters for a PI or PID controller.

## Setup dialog



## Parameter

| Parameter | Selection/settings ${ }^{1}$ | Description |
| :---: | :---: | :---: |
| Method [1] | Oscillation Step response | Oscillation method Step response method |
| Lock | Enabled Disabled | Self-optimization can be started on the device Self-optimization is disabled |
| Exit type 1, 2 | Automatic <br> Relay <br> Solid state, logic analog | Output level is recognized automatically. Output level is displayed using the relay... ... using the solid state relay or digital signal... ... using the analog output. |
| Standby output | 0 to 100 \% |  |
| Output level for step method | 0 to 30 to $100 \%$ | Output level for step response level |
| Acquisition of switching period (Cy) | $\begin{aligned} & \text { Yes } \\ & \text { No } \end{aligned}$ | Cy is detected during self-optimization Cy is not detected |
| Signal start/stop | No selection Digital selector | Start/stop signal for self-optimization |
| Locking signal | No selection Digital selector | Signal for locking self-optimization |

${ }^{1}$ Bold: default setting

## Method

The standard method is the oscillation method, whereas the step response method is used specifically in the plastics industry.

With the oscillation method, the output level is set alternately to $100 \%$ and $0 \%$, which produces oscillation of the control variable. With the step response method, a step of a specified size is made from the standby output. In both cases, the controller determines the optimum controller parameters from the response of the actual value.
$\Rightarrow$ Chapter 12.6.3 "Self-optimization controller", page 82 and following pages
Optimization according to the oscillation method or Optimization according to the step response method

## Exit type 1, 2

The cycle time is calculated on the basis of the type of controller output.

## Optimized controller parameters

With both self-optimization methods, certain parameters are optimized according to the configured controller type and configured parameters. The controller structure is derived from the type of the optimized parameters: Proportional band Xp (P component), derivative time Tv ( D component), and reset time Tn (I component).
The cycle time Cy and the filter time constant dF are also optimized.

| Configured controller type | Configured parameter | Optimized parameter | Optimized controller structure |
| :---: | :---: | :---: | :---: |
| Two-state controller | $\begin{aligned} & \text { Xp1 = any; } \\ & \text { Tv1 }=0 ; \text { Tn1 > } 0 \end{aligned}$ | Xp1, Tn1, Cy1, dF | PI |
|  | All other settings | Xp1, Tv1, Tn1 Cy1, dF | PID |
| Three-state controller | $\begin{aligned} & \text { Xp1 = Xp2 = any; } \\ & \text { Tv1 = 0; Tn1 > } \end{aligned}$ | Xp1, Xp2, Tn1, Cy1, Cy2, dF | PI |
|  | All other settings | Xp1, Xp2, Tv1, Tn1, Cy1, Cy2, dF | PID |
| Modulating controller | $\begin{aligned} & \text { Xp1 = any; } \\ & \text { Tv1 }=0 ; \text { Tn1 > } 0 \end{aligned}$ | Xp1, Tn1, dF | PI |
|  | All other settings | Xp1, Tv1, Tn1, dF | PID |
| Continuous controller | $\begin{aligned} & \text { Xp1 = any; } \\ & \text { Tv1 }=0 ; \text { Tn1 > } 0 \end{aligned}$ | Xp1, Tn1, dF | PI |
|  | All other settings | Xp1, Tv1, Tn1, dF | PID |
| Position controller | $\begin{aligned} & \text { Xp1 = any; } \\ & \text { Tv1 }=0 ; \text { Tn1 > } 0 \end{aligned}$ | Xp1, Tn1, dF | PI |
|  | All other settings | Xp1, Tv1, Tn1, dF | PID |

For first-order control paths, the parameters required for the PI controller structure are optimized, independently of the configured parameters.

## Error handling

If the actual value deviates above or below the measuring range during self-optimization, selfoptimization is aborted. In this case, the configured parameters are not changed.

## WARNING!

During self-optimization according to the oscillation method, output level limits Y 1 and Y 2 are not active for switched outputs or solid state outputs.
The output level may exceed or fall below the set limits.
It must be ensured that this does not result in damage to the plant.

## 12 Configuration

## NOTE!

1
Optimization must be performed under genuine operating conditions and requires a closed control loop, whose actuator influences the actual value(heating controlled by relay output). It can be performed as many times as required.

## Start of self-optimization

Self-optimization can be started using any signal from the digital selector. Any other signal from the digital selector can be used to abort (stop) autotuning.

## Optimization according to the oscillation method

In the case of a large control deviation between the setpoint value and actual value (for example, in the startup phase), the controller determines a switching line around which the control variable performs a forced oscillation during self-optimization. The switching line is determined so that the actual value does not exceed the setpoint value if possible.
In the case of minor control deviation (for example, if the control loop is in a steady state during operation), oscillation is forced around the setpoint value. Here, the setpoint value is exceeded in any case.
The controller automatically chooses between two procedures depending on the extent of the control deviation:

Self-optimization during the startup phase $\quad$ Self-optimization during operation


x Actual value
w Setpoint value
S Switching line
t1 Start of self-optimization

## 12 Configuration

## Optimization according to the step response method

Initially, a configurable standby output is produced until the actual value "settles" to a constant. This is automatically followed by a configurable output level step (step size) to the control path. Main applications of the step response method:

- Optimization immediately after "power on" during startup (considerable time saving, standby output setting = 0 \%)
- Control path does not oscillate easily (for example, extremely well insulated furnace with low losses, long oscillation period)
- Actual value must not exceed setpoint value

If the output level is known for the corrected setpoint value, overshooting is prevented with the following setting:
Standby output + step size $\leq$ output level in corrected state
The progression of the output level and actual value depends on the status of the process at the point when self-optimization starts:

$\begin{array}{cl}\text { y } & \text { Output level } \\ \text { ys } & \text { Standby output } \\ \text { x } & \text { Actual value } \\ \text { w } & \text { Setpoint value }\end{array}$
$\Delta y$ Step size
t1 Start of self-optimization
t2 Point of output level step
t3 End of self-optimization

## 12 Configuration

## Checking the optimization

You can check for optimum adjustment of the controller to the control path by recording the startup process (with "Startup", for example) with a closed control loop. The diagrams below indicate possible incorrect adjustments and correction of these.
Here, the guiding behavior of a third-order control path for a PID controller is recorded as an example. The procedure for setting the controller parameters can also be applied to other control paths.


Reset time Tn and derivative time Tv too short


Proportional band Xp too small


Cycle time Cy too great


Optimum setting


## 12 Configuration

### 12.6.4 Control loop monitoring

Control loop monitoring monitors the control behavior during startup of a plant and in the event of a setpoint value step by analyzing the change of the actual value during an output level change. An alarm is issued if the actual value does not respond according to the specifications. The alarm signal is available from the digital selector and can be processed further at any time.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Function | Inactive | Control loop monitoring is generally not permitted |
|  | Active | Control loop monitoring is generally permitted | Response time | 0 to 1999 | Time period in which the actual value must leave the <br> monitoring band. <br> "0 s" setting means: <br> Response time $=$ reset time Tn |
| :--- | :--- |
| Monitoring band | 0.0000 to 1999 |
| Monitoring band width that must leave the actual value <br> within the response time <br> "0" setting means: <br> Monitoring band $=0.5 \times$ proportional band $(\mathrm{Xp})$ |  |

## 12 Configuration

## Description of the function

Monitoring starts as soon as the maximum output level is produced in heating mode (see example) or as soon as the minimum output level is produced in cooling mode. Starting from this point, the actual value must leave the monitoring band - the range around the current value at the start of monitoring - within the response time. If it is not, an alarm is triggered.
On leaving the monitoring band, the actual value at the time is used as a reference value for a new monitoring band. The response time starts over.
Monitoring ends as soon as the maximum or minimum output level is no longer produced.

x Actual value
y Output level
t1 Start of monitoring
t2 End of monitoring
$\Delta x$ Monitoring band
$y_{M}$ Max. output level (for example, 100 \%)
$\mathrm{T}_{\mathrm{R}}$ Response time

## 12 Configuration

If the actual value does not leave the monitoring band within this timeframe, an alarm signal is generated. The alarm signal is maintained for as long as the maximum or minimum output level is produced and the actual value is within the monitoring band.

x Actual value
$\Delta x$ Monitoring band
y Output level
$y_{M}$ Max. output level (for example, $100 \%$ )
t1 Start of monitoring
$\mathrm{T}_{\mathrm{R}}$ Response time
$\mathrm{T}_{\mathrm{A}}$ Alarm period
t2 End of monitoring

An alarm may be caused by:

- Partial or total failure of heating elements or other parts in the control loop
- Reversal of the control direction (for example, "cooling" instead of "heating")


## 12 Configuration

### 12.6.5 Output level monitoring

Output level monitoring monitors the output level in the corrected state. The output level must be within a definable range around a mean output level. If it is not, an alarm is issued.
The alarm signal is available from the digital selector and can be processed further at any time.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Lock | Inactive | Output level monitoring generally not permitted |
|  | Active | Output level monitoring generally not permitted |
| Determination time | 0 s to 350 s to 9999 s | Calculation time for the mean output level |
| Output level band | $0 \%$ to $10 \%$ to $100 \%$ | Monitored output level band (admissible range <br> around the mean output level) |
| Alarm delay | 0 s to 9999 s | Delay time for alarm triggering |
| Controller differential <br> band | 0 to 1 to 1999 | Controller differential band (admissible range <br> around the actual value in corrected state) |

## 12 Configuration

## Description of the function

Once the output level monitoring has been activated, determination of the mean output level starts as soon as the actual value is within the controller differential band. When the mean output level has been determined, the current output level must be within the monitored output level band. If it is not, an alarm is triggered.
In the event of a setpoint value change, the output level monitoring is temporarily deactivated until the actual value returns to the controller differential band. The mean output level is then determined again.


x Actual value
y Output level
$T_{D}$ Alarm delay
$\Delta x$ Controller differential band
$\Delta y$ Monitored output level band
$\mathrm{T}_{\mathrm{A}}$ Alarm period

## Application examples:

- Monitoring of signs of aging and faults on heating elements
- Reporting of faults during operation


## Functional limitations

Output level monitoring is not active in the following cases:

- Proportional band Xp=0
- Self-optimization active
- Manual mode
- Ramp function active
- Controller operating as program controller
- Modulating controller without output level feedback (or output level feedback in "out of range" state)
- Position controller with output level feedback in "out of range" status


## 12 Configuration

## Parameter dimensioning

Appropriate dimensioning of parameters used for determining the mean output level is required for the output level monitoring to function correctly.
The controller differential band around the actual value defines the corrected state. It should be dimensioned so that it is adhered to during normal operation. The progression of the actual value can, for example, be recorded with the recording function on the device or with the startup function of the setup program. Determination of the mean output level starts when the actual value enters the control differential band. Calculation of the mean output level starts over if there is temporary deviation from the control differential band during output level determination or if the setpoint value is changed by more than $0.5 \times$ control differential band $\Delta x$.
An average output level is calculated over the determination time by a sliding average. The time selected should be sufficiently long to ensure as accurate a calculation as possible. A waiting time of $0.5 \times$ reset time Tn is connected to the determination time, during which time the actual value and output level are checked to see if they are within in the specified limits. If the limits are exceeded, the calculation will restart. Once the calculation is successful, the output level monitoring will be activated.

