# BH series Paddle joystick controllers

Distinctive features and specifications



Hall effect joystick and switch function
Sculpted ergonomic rubber grip
5V operation - standard dual redundant outputs
Analog or PWM outputs
Custom lever colors & designs available
IP67 sealed
EMC shielded
60mm above nanel height

#### **ELECTRICAL SPECIFICATIONS**

- Gain (Output Voltage Span): ±10% x V to ±50% x V
- Output at Center: V/2 ± (5% x Gain)
- Power Supply: 5V ±0.5V Transient free
- Switch Outputs: Open Drain, pulled high within paddle control via 1K5 to 5V, and smoothed to 0V with 100nF
- Sensor Type: Hall effect
- Current Consumption: <20mA
- Loads: Minimum 10K, preferred 100K+
  PWM frequency range: 100Hz to 1KHz

#### ENVIRONMENTAL SPECIFICATIONS

- Storage: -40°C to 85°C (-40°F to 185°F)
- Operating Temperature: -25°C to 70°C (-13°F to 158°F)
- Seal Above Panel: IP67 Dust & Water Ingress to BS EN60529:1992+A2:2013
- Damp Heat BS EN 60068-2-78:2002 Test Cab 21 days exposure @ +85°C 85%RH
- Salt Spray BS EN 60068-2-11:1999 Test Ka 48 hours exposure @ +35°C with 5% NaCl
- Conducted Emissions: CISPR 25:2008 Ed. 3.0
- Radiated Emissions: CISPR 25:2008 Ed. 3.0, EN61000-6-4: 2011
- Radiated Immunity: ISO 11452-2: 2004 (150V/m), EN61000-6-2: 2005
- Conducted Immunity: ISO 11452-4: 2011
- Signal Cable Transients: EN 61000-6-2: 2005
- AC Magnetic Field Immunity: MIL-STD-461F
- Electrostatic Discharge: ISO 10605: 2008 inc A1: 2014 (8KV contact / 15KV air discharge) EN61000-4-2
- Random vibration according to ISO15003 level 1 in 3 axes 10...350Hz, Level 2, 8 hours/axis
- Bump BS EN 60068-2-27:2009 40g 6ms half sine, 50 shock in each sense of each axis, total 300 shocks
- Freefall drop BS EN 60068-2-31:2008 1000mm drop onto all faces and edges
- Shock BS EN 60068-2-27:2009 50g 6ms half sine, 3 shocks in each sense of each axis, total 18 shocks



All parameters shown are based on a standard configuration and are provided for guidance only. Please contact APEM for assistance on how to achieve the best performance from your chosen configuration.

Note: The company reserves the right to change specifications without notice.

#### **MATERIALS**

• Body: PA

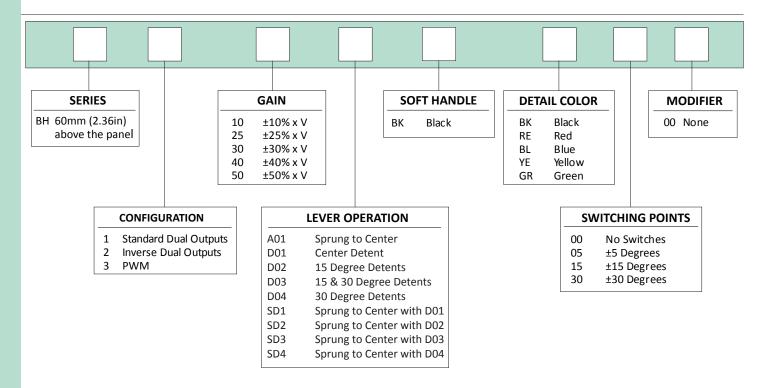
Actuator: PA & PCRubber Grip: TPE

#### **GENERAL SPECIFICATIONS**

- Operating Angle: ± 30 Degrees
- Life Cycles: 10 million cycles
- Soft touch lever with color options