$x$ Actual value
$y$ Output level
$\mathrm{T}_{\mathrm{C}}$ Determination time
$\Delta \mathrm{y}$ Output level band
w Setpoint value
$y_{A}$ Average output level
Tn Reset time
$\Delta x$ Controller differential band

## 12 Configuration

### 12.6.6 Controller setpoint values

With this separate setpoint value function, the setpoint values and the ramp function can be configured flexibly for both controller channels (Controller 1 to 2).
Up to four setpoint values are available for each controller channel and can be switched using two digital signals.
The analog signal for the setpoint value (external setpoint value 1 to 2 ) is selected from the analog selector. This signal can be charged with a correction value (setpoint value 1 to 4 ). If no analog signal is selected (inactive), the correction value acts as a stable setpoint value.

## NOTE!

The active setpoint value is not automatically used as a setpoint value for the controller channel; it must first be assigned in the controller configuration (see Chapter 12.6.2 "Controller inputs", page 80).

## NOTE!

If an analog signal is used as a setpoint value without a correction value, it can also be directly assigned in the controller configuration. In this case, setpoint value limitation, setpoint changeover, and the ramp function are not available.
Equally, a fixed setpoint value can be assigned directly in the controller configuration (see Chapter 12.6.2 "Controller inputs", page 80).

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Signal for ext. setpoint <br> value | No function | Signal source for ext. setpoint value. |
|  | Analog selector | There is no ext. setpoint offset |
| External setpoint value | No offset | The external setpoint value is added to the <br> internal setpoint value of the fixed setpoint <br> controller or program controller. |
|  | Offset |  |

## 12 Configuration

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Program setpoint value [1] | Program setpoint value 1 | The source for the program setpoint value is selected here for the active program controller. |
|  | Program setpoint value 2 |  |
| Setpoint value 1 to 4 start | -99999 to +99999 | Setpoint limit start |
| Setpoint value 1 to 4 end | -99999 to +99999 | Setpoint limit end |
| Boost function \& | No function | Boost function switched off |
|  | Delta value | Setpoint value is increased by a Delta value. |
|  | Percentage value | Setpoint value is increased by a percentage value. |
| Boost value | 0.00 to 99999 | Amount by which the setpoint value is increased (in K or \% by the setpoint value) |
| Boost signal | No selection | - |
|  | Digital selector | The boost function is switched on using this signal. |
| Boost duration | 0 to 999 | Duration of boost period (in s) |
| Signal 1 setpoint changeover $\square$ | No selection Digital selector | Signal 1 is selected here for the setpoint changeover for the fixed-setpoint controller. |
| Signal 2 setpoint changeover |  | Signal 2 is selected here for the fixed-setpoint changeover |

## Program setpoint value

This setting is only available if the program controller is configured. The setpoint values can then be read off the program curves that are entered.

## Boost function

The boost function is used to release tools in the plastics industry during the production process. The setpoint values for all heating zones are thereby increased by a specific Delta or percentage value for a specific time period.

## Setpoint changeover

The setpoint values 1 to 4 for both fixed-setpoint controllers are located in the parameter level and can be entered as follows:
$\Rightarrow$ Chapter 11.4 "Setpoint values", page 62
Switching can be performed using digital signals from the digital selector.

| Signal 2 (Bit 1) <br> setpoint <br> changeover | Signal 1 (Bit 0) <br> setpoint <br> changeover | Active setpoint value, Con- <br> troller 1 | Active setpoint value, Con- <br> troller 2 |
| :--- | :--- | :--- | :--- |
| 0 | 0 | Setpoint value 1 | Setpoint value 1 |
| 0 | 1 | Setpoint value 2 | Setpoint value 2 |
| 1 | 0 | Setpoint value 3 | Setpoint value 3 |
| 1 | 1 | Setpoint value 4 | Setpoint value 4 |

## 12 Configuration

### 12.6.7 Ramp function

The ramp function enables the setpoint value to be continually changed up to the ramp end value (active setpoint value).
A tolerance band can be set around the setpoint value curve to monitor the actual value. If the actual value deviates from the tolerance band, a digital signal (tolerance band signal) is activated.

## Setup dialog



## Parameter

$\left.$| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Ramp function <br> mad | Ramp off <br> Ramp in minutes <br> Ramp in hours <br> Ramp in days | Ramp function switched off |
| Pomp function switched on <br> gradient | 0.00 to 999.00 | In the event of a setpoint value step, the <br> ramp rises depending on the time unit <br> that has been set. |
| Negative <br> gradient | 0.00 to 999.00 | In the event of a setpoint value step, the <br> ramp declines depending on the time unit <br> that has been set. |
| Tolerance band <br> man | 0.00 to 999.00 | The tolerance band monitors deviation of <br> the actual value from the current setpoint <br> value (tolerance band = admissible devi- <br> ation) |
| Signal for ramp <br> stop | No selection | The ramp can be stopped with this signal <br> (see t4 in image) |
| Signal for ramp off | Digital selector | No selection |
| Digital selector |  |  | | The ramp can be switched off with this |
| :--- |
| signal | \right\rvert\,

## 12 Configuration

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Restart signal | No selection <br> Digital selector | The ramp can be restarted with this sig- <br> nal |
| Signal <br> actual value input | Analog selector/Controller 1 <br> Actual value for Controller 1 | This actual value is monitored by the tol- <br> erance band |
| Additional func- <br> tions (only setup) | 0.00 to 999.00 | Reserved functions for service |

## Ramp function

This function creates a ramp-like setpoint curve out of a step-like setpoint curve, where the rising and declining slopes can have different gradients.

t1 Power ON
t2...t3 Power failure, manual mode, probe break
t3 Ramp start at current value
t4 to t Ramp stop by digital input
5
(1) Setpoint value
(2) Actual value
t6 Setpoint changeover to w2

## Tolerance band function

For a program controller/generator and ramp function, a tolerance band can be laid to monitor the actual value of the setpoint value curve. If the upper and lower limits are exceeded, a tolerance band signal is triggered, which can be processed further internally or issued via an output.

(1) Tolerance band
(2) Ramp

## 12 Configuration

### 12.7 Digital outputs

Depending on how the expansion slots have been mounted, two fixed digital outputs called OUT1 and OUT2 and ten additional digital outputs (OUT3/4 to OUT11/12) are available.

## Setup dialog



## Parameter

$\left.$| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Designation | Relay [OUT 1] | (15 characters) of editable text <br> For example, for the signal that is issued <br> via the digital output. |
| Signal source | Digital selector/controller <br> 1st output, Controller 1 <br> No <br> Yes | This signal is issued at the digital output. |
| Inversion | Not permitted <br> Permitted | Switching behavior remains unchanged <br> Inverts the switching behavior |
| Manual mode | Digital output can be edited in manual <br> mode. |  |
| Designation | Relay [OUT 2] | Signal designation issued via the digital <br> output. <br> Inactive = output inactive |
| Signal source | Digital selector/controller <br> 2nd output, Controller 1 <br> No <br> Yes | This signal is issued at the digital output. <br> Inversion | | Not permitted |
| :--- |
| Permitted |
| Inverts the switching behavior | \right\rvert\, | Digital output can be edited in manual |
| :--- |
| mode. |

## 12 Configuration

### 12.8 Analog outputs

A maximum of three analog outputs can be configured as current or voltage outputs (standard signal) and are freely scalable.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Designation | Analog output 1 | (15 characters) of editable text for the signal issued via the analog output (for example, a math function event). |
| Signal source | No selection Analog selector | This signal is issued via the analog output. |
| Output signal | $\begin{aligned} & 0-10 \mathrm{~V} \\ & 0-20 \mathrm{~mA} \\ & 4-20 \mathrm{~mA} \\ & 2-10 \mathrm{~V} \end{aligned}$ |  |
| Signal in the event of an error | Low <br> High <br> Namur Low <br> Namur High <br> Frozen <br> Substitute value | Lower unit signal limit is issued <br> Upper unit signal limit is issued See table (limits according to Namur) See table (limits according to Namur) Retains the last valid values Issues the set substitute value |
| Substitute value | For example, 0 to 10 V | Substitute value which can be set within the output signal limits (for example, 0 to 10 V ). |
| Scaling start | 0.00 to 100.00 |  |
| Scaling end | 100.00 to. 0.00 |  |
| Manual mode | Not permitted | Analog output not editable in manual mode |
|  | Permitted | Analog output editable in manual mode. |

## Behavior on error

Limits according to NAMUR recommendation NE 43:

|  | Signal type 2 to 10 V | Signal type 4 to 20 mA |
| :--- | :--- | :--- |
| Measurement information M | 1.9 to 10.25 V | 3.8 to 20.5 mA |
| Failure information A <br> for deviation below measured value/short-circuit <br> ("NAMUR Low") | $\leq 1.8 \mathrm{~V}$ | $\leq 3.6 \mathrm{~mA}$ |
| Failure information A <br> for deviation above measured value/probe break <br> ("NAMUR High") | $\geq 10.5 \mathrm{~V}$ | $\geq 21 \mathrm{~mA}$ |

## Zero point and end value

A value range is assigned to the physical output signal by specifying the zero point and end value (scaling). The default setting corresponds to a value range of 0 to 100 (for example, an output level of $0 \%$ to $100 \%$ for a controller output).
If, for example, a temperature with a value range from $150^{\circ} \mathrm{C}$ to $500^{\circ} \mathrm{C}$ is issued via an analog output with signal type 0 to 20 mA , the zero point must be set to 150 (corresponds to 0 mA ) and the end value must be set to 500 (corresponds to 20 mA ).


## Status after change of configuration

Modified parameters are incorporated immediately.

## Behavior after power on

During the initialization phase of the controller module, the output signal adopts a value of $0 \%$ (in relation to the value range of the signal type).

## Error handling

The behavior in the event of deviation above or below the measuring range (out of range) can be configured. The settings made there also apply for probe/conductor breaks or probe/conductor short-circuits. This results in a safe state for operation in the event of an error. Error detection depends on the type of measuring probe (see technical data, measuring circuit monitoring).

## 12 Configuration

### 12.9 Limit value monitoring

One of eight alarm functions can be selected for all 12 limit value monitorings, to monitor a freely selectable input value (actual value) against a fixed limit values AF7 and AF8 or a limit value related to the setpoint value (setpoint value $\pm$ limit value) (AF1 to AF6). Each limit value monitoring delivers an output signal that can be linked to or issued to a digital output.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Function | No function |  |
|  | AF1 to AF8 | Alarm function (AF 1 to 8) selectable |
| Actual value | No selection <br> Analog selector | Analog signal to be monitored |
| Setpoint value | No selection <br> Analog selector | Setpoint value w (reference signal for AF1 to AF6) |
| Limit value AL | 0.0000 to 99999 | - For AF1 to 6, in relation to a changing setpoint <br> value w <br> - For AF7 and AF8, in relation to a fixed limit value |
| Hysteresis | 0.0000 to 1 to 9999.9 | Switching distance between switch-on and <br> switch-off |


| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Position of hysteresis | Standard <br> Non-standard left Non-standard right | Here you can adjust the setting for which side the hysteresis should be on. |
| Start-up alarm suppression $\mathbb{1}$ | Inactive | AF switching behavior is not suppressed |
|  | Active | AF switching behavior is suppressed, provided that value has is not within the valid range. |
| Switch-on delay | 0.0000 to 99999 | After entering the AF event, the time for the switch-on delay begins to elapse. <br> The AF output remains unchanged at first until the set time has completely elapsed and the AF event is relayed to the AF output. <br> If the AF actual value leaves the "bad area" for the switch-on delay during this time, the countdown begins again for each new limit value violation. |
| Switch-off delay | 0.0000 to 99999 | Identical behavior as with switch-on delay, except that the AF switch-off process is delayed. Selflocking takes priority over the switch-off delay. |
| Pulse time | 0.0000 to 99999 | AF output is automatically deactivated after the pulse time. <br> The output is only re-activated to the maximum level via the set pulse time after repeated deviation above or below the alarm values. <br> Self-locking takes priority over the switch-off delay. |
| Signal in the event of an error |  |  |
|  | Off | AF output is switched off in the event of an error |
|  | On | AF output is switched on in the event of an error |
| Self-locking [1] | Off | The alarm function is automatically reset following a limit value violation. |
|  | "Inactive" status | Self-locking can only be acknowledged if the AF actual value is re-located in the valid range. |
|  | "Active" status | Self-locking can always be acknowledged if it has been activated |
| Acknowledging selflocking | No selection Digital selector | No acknowledgement possible <br> This signal acknowledges self-locking. |
| Locking signal | No selection Digital selector | This signal locks the alarm function. |
| Additional functions not selected (empty) |  |  |
| (only setup) | (1) Expansion 1 | Reserved functions for service |
|  | (1) Expansion 2 |  |
|  | (1) Expansion 3 |  |
|  | (1) Expansion 4 |  |

## 12 Configuration

### 12.9.1 Function and hysteresis

For the AF1 to AF6 alarm functions, the final limit value depends on the setpoint value - the entered limit value is added to or subtracted from the setpoint value. The AF7 and AF8 alarm functions work with a fixed limit value which corresponds to the limit value entered. Shown with the associated hysteresis functions (non-standard left, standard, non-standard right)

## Limit value in relation to the setpoint value

|  | Non-standard left | Standard | Non-standard right |
| :---: | :---: | :---: | :---: |
| AF1 |  |  |  |
| AF2 |  |  |  |
| AF3 |  |  |  |
| AF4 |  |  |  |

1 Output signal active
$x$ Actual value
(1) Limit value (setpoint value distance)

0 Output signal not active
w Setpoint value
(2) Hysteresis

|  | Non-standard left | Standard | Non-standard right |
| :---: | :---: | :---: | :---: |
| AF5 |  |  |  |
| AF6 |  |  |  |

1 Output signal active
0 Output signal not active
x Actual value
w Setpoint value
(1) Limit value (setpoint value distance)
(2) Hysteresis

## Fixed limit value


1 Output signal active
0 Output signal not active
x Actual value
(1) Limit value (2) Hysteresis

### 12.9.2 Hysteresis

The designations "Non-standard left" and "Non-standard right" typically relate to alarm functions AF3/AF4 and AF7/AF8. The designation is not conclusive for alarm functions AF1/AF2 and AF5/AF6.
$\Rightarrow$ Chapter 12.9.1 "Function and hysteresis", page 102

## 12 Configuration

### 12.9.3 Start-up alarm suppression

Active start-up alarm suppression means:

- After power on, the output signal remains inactive, even if the actual value is in the alarm range.
- If the limit value or setpoint value is changed so that the actual value moves from outside of the alarm range to within the alarm range, the output signal remains inactive
- The limit value monitoring only starts to operate according to its alarm function again once the actual value has left the alarm range. This means that the output signal remains inactive until the actual value returns to the alarm range.


## Example of active start-up alarm suppression

The following example shows monitoring of the actual value "x" with the alarm function AF4 (without hysteresis) for a specified limit value (1). The setpoint value is changed from w1 to w2. Output state: The output signal is not active as the actual value is outside of the alarm range (gray area).


Change of setpoint value: The output signal remains inactive, although the actual value is now within the alarm range.


Set state: The actual value has left the alarm range and reached the new setpoint value. The output signal remains inactive until the actual value returns to the alarm range.


### 12.9.4 Acknowledging self-locking

For an alarm function, for example, one that is set to monitor an important process temperature, it may be necessary leave it permanently in this state rather than automatically resetting it.

If InACTIVE STATUS is set, this self-locking is only acknowledged if the actual value returns to the permitted area.
If Active status is set, this self-locking can always be acknowledged.
Self-locking takes priority over the switch-off delay.

### 12.9.5 Alarm

In addition to evaluation of the limit value monitoring output signal, there is also the option to make an entry in the event list in the case of an alarm.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Alarm type |  |  |
|  | Off | Alert switched off. |
|  | Alarm | A message will be entered in the alarm list <br> depending on the signal level that has been <br> set. |
|  | Event | A message will be entered in the events list <br> depending on the signal level that has been <br> set. |
| Polarity for alarm | High <br> Low | Limit value monitoring: High (logic "1") <br> Limit value monitoring: Low (logic "0") |
| Alarm text <br> $\mathbb{C d}$ | Alarm limit value 01 | 20 characters of editable text which is entered <br> into the alarm or event list. |

## Alarm text

Setup program: Selection of text from a list
Clicking on the " $>$ " button opens a list with text numbers and the associated texts. The texts are editable.

## 12 Configuration

### 12.10 Screen

The screen selection and the appearance of those screens in the operating loop is set using this function.

### 12.10.1 General configuration

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Display after restart | Controller screen 1 | Any of the screens in the operating loop can <br> be selected as the start screen. |
| Simulate inputs | No | Genuine recorded data is shown. |
|  | Yes | Simulated data is displayed within the mea- <br> suring range. |
| Alarm text for header | Yes | Alarms are inserted cyclically in the header. |
|  | No | Alarms are not inserted. |
| Lock touchscreen | No selection <br> Digital selector <br> Functional level | Display <br> the screen can be locked to prevent unau- <br> tade out |
| Function button 1 | Selecting user level | A selection of functions appears here that <br> 55 |
| Function button 2 | Home button | can be started using the function buttons. | | Home button | Controller screen 1 |
| :--- | :--- |
| Any of the screens in the operating loop can |  |
| be selected. |  |

### 12.10.2 Configurating the screen

The screen brightness and the screensaver can be set using this function.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Brightness | 0 to 8 to 10 | Screen brightness |
| Screen switch-off | Switched off | Screen is always on |
|  | Waiting period | Screen is switched off following a <br> waiting period. |
|  | Controller signal | Screen is switched off with a signal. |
| Waiting period | 10 to 300 to 32767 s | If the screen is not touched, it will turn <br> off after this period. |
| Controller signal | No selection <br> Digital selector | No switch-off <br> This signal switches the screen off. |

### 12.10.3 Start screen and watermark

Background screens and watermarks are set using this function.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Start screen <br> active | Default JUMO Sensors+Automation | Any screen shown with power ON (for <br> example, your company logo). |
| Watermark in dia- <br> gram | Default JUMO <br> Any screen shown as a watermark in the <br> recorder image. |  |
| Watermark his- <br> tory |  |  |

## 12 Configuration

### 12.10.4 Operating loop

Screens are set to appear in the operating loop using this function.

## Setup dialog



## Parameter (only setup)

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Controller screen <br> 1 | Display/do not display |  |
| Controller image <br> 2 | Display/do not display |  |
| Controller over- <br> view | Display/do not display |  |
| Program control- <br> ler | Display/do not display |  |
| General screen 1 | Display/do not display |  |
| General screen 2 | Display/do not display |  |
| Process screen | Display/do not display |  |

## 12 Configuration

### 12.10.5 Recording colors

The colors for the channels and alarms displayed can be set using this function.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Analog channel 1 to 4 |  | The color for the recording data |
| Digital channel 1 to 3 | 『47647825 [- | can be selected in the RGB color |
| Background color for analog channels | $R 0 G 080$ <br> $R 06089$ <br> $R 060160$ | selector. |
| Background color for digital channels | $R 0608255$ <br> $R 064750$ <br> $R 067795$ <br> $R 6478160$ |  |
| Alarm for reference channel | $\begin{array}{\|l} 20 G 478255 \\ \hline R 0 G 80 B 0 \\ \hline \end{array}$ |  |
| Alarm 1 | R0680 ${ }^{\text {Reg }}$ |  |
| Alarm 2 | R06808255 |  |
| Time stamp in diagram | $\frac{206127895}{\text { R06 } 1278160}$ |  |
| Grid lines in diagram |  |  |

## 12 Configuration

### 12.10.6 Color for controller screens 1, 2

The colors for controller image 1 and 2 can be set using this function.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| $y n n$ |  | BGB color selector |
| Color for actual <br> value |  |  |
| Color for setpoint <br> value |  |  |
| Color for output <br> level |  |  |
| Color for heating <br> contact |  |  |
| Color for cooling <br> contact |  |  |