### Paddle joystick controllers

Overview





#### **DETENT OPTIONS**

D01 = CENTER DETENT D02 =  $\pm$ -15 DEGREES

D03 = +/-15 & 30 DEGREES

D04 = +/-30 DEGREES









#### **SPRING TO CENTER WITH DETENT OPTIONS**

SD1 = CENTER DETENT SD2 = +/-15 DEGREES

SD3 = +/-15 & 30 DEGREES

SD4 = +/-30 DEGREES



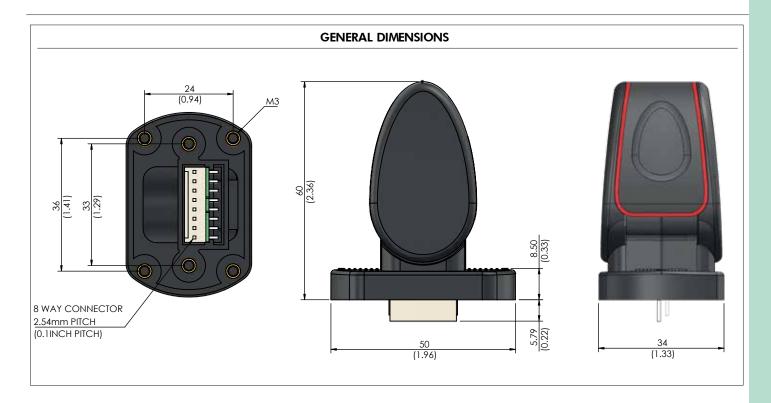






### Paddle joystick controllers

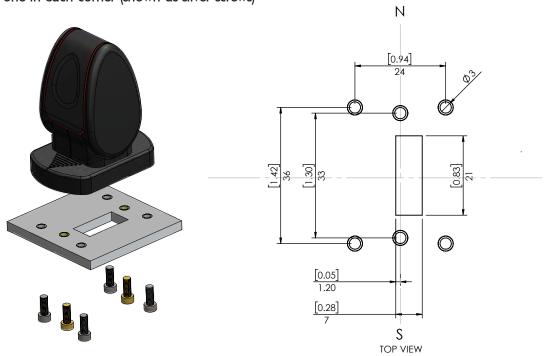
Overview



#### DROP IN MOUNTING - PANEL CUT-OUT & MOUNTING INSTALLATION

The Paddle may be mounted with two different hole patterns:

- Two screws in line on the Y axis (shown as yellow screws)
- Four screws one in each corner (shown as silver screws)



The Paddle is fitted with M3 bushes in all six positions, as standard.

Fasteners are not supplied as standard. The appropriate length of fastener is dependent on panel thickness.

NOTE: All dimensions in mm/(inch).

### Paddle joystick controllers

#### Overview

#### **MECHANISM**

The brand new mechanism design has been developed for strength and long life while retaining a superb feel.

#### **SPRING TOCENTER**

The lever springs back to the center position when released.

#### **DETENTPOSITIONS WITH SPRING TO CENTER**

The lever springs back to its center position when released.

#### **CONNECTIONS**

The paddle is fitted, as standard, with an industry standard 2.54mm pitch 8 way connector.

#### CONNECTIONS

Paddles are supplied with an eight way connector as standard.

PIN 1: 5V

PIN 2: Switch 1(+)

PIN 3: 0V

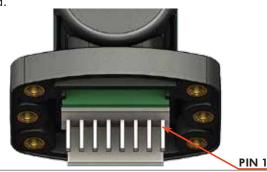
PIN 4: Analog/PWM output 1

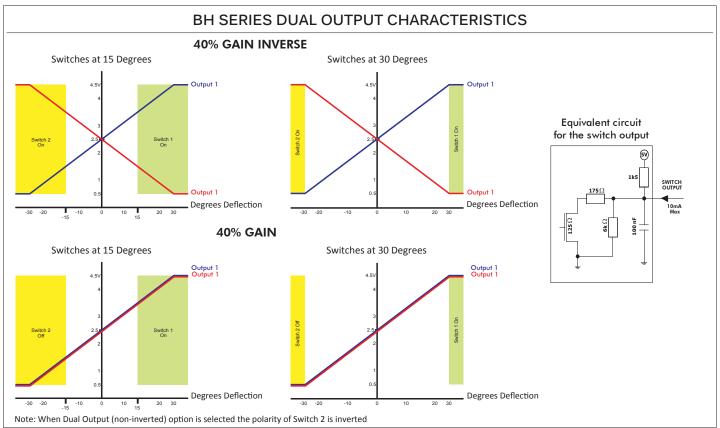
PIN 5: Analog/PWM output 2

PIN 6: 0V

PIN 7: Switch 2 (-)

PIN 8: 5V







Overview

#### **OUTPUT OPTIONS**

The BH series paddle joystick is configured as two "electrical" controls in one mechanical package. The Paddle operates from 5V and provides two proportional outputs. The second output is accurate to the first within ±3% of the power supply. The power supply for the secondary output is also completely independent. Customers may choose their preference of voltage outputs (gains).