### 12.10.7 Program controller screen

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Background color |  | RGB color selector |
| Designation of time value |  | Program runtime |
| Signal source | No selection <br> Analog selector (integer) |  |
| Color for time value | RO GO B0 | RGB color selector |

## Parameter for analog value 1 to 4, digital value 1 to 4

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Designation | Setpoint 1 | Text for analog value 1 to 3 |
| Signal source | No selection <br> Analog selector |  |
| Color | RGB color selector | Color for analog values and text |
| Designation | Stk 1 | Text for digital values 1 to 4 |
| Signal source | No selection <br> Digital selector |  |
|  |  |  |

## 12 Configuration

### 12.10.8 General screens 1, 2

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| General screen | General screen 01 | Text for general screen 1 |
| Background color | (white) | RGB color selector |
| Designation | Analog value 1 to 3 | Text for analog value 1 to 3 (in light-blue box) |
| Signal source | No selection <br> Analog selector | Any analog value can be displayed here |
| Color | RGB color selector | Color for analog values and text |
| Bar graph | Yes | Bar graph |
|  | No | No bar graph |
| Color for bar graph | RGB color selector | Color for analog values and text |
|  |  |  |
| Designation | Digital value 1 to 3 | Text for digital value 1 to 3 (in gray area) |
| Signal source | No selection <br> Digital selector | Any digital value can be displayed here |

## 12 Configuration

### 12.11 Recording

NOTE!
The recording is switched off by default and a maximum of four analog signals and a maxi-
mum of three digital signals are displayed in the form of a recording screen. Release is re-
quired for the recorded data to be saved or read out and processed.
$\Rightarrow$ Chapter 15.6 "Enabling of extra codes", page 163

The appearance of the recording image can be set here.
The watermark can be adjusted here
$\Rightarrow$ Chapter 12.10.3 "Start screen and watermark", page 107

### 12.11.1 Parameter

## Setup dialog

In this example, four analog signals and three digital signals are recorded per second.


Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Status | Switched off | The temporal variation of the analog and digital <br> signals is first displayed on the screen and then <br> saved. |
|  | Display and save |  |
|  | Recording image | Numeric representations of the analog signals <br> $\Rightarrow$ Chapter 12.10.5 "Recording colors", page 109 |
| Diagram header | Yes | No diagram header visible |
|  | No | Only visible if digital channels are switched off. |
| Perforation | Yes | No perforation visible |
|  | No | Digital signal levels are highlighted in color. |
| Display digital channels | Yes |  |
|  | No | The mean value is calculated using the set mem- <br> ory cycle and saved. |
| Memory values | Mean value |  |

## 12 Configuration

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
|  | Current value | The value is saved at the scanning instance. |
|  | Minimum value | The minimum is determined and saved using the <br> set memory cycle. |
|  | Maximum value | The maximum is determined and saved using the <br> set memory cycle. |
| Memory cycle | 1 to 5 to 3600 s | A value is recorded every 5 seconds. |

## Updating/backing up recording data

When the memory data recorder is full, the recorded data can be saved on the PC using data archiving software or exported onto a mass storage device. The USB host socket is used for this purpose.


| Function | Meaning |
| :--- | :--- |
| Safely remove hardware | To prevent hardware damage or loss of data, it is necessary to select <br> this menu item before removing an inserted USB stick. Please follow <br> the instructions on the device's display. |
| Recorded data update | Measurement data that have not yet been retrieved are stored on the <br> stick together with their configuration data. The measurement data <br> are stored in DAT files and the configuration data in SET files. This <br> data can be opened and evaluated with the aid of the JUMO <br> PCA3000 evaluation software. Data that has been read out is marked <br> internally as retrieved and the available memory display is reset to <br> 100 \%. |
| Recorded data backup | All measurement data in the ring buffer (including data already <br> retrieved) are transmitted to the memory stick together with their con- <br> figuration data. The measurement data are stored in DAT files and <br> the configuration data in SET files. These files can be opened and <br> evaluated with the aid of the JUMO PCA3000 evaluation software. In <br> contrast to the recorder update, there is no internal marking of the <br> recorder data and no reset of the available memory display. |

Table 1:

### 12.11.2 Analog channels

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Analog signal 1 to 4 |  |  |
| Designation | Channel 1 |  |
| Signal source | No selection <br> Analog selector | Any analog value can be recorded here |
| Line width | Fine |  |
|  | Bold |  |

### 12.11.3 Digital channels

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Digital signal 1 to 3 | Channel 1 |  |
| Designation | No selection <br> Digital selector | Any digital value can be displayed here |
| Signal source |  |  |

## 12 Configuration

### 12.12 Program controller

You can choose here between the program controller and the fixed-setpoint controller. With the fixed-setpoint controller, all program functions are deactivated and the setpoint values are switched, as described in Chapter 11.4 "Setpoint values", page 62.

## Setup dialog for fixed-setpoint controller

With the fixed-setpoint controller, all additional program functions are grayed out and therefore inactive.


## Setup dialog for program controller



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Function | Fixed-setpoint controller | All additional parameters are grayed <br> out for this setting. |
| Program start | From program start <br> Actual value <br> Time | Program is ... at start <br> $\ldots$ at current actual value $\ldots$ <br> $\ldots$ started at this time. |
| In the event of power failure | Abort | The program is aborted following a <br> power failure. |
|  | Continuous operation | The program continues to run from the <br> point of disruption after the power fail- <br> ure. |

## 12 Configuration

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
|  | Start at actual value | The program continues to run from the point of disruption after power failure. |
| In the event of an error | Continuous operation | Program continues to run. |
|  | Program stop | The time base for the program generator is halted. |
| Repeat | No | No program repeat |
|  | Yes | - |
| Regulate last setpoint value | No | - |
|  | Yes | Regulates the power return on the last setpoint value. |
| Start with power on | No | No automatic program start after power on. |
|  | Yes | Automatic program start after power on. |
| Adopt temp. changes | No | Temporary changes not adopted. |
|  | Yes | Adopt temporary changes |
| Setpoint step | No |  |
|  | Yes |  |
| Gradient unit | Kelvin/minute Kelvin/hour Kelvin/day |  |
| Actual value input for tolerance band monitoring | IN8 analog input 1 <br> Analog selector | This value is monitored by the tolerance band. <br> $\Rightarrow$ Chapter 12.6.7 "Ramp function", page 95 |
| Signal for actual value 2 | IN8 analog input 1 Analog selector |  |
| Program tolerance band | 0.0000 to 1.0000 to 9999 . 0 | Value of the tolerance band |
| Program end time | 0.0000 to 9999.0 |  |

## 12 Configuration

### 12.12.1 Controller signals

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Signal Program Start | Digital selector No selection | This signal starts a program. |
| Signal Program Abort | Digital selector <br> No selection | This signal aborts a program. |
| Signal Program Stop | Digital selector No selection | This signal stops a program. |
| Signal Next Section | Digital selector <br> No selection | This signal switches to the next program section. |
| Signal Fast Forward | Digital selector <br> No selection | This signal fast forwards through the programs. The longer the signal appears for, the faster the process. |
| Signal Section Start | Digital selector <br> No selection | Switches back to section start. |
| Signal Next Program | Digital selector <br> No selection | Start next program |
| Signal Last Program | Digital selector No selection | Start last program |
| Signal Manual Operation Mode | Digital selector <br> No selection | Start manual mode |
| Signal BCD Program Selection | Switched off | Program selection using digital controller signals |


| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
|  | Digital controller signal <br> 1 to 8 |  |

### 12.12.2 Extended functions

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Add. prog. functions | Not selected (empty) | - |
|  | (l) No function <br> (l) Fast forward <br> etc. | Reserved functions for service |
|  | Not selected (empty) | - |
| Input lock | (l) Setpoint value 1 <br> (l) Setpoint value 2 <br> (l) Section time | The checked program controller func- <br> tions are locked. |
| (l) Control contacts |  |  |
| (l) Tolerance band min. |  |  |
| (l) Tolerance band max. |  |  |
| (l) Start section |  |  |
| (l) Number of repetitions |  |  |
| (l) Parameter block |  |  |

## 12 Configuration

### 12.12.3 Basic status

This is where settings are adjusted for what should be active in the basic status of the program controller, that is, if no program is active in automatic mode.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Program setpoint value 1 | 0.00 to 99999 | The value entered here is the active basic status. |
| Program setpoint value 2 | 0.00 to 99999 |  |
| Control contacts | Not selected (empty) <br> () ) Contact 1 to 8 | Checked control contacts are active in the basic status. |
| Parameter block R1/R2 | Parameter block 1 to 4 | The parameter block set here is active for both controllers in the basic status |
| Active functions | Not selected (empty) <br> ( ) Limit value monitoring 1 to 12 <br> () Controller 1, 2 | The checked limit value monitoring is active in the basic status. <br> The checked controller is active in the basic status |

## 12 Configuration

### 12.12.4 Manual operation mode

You can set what is active in manual operation mode here.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Program setpoint value 1 | 0.00 to 99999 | The value entered here is active in manual operation mode. |
| Program setpoint value 2 | 0.00 to 99999 |  |
| Control contacts | Not selected (empty) <br> (l) Contact 1 to 8 | Checked control contacts are active in manual operation mode. |
| Parameter block R1/R2 | Parameter block 1 to 4 | The parameter block set here is active for both controllers in manual operation mode |

## 12 Configuration

### 12.12.5 Behavior for out of range parameters

Here you can set which parameters should be active in the program controller in the event of a deviation above or below the measuring range.

## Setup dialog



## Parameter

\(\left.$$
\begin{array}{|l|l|l|}\hline \text { Parameter } & \text { Selection/settings } & \text { Description } \\
\hline \text { Program setpoint value 1 } & 0.00 \text { to } 99999 & \begin{array}{l}\text { The value entered here is active for out } \\
\text { of range parameters. }\end{array} \\
\hline \text { Program setpoint value 2 } & 0.00 \text { to } 99999 & \begin{array}{l}\text { Checked control contacts are active } \\
\text { when out of range. }\end{array}
$$ <br>

\hline Control contacts \& (1) Contact 1 to 8\end{array}\right]\)| The parameter block set here is active |
| :--- |
| for both controllers when out of range |

## 12 Configuration

### 12.12.6 Weekly program

Ten different weekly programs can be defined here.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Automatic start | Not selected (empty) <br> $( \rceil)$ Weekly program 1 to 10 | Checked weekly programs start <br> automatically |
| Weekly program 1 | Program number: 0 <br> Program number: 1 <br> Start day: Sunday <br> Start time: 1 | Inactive <br> Number of program to be started <br> Program starts on this day <br> Program starts at this time |
| Weekly program 2 to 10 | Program number <br> Start day <br> Start time | Number of program to be started <br> Program starts on this day <br> Program starts at this time |

## 12 Configuration

### 12.13 Timer or time switch

Two functions are available that can be used as a timer or time switch. The settings can be copied to another timer using the Copy button.

## Setup dialog timer



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Function | Inactive | - |
|  | Timer | Timer function active, time switch grayed out |
| Designation | Timer 01 | (15 characters) of editable text |
| Behavior after power on | Stop | The timer is stopped after power failure. |
| Lead time | 0 to 9999 | Lead time, until the timer is started |
| Timer time | $00: 00: 00$ to 99:59:59 | The timer works for this time period |
| Timer end time | 0 to 9999 | Time until the timer is stopped |
| Tolerance band | 0.0000 to 99999 | If the distance between the tolerance band set- <br> point and actual values still lies within the toler- <br> ance band, the timer output signal is low (logic <br> "0"). |
| Tolerance band actual <br> value | Analog selector | These values are compared with one another: <br> If setpoint and actual values lie far apart from <br> one another and exceed the tolerance band, the <br> timer stops and the timer output signal changes <br> to high (logic "1"). |
| Tolerance band setpoint <br> value | Analog selector | No function |

## 12 Configuration

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Start signal | Digital selector <br> No function | The timer is started with this signal |
| Stop signal | Digital selector <br> No function | The timer is stopped with this signal |
| Signal hold | Digital selector <br> No function | The timer is halted with this signal. |
| Restart signal | Digital selector <br> No function | High |
|  | Low | The signal level is set here for the active timer. <br> This signal is available in the digital selector for <br> further use. |
| Additional timer function | Not selected (empty) <br> $($\) Extension 1 | Reserved functions for service |

## Setup dialog for time switch

| Timer |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Timer 1 | Timer $1 \backslash$ Sunday <br> 24 Hours timer: |  |  |  |  |  |
|  |  |  |  |  |
|  | $\checkmark$ Hour 0 | Switch-on time 1: | 04:15:00 |  |  | Switch-off time 1: | 04:45:00 |  |
|  | $\checkmark$ Hour 1 |  |  |  |  |  |
|  | $\checkmark$ Hour 2 |  |  |  |  |  |
|  | $\square$ Hour 3 |  |  |  |  |  |
|  | Hour 4 |  |  |  |  |  |
|  | $\square$ Hour 5 | Switch-on time 2: | 10:30:00 | Switch-off time 2: | 11:00:00 |  |
|  | $\checkmark$ Hour 6 |  |  |  |  |  |
|  | $\checkmark$ Hour 7 |  |  |  |  |  |
|  | $\square$ Hour 10 |  |  |  |  |  |
|  | $\square$ Hour 11 | Switch-on time 3: | 15:00:00 | Switch-off time 3: | 15:30:00 |  |
|  | $\square$ Hour 12 |  |  |  |  |  |
|  | $\square$ Hour 13 |  |  |  |  |  |
|  | $\checkmark$ Hour 14 |  |  |  |  |  |
|  | $\square$ Hour 15 |  |  |  |  |  |
|  | $\square$ Hour 16 | Switch-on time 4: | 23:00:00 | Switch-off time 4: | 23:45:00 |  |
|  | $\checkmark$ Hour 17 |  |  |  |  |  |
|  | $\square$ Hour 18 |  |  |  |  |  |
|  | $\square$ Hour 19 |  |  |  |  |  |
|  | $\checkmark$ Hour 20 |  |  |  |  |  |
|  | $\square$ Hour 21 |  |  |  |  |  |
|  | $\square$ Hour 22 |  |  |  |  |  |
|  | $\square$ Hour 23 |  |  |  |  |  |
| Copy |  |  |  |  | OK | Cancel |

## Parameter

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Function | Inactive | - |
|  | Control timer | Timer function active, timer function grayed out |
| Sunday | Hours 0 to 24 (1) | The period of time for which the time switch should be active on this day can be selected in hour units here by checking the relevant box ("High": logic 1). |
|  | Switch-on time 1 to 4 | Four additional switch times can be set here, for |
|  | Break time 1 to 4 | example if the switch-on time period is less than a full hour. |

## 12 Configuration

| Parameter | Selection/settings | Description |  |  |
| :--- | :--- | :--- | :---: | :---: |
| Monday to Saturday | Hours 0 to 24 ()) | Same settings possible as for Sunday |  |  |
|  | Switch-on time 1 to 4 |  |  |  |
|  | Break time 1 to 4 |  |  |  |

### 12.14 Digital controller signals

A maximum of eight unrelated links with up to four signals each (digital selector) can be configured.
Use the Copy button to transfer the selected link to another link and to then make changes there as desired.
The result of a link is available in the digital selector.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Designation | Digital controller 01 | (15 characters) of editable text |
| Signal source | No selection <br> Digital selector | Any digital value that should be linked <br> with a function |
| Function | No function <br> Impulse <br> Delay <br> Pulse function <br> Positive slope <br> Negative slope | - |

## 12 Configuration

| Parameter | Selection/settings <br> "Or" function <br> BCD function | Description |
| :--- | :--- | :--- |
| "OR" signal | No selection <br> Digital selector | Any digital value that should be linked <br> with an OR signal source at top |
| BCD signal 1 | No selection <br> Digital selector | 1st BCD digital value |
| BCD signal 2 | No selection <br> Digital selector | 2nd BCD digital value |
| BCD signal 3 | No selection <br> Digital selector <br> No selection <br> Digital selector | 3 BCD digital value |
| BCD signal 4 | No <br> Yes | 4th BCD digital value |
| Inversion | 0 | For example, if the signal set under the <br> signal source is delayed |
| Switch-on time | For example, if the signal set under the <br> signal source has a pulse function |  |
| Break time | 0 | 0 |

## Function

The following screen shows an OR function for digital inputs 1 and 2, which is issued from digital output OUT2


## BCD signal

With the BCD function (Binary Coded Decimal), four digital signals (four-bit) are processed for one digital controller signal, for example, one that can switch between 16 different programs.

## 12 Configuration



### 12.14.1 Alarms

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Alarm type |  |  |
|  | Off | Alert switched off. |
|  | Alarm | A message will be entered in the alarm list depending on the signal level that has been set. |
|  | Event | A message will be entered in the events list depending on the signal level that has been set. |
| Polarity for alarm | Signal level that triggers a an alarm or event |  |
| (only setup) | High <br> Low | Digital controller signal: High (logic "1") Digital controller signal: Low (logic "0") |
| Alarm text (only setup) | Alarm digital controller 01 | 20 characters of editable text which is entered into the alarm or event list. |

## 12 Configuration

## Polarity for alarm

An alarm is only displayed for as long as the digital controller signal High (logic "1") is shown. If the signal level Low (logic " 0 "), the alarm entry disappears automatically.

## Alarm text

The setup program is required to view and edit the texts.

## 12 Configuration

### 12.15 Mathematics/logic

Limited functionality only is possible on the device.
Programming, for example, of formulas, can be done using the setup program:
Eight functions are available. The optional mathematics/logic function supports four formulae, which can be used freely either for mathematical calculations (analog values) or for logical links (binary values). Fixed formulae for calculating the differential, ratio, and relative humidity are also provided. In this case, two analog values (variable A and B), for example, the measured values of analog input 1 and 2 are linked to each other. The dry-bulb temperature and the wetbulb temperature are required for calculating the relative humidity and should be determined with a psychrometric humidity sensor.
The results are available in the analog selector or digital selector. If the function is not active, the mathematical value $=3.0 \mathrm{E}+37$ and the logic value $=0$ (FALSE). The settings can be copied to another math/logic function using the Copy button.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Designation | Math configuration 1 to 8 <br> (inactive) | Name of the mathematical function <br> available as a variable in the analog <br> selector for further processing. |
| Function | Inactive <br> Differential <br> Ratio | Differential controller (a-b) <br> Ratio controller (a/b) |

## 12 Configuration

| Parameter | Selection/settings <br> Humidity <br> Math formula <br> Logic formula | Description <br> Humidity controller (a;b) <br> Mathematical linking (a+b) x 2 <br> Logic linking (a AND b) |
| :--- | :--- | :--- |
| Linearization |  | The mathematical calculation can be <br> linked with a (customer-specific) linear- <br> ization table. |
| Secure using power off |  |  |
| Measuring range start | 0 |  |
| Measuring range end | 100.00 |  |
| Variable a |  |  |
| Variable b | $\%$ |  |
| Unit |  |  |
| Decimal place |  |  |
| Temperature |  |  |
| Additional math functions |  |  |
| Formula (text) |  |  |

## Function

The math and logic functions are available if the "Math/logic" option in the setup program has been activated.

## Math formula, logic formula

Use the "Formula Editor" button to open an editor that can be used to create formulae by selecting variables and operators. Formulae can be entered freely according to standard mathematical rules. Any number of spaces may be used within the formula symbol string. Spaces are not admissible in function designations, names of variables, or constants.


## 12 Configuration

### 12.16 Flags/service

### 12.16.1 Flags

Eight analog flags and 8 digital flags are available. The settings can be copied to another flag using the COPY button.