The secondary output can be of the same or inverse polarity to the primary wiper. For example, with a secondary inverse output, the first and second outputs can be summed and compared to zero to verify that the joystick is operating correctly. Paddles having two identical outputs of the same polarity may be used to drive two identical dual redundant circuits.

There are also two Hall effect switches that trigger at pre-determined lever positions.

The BH series paddle joystick may be specified with a variety of PWM output options. For more details on available PWM options please refer to APEM.

#### ADDITIONAL OUTPUT INFORMATION

#### SELECTABLE SWITCHING POINTS

The Paddle incorporates two Hall effect switches. The angle of the lever at the switch trigger point can be selected when ordering. If no switches are specified then the output on pins 2 and 7 will be unused. The outputs are configured as 'open drain' type with a 1K5 pull up resistor to 5V.

#### **GAIN OPTIONS**

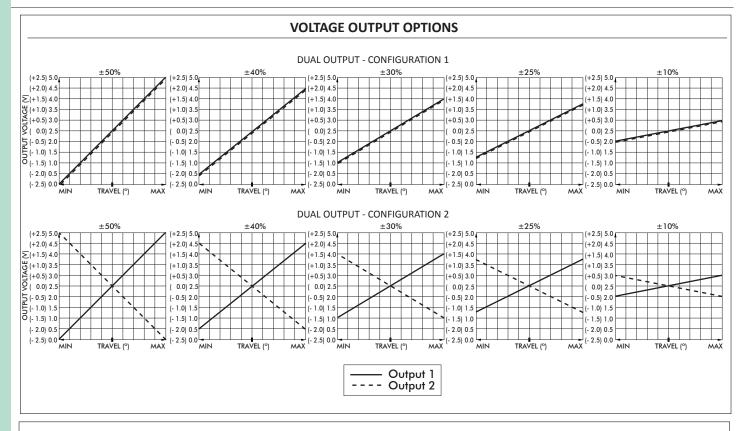
The voltage output on the wiper, at full scale deflection is determined by the gain. The gain is expressed as a percentage of the voltage supplied. Therefore (assuming a 5V supply) a Paddle specified with ± 25% gain would yield 1.25V at South, 2.5V at center and 3.75V at North. A range of gain options are available as standard. All controls are supplied pre-set and no further calibration is needed throughout the lifetime of operation.

#### **OUTPUT IMPEDANCE**

The voltage outputs at center and at each end of travel are specified across an infinite load, with no current flowing. The output impedance specified in the electrical specification should be taken into account when designing a system. Load resistance of less than 10K Ohms is not recommended.

### Miniature paddle controllers

Overview



#### **POWER SUPPLY**

The BL is designed to be powered by a regulated 5V± 0.5V power supply. The outputs are ratiometric, making a stable, noise free, power supply essential. The power supply to the joystick should be carefully regulated to be within tolerance. Should the power supply change outside of the specified tolerances, permanent damage may occur.

#### **MAGNETIC IMMUNITY AND SYSTEM DESIGN**

The Series incorporates internal magnetic screening to minimize the effect of external magnetic fields. Mounting or operating the Paddle close to strong magnetic fields is not recommended. System designers should follow best practice when incorporating the BH/BL Series Paddle into their products. Care should be taken to decouple the power supply properly and to employ adequate EMC shielding.

#### **MOUNTING**

When mounting the Paddle, care should be taken to site it in a position that does not make vulnerable to damage when in use. If the Paddle is intended for use in a handheld enclosure then care must be taken to protect the Paddle from damage caused by dropping. For long term reliability, basic precautions should be implemented, such as mounting it at the lightest end of the enclosure or by protecting it with a guard. The body of the Paddle, on the underside of the panel, must not be subject to water spray, excessive humidity or dust.



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**APEM** 

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