## Setup dialog



## Analog flag parameters

| Parameter | Selection/settings | Description |
| :---: | :---: | :---: |
| Analog flag | 0.0000 to 100 | Can be set within the limits of any value with four decimal places. |
| Temperature | None |  |
|  | Relative |  |
|  | Absolute |  |
| Unit | \% | Entry of a unit with up to five characters possible |
| Decimal place | Auto <br> XXXXX. <br> XXXX. X <br> XXX.XX <br> XX.XXX <br> X.XXXX | Automatic switching <br> No decimal place <br> 1 decimal place <br> 2 decimal places <br> 3 decimal places <br> 4 decimal places |
| Measuring range start | 0.0000 to 100 |  |
| Measuring range end | 0.0000 to 100 |  |

## Digital flag parameters

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Digital flags 1 to 8 | Off | Low (logic "0") |
|  | On | High (logic "1") |

## 12 Configuration

### 12.16.2 Service

Here you can set which signal should be monitored, for example with a service counter. This can trigger an alarm if exceeded and can be acknowledged with the set signal.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Service interval | 0 to 99999 | The number of switching operations for the set <br> digital signal are counted. |
| Function | Switch operation counter | Switch operations are counted |
|  | Time in hours | The hours in which the High signal (logic "1") <br> appeared are counted. |
|  | Time in days | The days in which the the High signal (logic "1") <br> appear are counted. |
| Monitoring signal | No selection <br> Digital selector | This signal is monitored using the service and if <br> the alarm condition is exceeded (for example, <br> the number of switch operations), the logic <br> level switches from "0" to "1". <br> The signal can be processed further in the digi- <br> tal selector. |
| Acknowledgement sig- <br> nal | No selection <br> Digital selector | The elapsed service interval is acknowledged <br> with this signal. |
| Operation hours coun- <br> ter | Off <br> Display in hours <br> Display in days |  |

## 12 Configuration

### 12.17 External digital inputs

Eight external digital inputs are available. The settings can be copied to another input using the Copy button. The settings can be copied to another external input using the Copy button.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Channel descrip- <br> tion | ext. DE 01 |  |
| Secure power off | No <br> Yes | Status is secured beyond power failure. |
| Alarm type | Off |  |
| Polarity for alarm |  |  |
| Alarm text | Ext. digital alarm 01 |  |

## 12 Configuration

### 12.18 External analog inputs

Eight external analog inputs are available. The settings can be copied to another input using the Copy button.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Designation | Ext. AE 01 |  |
| Temperature | None <br> Relative <br> Absolute |  |
| Decimal place | Auto <br> XXXXX. <br> XXXX.X <br> XXX.XX <br> XX.XXX <br>  <br> X.XXXX | Automatic switching <br> No decimal place <br> 1 decimal place |
| Measuring range <br> start | 0.0000 | 2 decimal places <br> 3 decimal places <br> 4 decimal places |
| Measuring range end | 100.00 |  |
| Secure power off | No <br> Yes |  |

## 12 Configuration

### 12.18.1 Alarms

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Minimum alarm |  |  |
|  | Off | Alert switched off. |
|  | Alarm | A message will be entered in the alarm list depending <br> on the minimum value that has been set. |
|  | Event | A message will be entered in the events list depending <br> on the minimum value that has been set. |
| Minimum value | -99999 to 99999 | In the event of deviation below the limit values, an <br> alarm/event will be entered. |
| Minimum alarm <br> text | Underrange ext. AE 01 | 20 characters of editable text |
| Maximum alarm |  |  |
|  | Off | Alarm |
|  | Event | A message will be entered in the alarm list depending <br> on the maximum value that has been set. |
| Maximum value | -99999 to 99999 | A message will be entered in the events list depending <br> on the maximum value that has been set. |
| Maximum alarm <br> text | Overrange ext. AE 01 | In the event of deviation above the limit values, an <br> alarm/event will be entered. |

## 12 Configuration

### 12.19 Serial interfaces

One serial interface is available by default. If additional serial interfaces should be added in the form of optional boards, they will appear here.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Protocol | Modbus slave |  |
|  | ER8 |  |
|  | Modbus master |  |
| Baud rate | $9600,19200,38400$ |  |
| Data format | $8-1-$ no parity |  |
| Minimum response <br> time | 0 to 40 to 500 ms | Minimum response time required. |
| Master timeout | 60 to 10000 to 60000 |  |
| Device address | 1 to 254 |  |
| Timeout | 60 to 700 to 10000 |  |
| Scan cycle | 60 to 500 to 99999 |  |

## 12 Configuration

### 12.20 Modbus TCP

There is no Modbus TCP interface available by default. If it is integrated into the device using optional boards, the following values should be set for Modbus communication:

## Setup dialog



## Parameters for Modbus slave

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Port | 0 to 502 to 1024 |  |

## Parameters for Modbus master

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Timeout | 4000 to 5000 to 10000 |  |
| Scan cycle | 0 to 500 to 1024 |  |
| Device 1 | $0.0 .0 .0 \ldots$ |  |
|  | 255.255 .255 .255 |  |
| Device 2 | $0.0 .0 .0 \ldots$ |  |
|  | 255.255 .255 .255 |  |
| Device 3 | $0.0 .0 .0 \ldots$ |  |
|  | 255.255 .255 .255 |  |
| Device 4 | $0.0 .0 .0 \ldots$ |  |
|  | 255.255 .255 .255 |  |
| Manual IP address | $0.0 .0 .0 \ldots$ |  |
| Port | 255.255 .255 .255 |  |

### 12.21 Relay module (accessories)

An ER8 external relay or logic module can be connected at the serial interface COM1. Relays 1 to 8 can be controlled using the digital selector.
The relay module is switched to inactive by default:

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Activation | Inactive <br> COM1 active <br> COM2 active | Not activated <br> The external relay module is connected and activated at <br> this interface. <br> (only if the interface is integrated as an option) |
| Device address | 0 to 255 |  |
| Relay 1 | No selection <br> Relay 2 | Digital selector |
| Relay 3 |  | - |
| Relay 4 |  |  |
| Relay 5 |  |  |
| Relay 6 |  |  |
| Relay 7 |  |  |
| Relay 8 |  |  |

## 12 Configuration

### 12.22 PROFIBUS DP (option)

For a device with integrated PROFIBUS DP, optional boards can adopt the following settings:

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Function | Inactive <br> Active | PROFIBUS inactive (bus error message suppressed) <br> PROFIBUS active |
| Device address | 0 to 127 | - |
| Device address | 1 to 125 | May be used for the connected devices |
| Data format | Big Endian <br> Little Endian | Also known as "Motorola format" <br> Also known as "Intel format" |

## 13 Configuration - in setup program only

### 13.1 Installing the setup program

Insert the CD and the setup program will start automatically.
Follow the instructions on the screen.

### 13.1.1 Hardware

- 500 MB hard disk space
- 512 MB RAM


### 13.1.2 Software requirements

- Microsoft Windows XP
- Microsoft Windows7 32 or 64-bit


### 13.2 Starting the setup program

| Step | Activity |
| :---: | :---: |
| 1 | Start the program by selecting it from the start menu and the version display will appear briefly. |
| 2 | The main window appears and the program can be run. |

Setup program started

## 13 Configuration - in setup program only

### 13.2.1 Establish the connection to the device

First of all, you will see from the connection symbol on the menu panel that a device has not yet been connected.


The following possibilities are available for connecting the device:
Via USB device interface

| Step | Activity |
| :---: | :---: |
| 1 | Connect USB interfaces between the device and the PC |
| 2 | Click on ConNECT and the empty connection list will appear. <br> Click on New entry |
| 3 | Select the USB and click Next (no logon) |
| 4 | Select the USB connection and click Finish |

USB connection established

## 13 Configuration - in setup program only

## Via Ethernet interface

| Step | Activity |  |
| :---: | :---: | :---: |
| 1 | Connect Ethernet socket on the device with LAN socket on the router or company network and perform step 2 as with the USB interface |  |
| 2 | Select TCP/IP and click Next (no logon) |  |
| 3 | Enter IP address and click Finish |  |

$\Leftrightarrow$ LAN connection established

### 13.2.2 Setup data transfer on or from the external mass storage device

The setup program first saves the setup data on the internal hard disk drive, from which the setup program also runs.
However, setup data can also be exported/imported from the device or with the setup program using a mass storage device. The USB host socket is used for this purpose.
The devices can therefore be easily duplicated with identical firmware versions.


| From the device | With the setup program |
| :--- | :--- |
| Write config. to USB stick | Setup data transfer from the device to an external mass <br> storage device |
| Reading USB stick config. | Setup data transfer from the external mass storage device <br> to the device |

## 13 Configuration - in setup program only

### 13.3 Country settings

Additional device languages can be generated or edited here. For example, French can be selected as a second language from the current library and transferred to the device.


### 13.4 User list

The user currently logged on is displayed.

| User list |  |  |  |
| :---: | :---: | :---: | :---: |
| Character table: <br> Public rights: |  |  |  |
|  |  |  |  |
| User $1 \quad$ - |  |  |  |
| ID: ${ }^{\text {ID }}$ Master |  |  |  |
|  |  |  |  |
| Password: <br> Rights: |  | ******* |  |
|  |  | $\ldots$ |  |
|  |  |  |  |

## 13 Configuration - in setup program only

### 13.5 User level

The user levels can only be edited using the setup program.
An example of this can be seen in Chapter 7.1 "Example 4 Transferring controller setpoint values to the user level", page 45.

### 13.6 E-mail

Five different e-mail texts are entered here and sent to the plant, for instance, in the event of an alarm.


### 13.7 Web server

HTML documents, which can be created using a conventional HTML editor, can be stored in the JUMO DICON touch using the PC setup program. These documents can contain texts, graphics, and JavaScript code. Analog and digital values for the device can be displayed with JavaScript. The result is a website which can be retrieved over the Internet or LAN and displayed via a PC using a conventional web browser. On this website, the user can now see a clear display of the plant or the process, including measured values and operating states. A "standard online visualization" function is stored as default. A PC with Microsoft® Windows® operating system and Silverlight $®$ installed is required to use this function. An HTML document can be created here which visualizes the DICON touch using a web application.

## 13 Configuration - in setup program only



### 13.8 Modbus frames for reading

This function is used to compile up to eight Modbus frames for reading process values of external devices (via interface) individually for each opposite side. The process values (analog, integer, and digital values, and text) are written to the selected variables from the received Modbus telegram and are available for use in the system. Each frame can be used to configure up to 64 entries (variables); the process values are then grouped and transferred in a Modbus telegram.

## Setup dialog



Configuration and use of the Modbus frames for writing is described in the Modbus interface description B 703571.2.0.

## 13 Configuration - in setup program only

### 13.9 Modbus frames for writing

This function is used to compile up to eight Modbus frames for writing process values to external devices (via interface) individually for each opposite side. The process values (analog, integer, and digital signals, and text) are written to the frames by the system and are available to external devices. Each frame can be used to configure up to 64 entries (process values), which are then grouped and transferred in a Modbus telegram.

## Setup dialog



NOTE!
Configuration and use of the Modbus frames for writing is described in the Modbus interface description B 703571.2.0.

## 13 Configuration - in setup program only

### 13.10 Customer-specific linearization

No linearization tables are stored by default.
A maximum of four linearizations can be created with the setup program.

### 13.10.1 Grid points

Customer-specific linearization is specified by entering up to 40 grid points (pairs of values X/ Y ). Here, value X indicates the physical measured value (in mV , mA , or Ohm for example; depending on the sensor type) and value Y indicates the linearized value (temperature in ${ }^{\circ} \mathrm{C}$, for example).

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Measured value <br> $(\mathrm{X})$ | -99999 to $\mathbf{0}$ to +99999 | Value of the relevant grid point on the x <br> axis |
| Linearized value <br> (Y) | -99999 to $\mathbf{0}$ to +99999 | Value of the relevant grid point on the $y$ <br> axis |

The definition range of linearization (measuring values, $x$ axis) is monitored in the module and limited as follows:
Lower limit of the definition range $=X \min -0.0125 \times(X \max -X \min )$
Upper limit of the definition range $=\mathrm{Xmax}+0.03125 \times(\mathrm{Xmax}-\mathrm{Xmin})$

## NOTE!

A measured value that lies outside of the definition range results in a deviation above or below the measuring range (out of range).

## 13 Configuration - in setup program only

## Displaying linearization on a graphic ("Display graphic" button)

Use this button to create a graphic of the linearization.
The graphic includes the characteristic lines for both types of linearization where applicable, namely the grid points (table) and the formula.
The display range for the graphic is first of all determined by the smallest and largest grid points; it can be temporarily changed in the display by entering different x values.

## Calculating the polynomial using the grid points ("fx" button)

After entering the pair of values, use this button to calculate a polynomial that describes the progression of the linearization characteristic line.
The calculated coefficients are incorporated into the formula. The characteristic lines for both types of linearization then correspond to each other.
If the $x$ values do not increase in a straight line, the linearization will not be adopted. In this case, it will not be possible to display the graphic or calculate the polynomial.

### 13.10.2 Formula

Customer-specific linearization is specified using a 4th order polynomial. The polynomial is calculated for the entire linearization range.
Polynomial formula: $y=X 4^{*} x^{4}+X 3^{*} x^{3}+X 2^{*} x^{2}+X 1^{*} x+X 0$

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Measuring range <br> start $($ Ymin $)$ | -99999 to $\mathbf{0}$ to +99999 | Start value of the y axis |

## 13 Configuration - in setup program only

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Measuring range <br> end (Ymax) | $-\mathbf{- 9 9 9 9 9}$ to $\mathbf{1 0 0}$ to +99999 | End value of the y axis |
| X0 | -99999 to $\mathbf{0}$ to +99999 | Absolute component of the polynomial <br> (point of intersection with the y axis) |
| X1 | -99999 to $\mathbf{1}$ to +99999 | Coefficient of the linear component $(x)$ |
| X2 | -99999 to $\mathbf{0}$ to +99999 | Coefficient of the quadratic <br> component $\left(x^{2}\right)$ |
| X3 | -99999 to $\mathbf{0}$ to +99999 | Coefficient of the cubic component $\left(x^{3}\right)$ |
| X4 | -99999 to $\mathbf{0}$ to +99999 | Coefficient of the quartic component $\left(x^{4}\right)$ |

The value range for the linearization (linearized values, $y$ axis) is monitored in the module and limited as follows:
Lower limit of the value range $=$ Ymin $-0.0125 \times($ Ymax $-Y m i n)$
Upper limit of the value range $=$ Ymax $+0.03125 \times($ Ymax $-Y m i n)$

## NOTE!

A linearized value that lies outside of the value range results in a deviation above or below the measuring range (out of range).

## Displaying linearization on a graphic ("Display graphic" button)

Use this button to create a graphic of the linearization.
The graphic includes the characteristic lines for both types of linearization where applicable, namely the formula and the grid points (table).
The display range for the graphic is first of all determined by the "measuring range start" and "measuring range end" values ( y values); it can be temporarily changed in the display by entering different $x$ values

## Example of third-order polynomial



## 13 Configuration - in setup program only

### 13.11 Process screen

The process screen is empty by default and can only be created using the setup program.


A process screen can consist of a maximum of 50 objects. These could be icons in bitmap format, frames, surfaces, texts, and analog and digital values of various colors and sizes. The object background is always located right at the bottom. All other objects at the bottom of the list are covered by those at the top.
If a particular object is problematic, it can first be set to VISIBLE>NO.

## Preview

In the list on the right-hand side, the position for screen elements is set and displayed on the left in the preview. Clicking on an object (highlighted in blue) causes it to appear in a frame on the left side of the preview window. You can also click in the preview window.

## NOTE!

1
Before beginning the screen layout, icons and background screens must be contained in the library and in the "list of screens" (bitmap max. $320 \times 182$ pixel).
C:IUserslyournamelDocuments|Set266u...

## 13 Configuration - in setup program only

### 13.11.1 Process screen editor

## Setup dialog


(1)Object list
(3)Selected process screen
(5)Select background image
(7)Select background color
(9)-
(11)Exit process screen editor; settings are adopted
(2)Object used
(4)Activate process screen
(6)Name of the process screen
(8)Navigation and processing functions
(10)Exit process screen editor; settings are not adopted
(12)Preview of the process screen (preview window is opened in the setup program)

## Navigation and processing functions

| Button | Function |
| :---: | :---: |
| \% | Cut object from the object list |
| 嚂 | Copy object to another object (only within the same process screen) |
| 量 | Paste cut object into the object list |
| \% | Add new object to the object list |

## 13 Configuration - in setup program only

| Button | Function |
| :--- | :--- |
| $\mathbf{X}$ | Remove object from the object list |
| $\boldsymbol{4}$ | Move object up in object list |
| $\boldsymbol{\downarrow}$ | Move object down in object list |
| Edit object |  |

### 13.11.2 Background

In addition to the background color, a background image can also be used for the background of the process screen. The background image is selected from the list of available screens in the setup program. If the background color is to be visible, the background image must not cover the entire area of the process screen or it must be transparent (option when replacing a screen).

## Example

A furnace whose temperature is regulated via an SCR power controller should be displayed here. For this purpose we need a screen of the plant with the most important parameters.


Assign screen name, click on "Visible", click ... , click "Replace"


## 13 Configuration - in setup program only

Select the new furnace screen, click "Transparent" and it will appear in the list of screens.


Once "Active" is ticked, the background screen will appear in the preview.


## 13 Configuration - in setup program only

### 13.11.3 Signal types for process screens (overview)

The variables and icons are now entered in the list until the process screen is complete. The first blue highlighted entry is highlighted in a blue frame in the preview.

## Setup dialog



## Signal types

| Parameter | Description |
| :--- | :--- |
| Pictogram | Screwdriver, alarm bell... |
| Analog signal | ...from the analog selector |
| Integer signal | ...from the integer selector |
| Digital signal | ...from the digital selector |
| Text | Text from the process or configuration selector |
| Frame | Transparent border |
| Rectangle | Rectangle with color fill and border |
| Time | Run times, timer times, service times |
| Bar graph | ...from the analog selector |
| Extra analog value | Unit, channel description, min or max limit value |
| Float value input | Field for entering a floating point value |
| Text input | Field for entering a text |
| Time input | Field for date and time input |
| Digital value input | Field for binary value output |
| Button | Button with touch function |

## 13 Configuration - in setup program only

### 13.11.4 General object features

The description of the general object features applies for all object types for which the parameters in question are available.
The specific object features are described in the following chapters under the corresponding object type.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Type | Selection from list of object types | Object type for the process screen |
| X position | 0 to $\mathbf{1 0}$ to 634 | X coordinate of the upper left corner of <br> the object in the process screen |
| Y position | 0 to $\mathbf{2 0}$ to $\mathbf{4 0 2}$ | Y coordinate of the upper left corner of <br> the object in the process screen |
| Width | $\mathbf{1}$ to $\mathbf{5 0}$ to 635 | Width of the object |
| Height | $\mathbf{1}$ to $\mathbf{2 0}$ to $\mathbf{4 0 3}$ | Size of the object |
| Visible | Yes (), No (), No ()■ $\square$ | "Yes" releases the display of the object <br> in the process screen. |
| Editable | "Yes" releases the option for entry in the <br> process screen (only for input objects). |  |
| Send acknowl- <br> edgement | Yes (), No ()■ $\square$ | "Yes" means that an acknowledgement <br> is sent to the internal PLC following an <br> entry in the process screen (only for <br> input objects with a destination vari- <br> able). |
| Background color | Select color (drop-down menu). | Background color of the object |

## 13 Configuration - in setup program only

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Transparent | Yes (), No ()■ $\square$ | If "Yes", the background color of the <br> object is not active. Instead, the font will <br> be displayed in front of the background <br> color of the process screen. |
| Frame type | Select form (drop-down menu). | The object can be provided with a <br> frame. |
| Foreground color <br> ■ | Select color (drop-down menu). | Font color within the object |
| Font size | Select font size (drop-down menu). | Font size within the object |
| Alignment | Select alignment (drop-down menu). | Alignment of the font within the object <br> (left-aligned, right-aligned, centered) |
| Orientation <br> (object type) | Select orientation (drop-down menu). | Orientation of the object in the process <br> screen (horizontal, vertical; not for input <br> objects). |

## Foreground color

In order for the font to be visible, the foreground and background color must be different from each another. If the "Transparent" setting is selected (), this applies with regard to the background color of the process screen.

### 13.11.5 Preview screen

A process screen that has been created can be inspected and changed in the preview screen using the setup program prior to being transferred to the device.
The preview screen is opened by touching the "Preview" button:
Preview screen


## 13 Configuration－in setup program only

## Processing functions

| Button | Function |
| :---: | :---: |
| $1-$ | Select background color（for example，font color）within the object（drop－down menu）． |
| 256 | Select background color of the object（drop－down menu）． |
| $\square$ | Changing the frame form of the object（none，thin，thick，raised，sunken）． |
| $\mathrm{A}^{\text {a }}$ | Change font size（ $12,16,24,31,48,64$ pixels）． |
| 产 | Change alignment of the font within the object（left－aligned，centered，right－aligned）． |
| ＋ | Change orientation of the object in the process screen（horizontal，vertical）． |
| 近 | Move object in process screen forward one level with each click． <br> The object is simultaneously moved down in the object list（larger number）． |
| 岛 | Move object in process screen back one level with each click． <br> The object is simultaneously moved up in the object list（smaller number）． |
| $\ddagger$ | Move object in process screen horizontally or vertically． <br> Clicking on this button opens an additional window．This contains different arrows （buttons）for moving the object in preset steps． |

## Processing object features

Changes can be made directly to the object features in question using the processing functions described above．It is also possible to open the object by double－clicking（in the preview screen or in the object list）in order to process the object features．

## Moving objects

The user has the following options for moving an object in the preview screen：
－Double－clicking the object to open it and changing the X／Y position．
－Left－clicking and holding the object and moving it directly into the preview screen．
－Moving the object using the arrows．

## Foreground color

In order for the font to be visible，the foreground and background color must be different from each another．If the＂Transparent＂setting is selected（），this applies with regard to the back－ ground color of the process screen．

## 13．11．6 Transfer process screen to device

As soon as the setup data is transferred to the device，it can be retrieved from the operating loop．

### 14.1 Calibrating the touchscreen

The display on the TFT screen may no longer correspond to the points of contact on the adhesive touchscreen cover.
In this case, the touchscreen must be calibrated.

## Device menu>Calibrate touchscreen

To do this, four interchangeable screen points must be treated as accurately as possible with a pen wherever an ' $x$ ' appears.
The device saves these coordinates and this enables the assignment of the TFT screen and the touchscreen to correspond again.


## 14 Special functions

## 15 Online parameter

### 15.1 Fine adjustment

You can use customer-specific fine adjustment to correct the measured values of the analog input. In contrast to offsetting, which is used to specify a constant correction value for the entire characteristic line, fine adjustment can also be used to change the gradient of the characteristic line.

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| Actual zero point | -99999 to $\mathbf{0}$ to +99999 | Lower displayed value |
| Actual end value | -99999 to $\mathbf{0}$ to +99999 | Upper displayed value |
| Set zero point | -99999 to $\mathbf{0}$ to +99999 | Lower reference value |
| Set end value | -99999 to $\mathbf{0}$ to +99999 | Upper reference value |

## Example

The temperature inside a furnace is measured with an RTD temperature probe and displayed. Due to the temperature drift of the probe, the true temperature (reference measurement) deviates from the displayed value. The amount of deviation is different at the upper and lower measuring points, meaning that measured value offset is not suitable.
Actual zero point: $15^{\circ} \mathrm{C}$ (lower displayed value)
Set zero point: $20^{\circ} \mathrm{C}$ (lower reference value)
Actual end value: $70^{\circ} \mathrm{C}$ (upper displayed value)
Set end value: $80^{\circ} \mathrm{C}$ (upper reference value)

(1) Display values
(2) Reference values
(3) Furnace
(4) Sensor in RTD temperature probe

## 15 Online parameter

## Performing fine adjustment

1) Determine the lower value (as low and constant as possible) with the reference measuring device.
Example: Set furnace temperature to $20^{\circ} \mathrm{C}$.
2) Enter the display value as the actual zero point and the reference value as the set zero point.
Example: Enter 15 and 20.
3) Determine the upper value (as high and constant as possible) with the reference measuring device.
Example: Increase furnace temperature to $80^{\circ} \mathrm{C}$.
4) Enter the display value as the actual end value and the reference value as the target end value.
Example: Enter 70 and 80.

## Characteristic line

The following diagram shows the changes in the characteristic line caused by the fine adjustment (point of intersection with the x axis as well as the gradient).

$\begin{array}{ll}\mathrm{y} & \text { Display value } \\ \mathrm{x} & \text { Reference value }\end{array}$
(1) Characteristic line before fine adjustment
(2) Characteristic line after fine adjustment

## Resetting the fine adjustment

The following settings must be made to reverse the fine adjustment:
Actual zero point = set zero point
Actual end value $=$ set end value

## 15 Online parameter

### 15.2 Ethernet (option)

There is no Ethernet interface available by default. If it is integrated into the device using optional boards, the following values should be set:

## Setup dialog



## Parameter

| Parameter | Selection/settings | Description |
| :--- | :--- | :--- |
| IP address assign- <br> ment | Automatic | The DICON touch automatically obtains <br> its IP address from the DHCP server. <br> The IP address for the DICON touch must <br> be assigned manually. |
| Manual IP address | $0.0 .0 .0 \ldots$ <br> $233.233 .233 .1 \ldots$ <br> 255.255 .255 .255 | The IP address is entered manually here <br> (if necessary, it should be requested from <br> the administrator responsible). |
| Subnet mask | $0.0 .0 .0 \ldots$ <br> $255.255 .255 .0 \ldots$ <br> 255.255 .255 .255 | Manual setting of the subnet mask |
| Standardgateway | $0.0 .0 .0 \ldots$ <br> 255.255 .255 .255 | Manual setting of the IP address of the <br> standard gateway (router) |
| DNS device name | $097 e 25-$ TYP703571 <br> Admissible characters: a to z, <br> A to z, -, 0 to 9 (max. 63 charac- <br> ters); name must begin with a let- <br> ter and may not end with a "-" <br> (hyphen) | Example of unique DNS device name for <br> multifunction panel (assigned by default) |
| DNS server | $0.0 .0 .0 \ldots$ <br> 255.255 .255 .255 | IP address of DNS server <br> Automatic <br> 10 MBit/s half duplex 10 MBit/s <br> full duplex 100 MBit/s half duplex <br> 100 MBit/s full duplex |

## 15 Online parameter

### 15.3 Date and time

The date and time for the device can be adopted from the connected PC or even entered manually.

## Setup dialog



### 15.4 Screenshot

A screenshot can be created here from the current device and saved as a bitmap.

## Setup dialog



### 15.5 Deleting measurement data memory

A screenshot can be created here from the current device and saved as a bitmap.

## Setup dialog

JUMO DICON touch
(?) Delete internal measurement data memory in the device. Are you sure?
$\square$
Ja
Nein

## 15 Online parameter

### 15.6 Enabling of extra codes

To do this, you need a device that is connected to the setup program.

| Step | Activity |
| :---: | :---: |
| 1 | Connect device to the PC using the USB or LAN |
| 2 | Click on Enabling of extra codes |
| 3 | Generate code number and click Next |
| 4 | Select the required extra codes and click Next |
| 5 | Code number appears |
| 6 | Send the code number to JUMO and the enabling code will be sent to you. |
| 7 | Enter the enabling code under Enabling of extra codes and click Next. |

$\Leftrightarrow$ Extra code enabled

## 15 Online parameter

### 15.7 Testing calibration

This is where the dialogs for calibration and testing of analog and digital outputs appear, along with other device functions.

## Setup dialog



### 15.8 Various process values

Values can be read and saved here.

## Setup dialog



### 16.1 Error messages in float values and on the display

The display is shown as a float value itself. The following statuses are defined.

| Error | Float value display | Display |
| :---: | :---: | :---: |
| First error value | $1.0 \mathrm{E}+37$ |  |
| Software - underrange | $1.0 \mathrm{E}+37$ | <<<<<<< |
| Software - overrange | $2.0 \mathrm{E}+37$ | >>>>>> |
| No valid input value | $3.0 \mathrm{E}+37$ | -- |
| Division by zero | $4.0 \mathrm{E}+37$ | -- |
| Incorrect mathematical value | $5.0 \mathrm{E}+37$ | ----------- |
| Display capacity exceeded |  | ******** |
| Invalid value |  | ----------- |

In the event of an error, the device function reports this error itself in its output value. All device functions monitor an input value for these error values. In the event of an error, the output value is applied in turn to one of these error values, or another value is specified in the configuration (error value/substitute value).

### 16.2 Display of error messages for binary values

Binary input values are only displayed with 0 and 1 . If no valid input value is available, or the device function cannot deliver a valid output value, the value is set to 0 .

## Exception

In the configuration level you can set which value the output should accept in the event of an error (error value/substitute value) and this value is then faded in.

## Start/end display:

The graphic display elements of the display range are established for this (lower and upper limit in a bar graph display). The numeric representation is dependent on the display start/end and is produced from the entire measuring range. In the recording, measured values smaller than the display start are saved as UNDERRANGE and measured values larger than the display end are saved as OVERRANGE.

## Bar graph display:

The numeric representation is dependent on the display start/end and is produced from the entire measuring range. In the recording, measured values smaller than the display start are saved as UNDERRANGE and measured values larger than the display end are saved as OVERRANGE.

## Over- and underrange:

Detection is performed at hardware limits and on the scaling in mV . The maximum number of display ranges are therefore always available. For all the values calculated in the device such as mathematics output, flow rate, and external inputs, the following applies: The display range has the same significance here as for hardware inputs.

## 17 Retrofitting optional boards

### 17.1 Safety information

You can upgrade or retrofit the device flexibly using the following description. All the necessary settings are described in the operating manual. Manipulations not described in the manual or expressly forbidden will jeopardize your warranty rights.

## CAUTION!

Risk of damage to the modules by electrostatic discharge can occur. For this reason, avoid electrostatic charge during fitting and removal. Work in an "earthed" working area with the corresponding upgrade!


## DANGER!

Do not touch live parts inside the device as they are highly charged.
Disconnect (all poles) the device from the voltage supply before retrofitting.
Only qualified personnel are permitted to carry out module retrofits. The country-specific requirements available regarding changes to an electrical device must be observed.

### 17.2 Identifying the modules

| 1 | Identify the module from the part number on the sticker attached to the packaging |
| :--- | :--- |
| 2 | Check which slot the optional board may be inserted into. <br> $\Rightarrow$ Chapter 4.3 "Connection diagram", page 27 |
| 3 | Only install modules in the device that are permitted for this optional slot. |

## Block diagram



### 17.3 Installing modules

In this example, a universal analog input is inserted in slot $\ln 10$.

| Step | Activity |
| :---: | :---: |
| 1 | Disconnect screw terminals and interface cables connected at the rear |
| 2 | Loosen two screws at bottom (do not remove), remove side screw completely |
| 3 | Lift up back panel and pull out |

## 17 Retrofitting optional boards


$\Rightarrow$ Result: The correctly recognized slot can now be configured and connected.

## 17 Retrofitting optional boards

17.3.1 Accessories

| Article |  | Part no. |
| :---: | :---: | :---: |
| Modules for expansion slots: |  |  |
| 1 analog input (universal) |  | 00581159 |
| 1 relay output (changeover contact) |  | 00581160 |
| 2 relay outputs (N/O contact) |  | 00581162 |
| 1 logic output DC 0/22 V max. 30 mA |  | 00581165 |
| 2 logic outputs DC 0/12 V max. 20 mA |  | 00581168 |
| 1 solid state relay AC $230 \mathrm{~V}, 1 \mathrm{~A}$ |  | 00581164 |
| 2 PhotoMOS® relays ${ }^{1}$ DC 50 V, max. 200 mA , AC 35 V , max. 200 mA |  | 00581171 |
| 1 analog output (universal) |  | 00581169 |
| Ethernet interface |  | 00581174 |
| Serial interface RS422/RS485 |  | 00581172 |
| PROFIBUS-DP interface |  | 00581173 |

[^1]
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